H10833

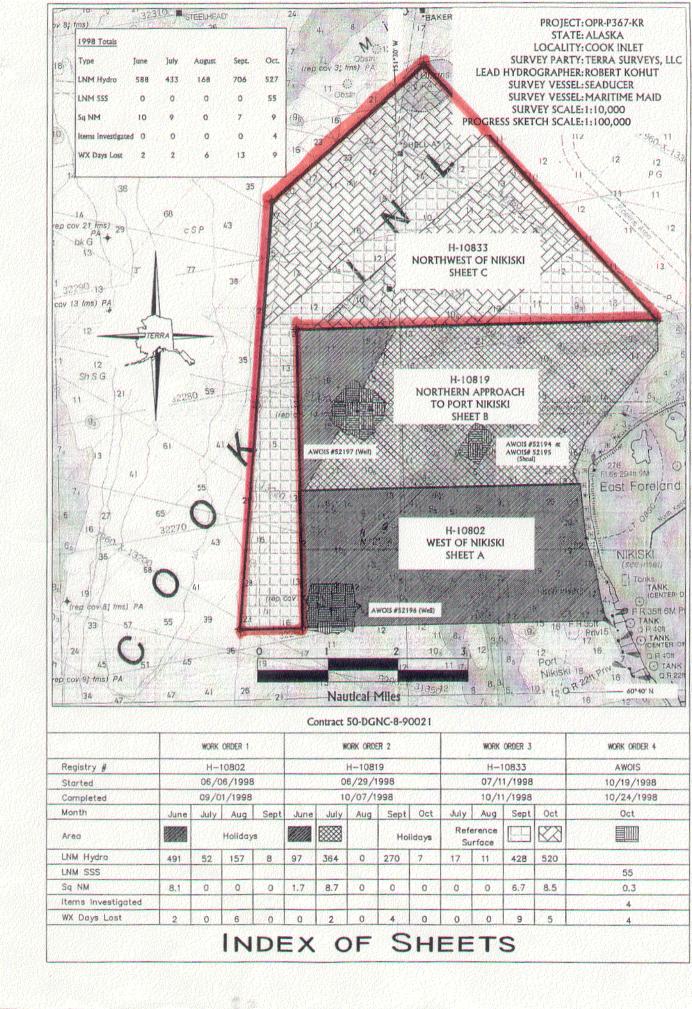
NOAA FORM 76-35A

U.S. DEPARTMENT OF COMMERCE
NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION
NATIONAL OCEAN SERVICE

DESCRIPTIVE REPORT

Type of Survey	Hydrographic	
Field No.	NA	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
Registry No.	H-10833	
	LOCALITY	
State	Alaska	
General Locality	Cook Inlet	
Sublocality	Northwest of Nikiski	
	1998	
	CHIEF OF PARTY Robert Kohut	***************************************
	LIBRARY & ARCHIVES	
DATE	JUN 2 200	

NOAA FORM 77-2 (11-72)		U.S. DEPARTMENT OF COMMER C AND ATMOSPHERIC ADMINISTRATI	
	HYDROGRAPHIC T	ITLE SHEET	H-10833
	The hydrographic sheet should	· · · · · · · · · · · · · · · · · · ·	FIELD NO.
filled in as comp	eletely as possible, when the shee	it is forwarded to the office.	C
State	Alaska		
General Locality	Cook Inlet		
Sublocalit <u>y</u>	Northwest of Nikiski		
Scale	1:10,000	Date of Survey July 11 -	October 11, 1998
Instructions Date		Project No. OPR-P36	7-KR
WO #3 signed 8	8/21/98 and Modification signed	d 12/23/99	
Vessel	Sea Ducer (AK Reg "AK00	691P")	
Chief of Party	Robert Kohut		
Surveyed by	Terra Surveys, LLC		
Graphic record	by echo sounder, hand lead, polescaled by $oxed{NA}$ checked by $oxed{NA}$	e Reson 8101 Multi-Beam E	
Evaluation by		Automated plot by HP Desig	
Verification by	G. Nelson, D. Hill, B. Miha	ailov	
Soundings in	Fathoms and tenths	at MLLW	
REMARKS:	Time in UTC. Revisions	and marginal notes in black w	vere
		ranch during review of the sur	
generated at t	ne i acine nyurograpine bi	anch during review of the sur	vey.
	Contractor: Terr	ra Surveys, LLC	
		n Whiting Circle	
	Palmer, AK		
	907-745-7		· · · · · · · · · · · · · · · · · · ·
	707-743-7	41 3	···



Descriptive Report to Accompany Hydrographic Survey H-10833

Sheet C

Scale 1:10,000

July-October 1998

Terra Surveys, LLC

Chief of Party: Robert Kohut, P.L.S. and Certified Hydrographer

A. PROJECT ✓

This navigable area survey was conducted in accordance with Hydrographic Project Instructions OPR-P367-KR, Northwest of Nikiski, Cook Inlet, Alaska, dated November 28, 1997, amended on January 6, April 25, July 15, and August 6 of 1998.

The purpose of this contract is to provide NOAA with modern, accurate hydrographic survey data with which to update the nautical charts of this area. Numerous obstructions and shoaling have been reported in this area. The area is adjacent to four docks including one commercial multipurpose dock used primarily in oilfield support, a petroleum dock, a liquid natural gas (LNG) dock and a loading dock for a fertilizer manufacturing plant. The area is transited by oil tankers, liquid natural gas tankers, oilfield support vessels, commercial fishing boats and tenders, tug and barge contractors and oil spill response vessels.

The project area encompasses approximately 15.2 square nautical miles located near East Foreland in upper Cook Inlet. The survey covers the mostly deep water channels to the north and west of Port Nikiski.

A shallow water, multibeam sonar system was used to locate and determine the least depth over the obstructions and shoals as well as to determine the least depths over the entire project area. Every effort was made to ensure that the survey product could be traced to and reconstructed from the raw data.

B. AREA SURVEYED

The area surveyed (Sheet C) for H-10833 covers approximately 15.2 square nautical miles to the north and west of Nikiski, Alaska. The following NAD 83 latitudes and longitudes are the hydrographic survey limits:

Degrees Latitude (N)	Degrees Longitud	e(W) 27.0
60.754102 60/45/14.7	151.375058	151/22/3002
60.815999 60/48/57.6	151.485888	151/29/09.2
60.784446 60/47/4.0	151.560717	151/33/38.5
60.683436 60/41/00.3	151.580433	151/34/49.5
60.683443 60/41/00.4	151.550157	151/33/00.5
60.754102 60/45/14.7	151.550159	151/33/00.5

The Index of Sheets shows the area surveyed for H-10833.

C. SURVEY VESSELS

The **Sea Ducer**, a 31-foot Uscola Offshore Pilot with aluminum hull, was used for all data acquisition.

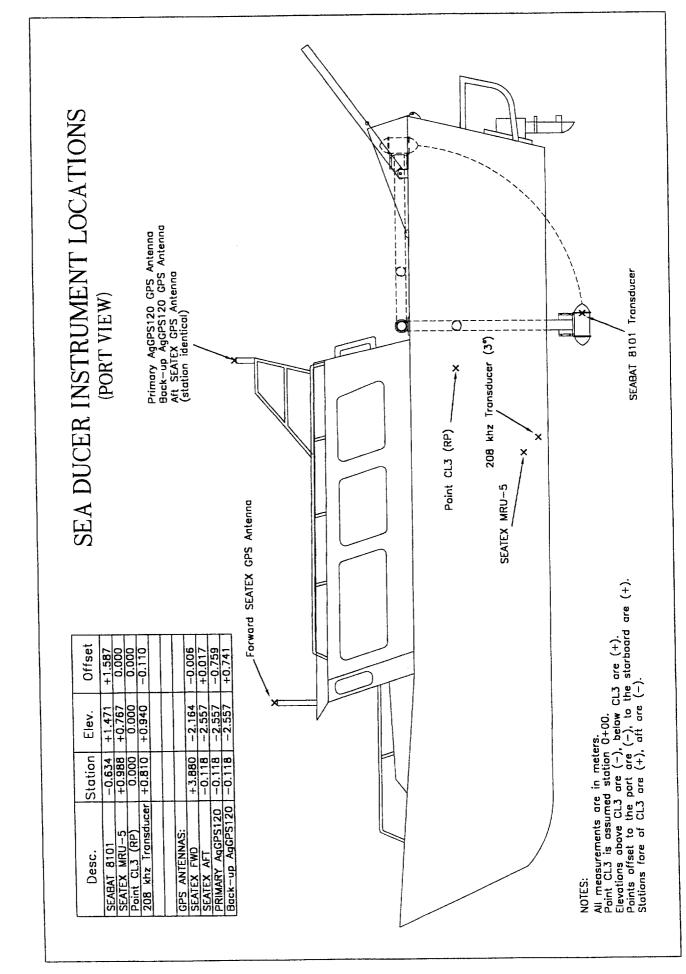
The Sea Ducer	AK ID # 0691
1997 Uscola Offshore Pilot	Hull ID # UCN0317M997
Manufacturer	Uscola Boat Works Palmer, AK
L.O.A.	31 ft.
Beam	10 ft.
Draft	1.5-2.0 ft.
Power Plant	Twin 188hp AD41/DP Volvo-Penta turbo diesels with stern drives.
Data collection power source	24vdc, 12vdc from mains 110vac from 2.4 kW Trace Inverter 110vac from 5kw Northern Lights Genset
Cruise Speed	35 knots
Fuel Cap	204 gallons
Fuel consumption	13 gal/hr @ cruise
Gross tonnage	5 short tons displacement

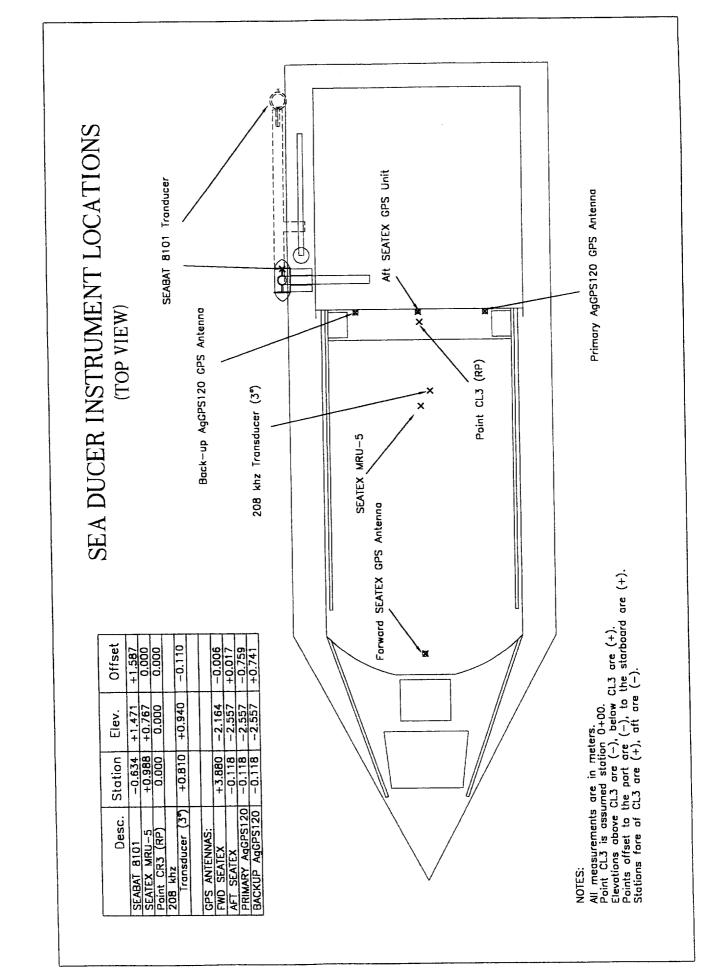


The Sea Ducer

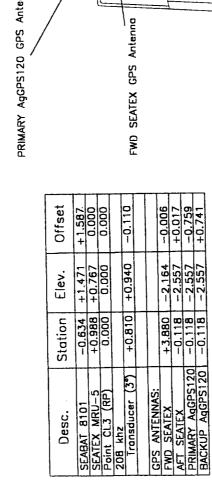
The Sea Ducer was configured as shown on the Sea Ducer Instrument Locations Port, Top and Stern view drawings on the following pages.

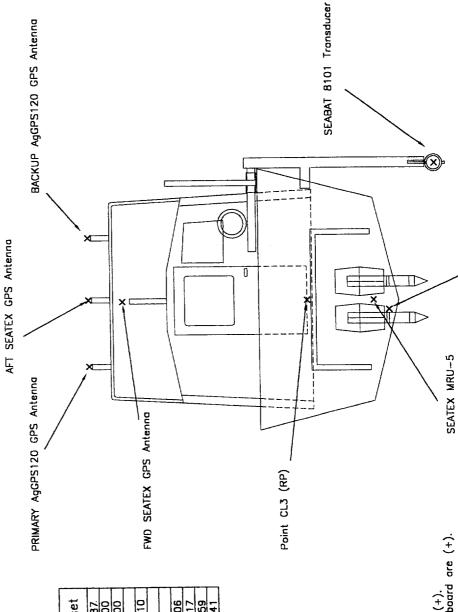
OPR-P367-KR 5 H-10833





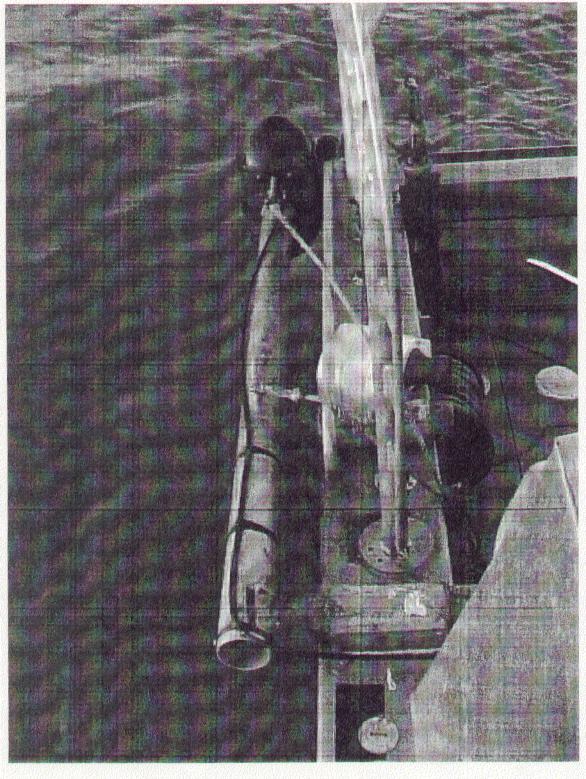
SEA DUCER INSTRUMENT LOCATIONS (STERN VIEW)



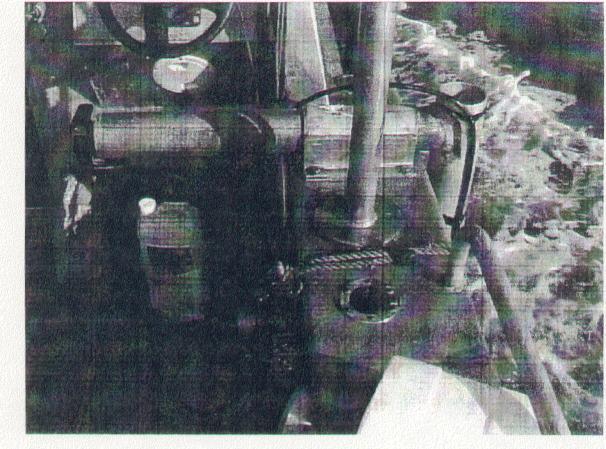


All measurements are in meters. Point CL3 is assumed station 0+00. Elevations above CL3 are (-), below CL3 are (+). Points offset to the part are (-), to the starboard are (+). Stations fore of CL3 are (+), aft are (-).

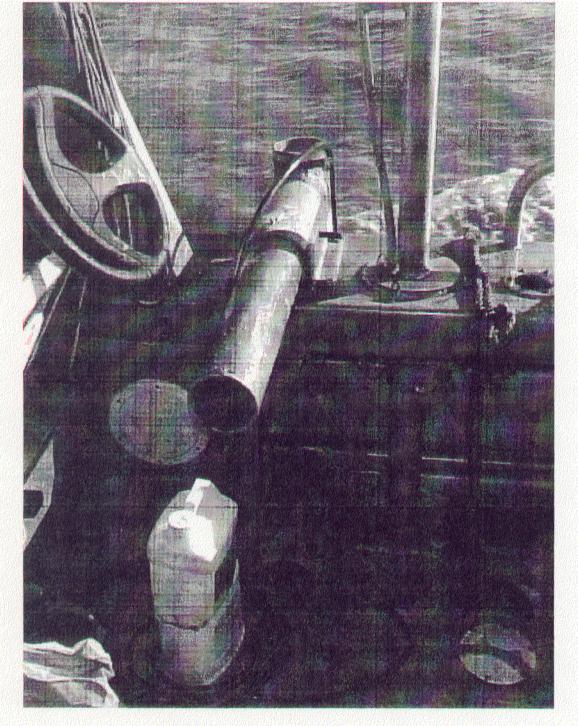
208 khz Transducer (3°)



Sonar Head Pole Mount from bow while out of water



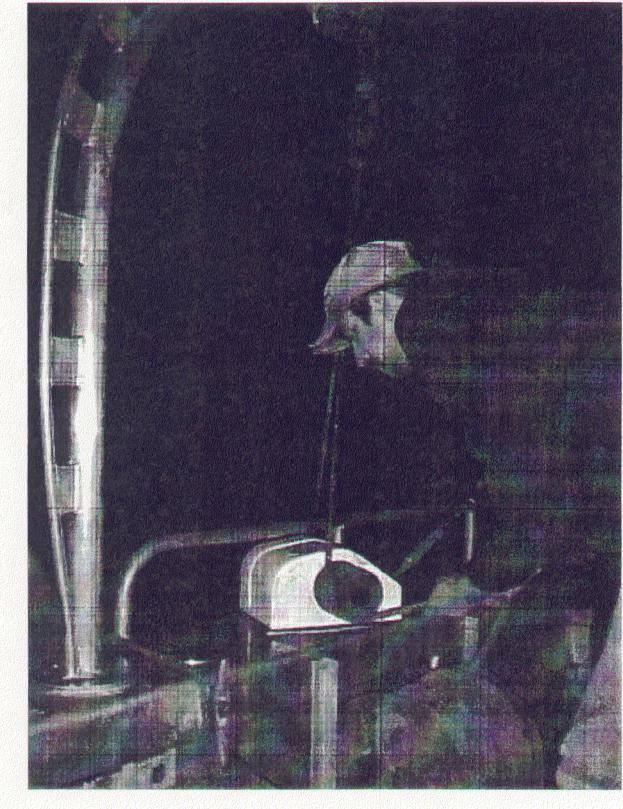
Sonar Head Pole Mount from stern while deployed



Sonar Head Pole Mount from deck while deployed



Sonar Head Pole Mount from bow while underway



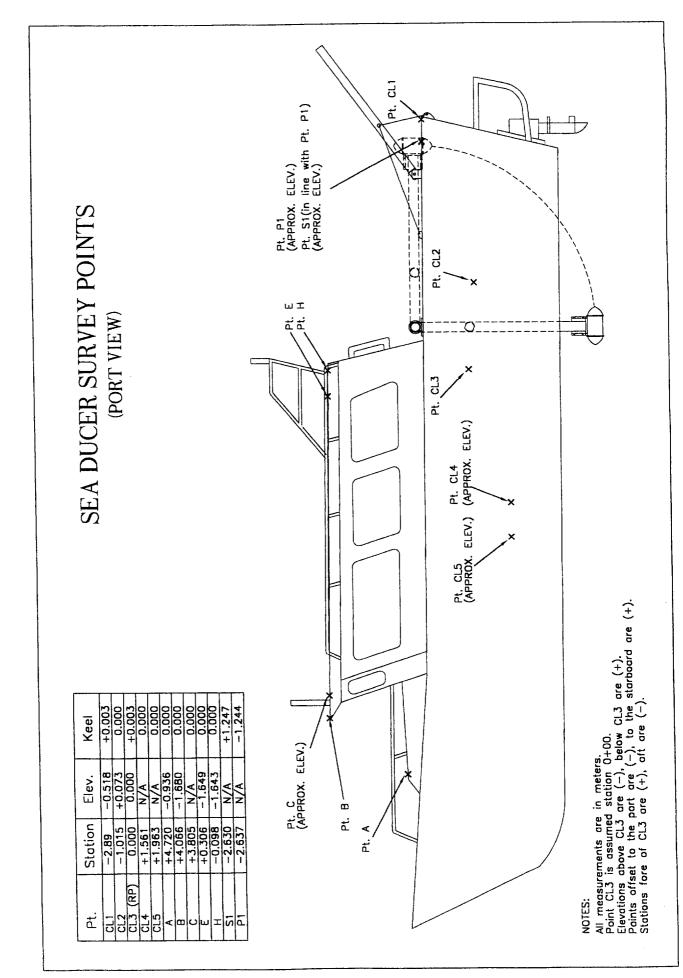
Retrieving Sonar Head Pole Mount

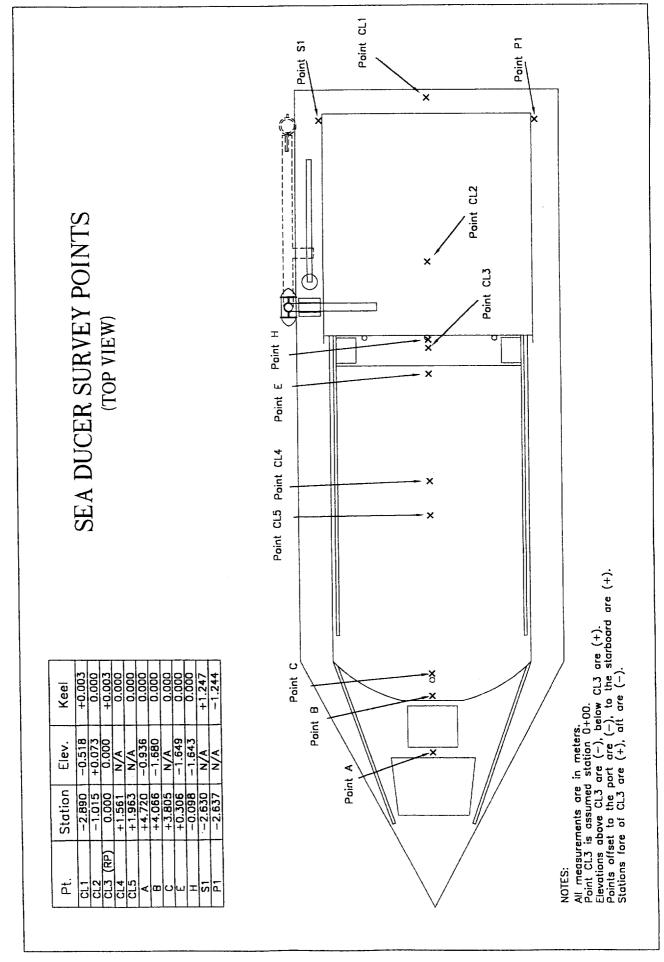
Two Seapath 200 GPS antennas were mounted on centerline 4 meters apart over the cabin. Two AgGPS120 GPS antennas were mounted on the radar rack to port and starboard of the rear Seapath 200 antennae. The Seatex Motion Reference Unit (MRU-5) was mounted on centerline, forward of the rear cabin bulkhead and below the deck. The Sea Ducer also has three single beam transducers mounted in a sea chest amidships on centerline.

Control positions on the *Sea Ducer* are the result of surveys done both in Terra Surveys' shop using conventional surveying equipment and in the field using the survey points (punch marks) set during the original survey. The original survey involved leveling the boat on its trailer such that the apparent water line found on the hull was level. Elevation and location were then obtained using an automatic level, a digital total station, and steel chain. Punch marks were made and named for later use as equipment was mounted.

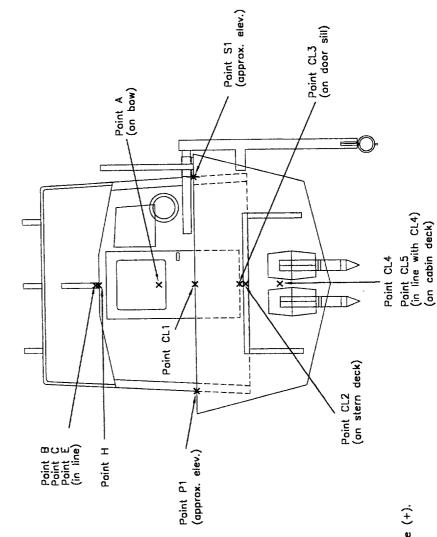
Metric adhesive rod face was adhered to the sides of the hull and also to the multibeam pole for daily readings of vessel draft.

The Sea Ducer's survey power was provided by a 12/24vdc alternator on each of the mains connected to a bank of batteries for dc power and a 2.4 kW Trace inverter for 110ac. A back up, 5 kW diesel generator was also available but not typically used.





SEA DUCER SURVEY POINTS (STERN VIEW)



Keel	+0.003	0.000	+0.003	0.000	0.000	0.000	0.000	0.000	0.000	0.000	+1.247	-1.244
Elev.	-0.518	+0.073	0.000	N/A	N/A	-0.936	-1.680	N/A	-1.649	-1.643	∀ /Z	N/A
Station	-2.890	-1.015	0.000	+1.561	+1.963	+4.720	+4.066	+3.805	+0.306	-0.098	-2.630	-2.637
Pt.	21.1	CIS	CL3 (RP)	C 4	CI 5	V	œ	ار) _	I	ī	<u>P</u>

NOTES:
All measurements are in meters.
Point CL3 is assumed station 0+00.
Elevations above CL3 are (-), below CL3 are (+).
Points offset to the port are (-), to the starboard are (+).
Stations fore of CL3 are (+), aft are (-).

D. Automated Data Acquisition and Processing

Data Collection

Multibeam data collection was performed on a 333 MHz Pentium II PC running Reson's 6042 Multibeam Data Collection software under Windows 95. The data collection PC received Reson 8101 bathymetry via a serial interface and Reson 8101 sonar imagery via an Ethernet interface. It received motion and position information (heave, pitch, roll, heading, latitude and longitude) via serial interface from the Seatex Seapath 200 system. The Seapath 200 received differential correctors from an Ag120 GPS receiver tuned to the U.S. Coast Guard Beacon Kenai.

The Reson 8101 received motion information from the Seapath 200 to aid in filtering. The motion information allowed the Reson to apply filters based on minimum and maximum depths while the vessel was experiencing roll.

Coastal Oceanographics' Hypack software was utilized for navigation and line tracking as well as for the collection of quality control statistics. The Hypack software ran on a 200mhz Pentium computer. It received motion and position data (heave, pitch, roll, heading, latitude and longitude) from the Seapath 200. It also received a check position from a second Ag120 GPS receiver receiving differential correctors from the U.S. Coast Guard Beacons Kodiak or Cape Hinchinbrook.

Processing Overview

The Reson 6042 software collects multibeam data in its native format, a binary file with a 'SVY' extension. The first step in processing the data was to convert the 'SVY' file to a 'XTF', Extended Triton Format, for compatibility with CARIS HIPS. This was done using the Reson 6042 software while offline. The data was then transferred in Hypack raw navigation data files off the vessel via 2.6-gigabyte Magneto-Optical (MO) disks.

The MOs were transferred daily from the vessel to the project office for processing. The data was copied to the server for storage and archived on 4mm DAT tapes. The XTF files were converted to HIPS files using HIPS' refoXTF program.

Once converted, the lines were reviewed in HIPS 'Line' mode for defects in positioning, motion sensor data or sounding data. The positioning data was examined for jumps in position and if necessary data was rejected without interpolation. The various sensors, including azimuth, heave, pitch, roll and tide, were also checked. If necessary data was rejected without interpolation or in the case of small isolated spikes, rejected with interpolation. Typically no rejection was required for either the positioning or for the various sensors. The soundings were then reviewed in the Hydrographic Data Cleaning System (HDCS) editor where the user could filter or manually reject outliers. Filters used were beam quality, beam number and (when implemented by Universal) a roll value or angle from nadir filters. Beams of only the highest quality were accepted. If a question arose about a possible bottom feature then beams of lesser quality were reviewed. Initially, beam filters were overused resulting in some data after editing

yielding only 61 beams per profile. This practice was quickly discarded and only the beam filtering necessary to speed processing was performed, typically 5 to 15 outer beams on each side. The implementation of an angle filter by Universal was used when available and soundings outside a 100 degree sector about nadir were rejected by filter after that. Line spacing was adjusted with water depth in the field to ensure three-beam overlap on adjacent lines with a 90° swath. This underestimation of swath width ensured sufficient overlap. When reviewing the soundings, the sidescan imagery obtained from the Reson 8101 was viewed in a window on the edit screen. This allowed the hydrographer to make decisions about the veracity of questionable features with the sidescan imagery to aid them.

Following adjustment for the sound velocity profile measured in the field, the data was beam edited in **HIPS** 'Line' mode. Preliminary tides for the National Ocean Service (NOS) gage at Nikiski (945-5760) were applied without zoning. The next step in HIPS was to 'merge' the data. In the merge step the various sensors for motion and position of the vessel were used to compute the final position and depth of the sounding.

Following merging, the data was reviewed in the HIPS 'Subset' editor for outliers. Soundings for a geographic area from multiple lines can be viewed from several directions and flagged as 'Rejected' if deemed an outlier or as 'Outstanding' if it is a feature the user desires to track. The soundings 'Rejected' in subset mode were typically single outliers. Soundings marked as 'Outstanding' are features which rose ten percent of the water depth. In the absence of sidescan information or reports of obstructions, these features are assumed to be rocks. The status of the 'Outstanding' flag is accessible from this point to the final drawing.

Following the 'Subset' editor, the data was exported to the Caris Editor, a Geographic Information System (GIS) and inspected for coverage. In the Caris Editor, the soundings were displayed and the operator zoomed and panned along each line to check for sufficient overlap between adjacent lines and gaps within the line. Areas requiring additional coverage were outlined and fill in lines were chosen, data collected and edited as described.

Once coverage was complete for the project, the data was exported from the Caris HIPS files to a database. During the export, the tide zone for each profile was determined, the angle from nadir that the sounding was taken at was determined and the athwartships footprint size was calculated. This information with all the flags from Caris HIPS are maintained in the database. After transfer to the database the soundings were tide adjusted using the zoning scheme provided and the Final Verified tides from the NOS gage at Nikiski (945-5760). These tides were down loaded from the NOS internet site. The tide was applied equally to all soundings within each profile. A new tidal datum was provided after final processing was complete and the data was reprocessed starting from the merge step. Ten percent of the subsets were reviewed as a check. This data was exported to a binary file format developed by Terra Surveys. The data was then sorted into one meter square cells. Each cell collected information on the number of soundings in that cell, the average depth for the cell and the shoalest sounding for each cell with it's corresponding sounding ID number for later retrieval. The average depth for each square

meter is exported to an ASCII file which can be read into the Caris Editor. A DTM was created and rechecked for coverage.

Following the tide adjustment, soundings were flagged as rejected if the footprint was deemed to large for the required shoal detection or the angle at which the sounding was taken was outside of the acceptable swath. The athwartships footprint was maintained at 2 meters or less down to 30 meters (MLLW) and at 10% of water depth or less (tide reduced) below 30 meters. The angle from nadir was maintained at less than 50° for most of this survey. Crossline statistics indicated that the allowable angle could be raised to 58° in water depths less than 30 meters (MLLW) and to 55° in water depths greater than 30 meters (MLLW). These wider nadir angles were used to reaccept a limited number of soundings in a small area devoid of soundings. The accepted soundings were within expected accuracy standards and footprint size.

An average of the acceptable soundings within each square meter was then exported to the Caris Editor as a tide adjusted final data set. The cleaned cross lines were exported to the Caris Editor in their entirety. The combined data was used for cross line analysis, tide zone analysis and coverage plots.

All accepted soundings were checked for overplot removal. Deeper soundings that would overplot the shoalest soundings were then suppressed. The unsuppressed soundings were then exported to AutoCAD. The unsuppressed soundings, which had been flagged by the operators as 'Outstanding', were placed on a separate layer in AutoCAD for identification on the drawing as rocks. All of the plotted soundings in AutoCAD contain an identification number, which allows tracing the sounding back to the database and thus back through all steps to collection. A histogram of unsuppressed soundings was generated from the database. The data was also exported to AutoCAD for trackline plots which depict the track of the sonar head.

Quality Control

The raw navigation files from Hypack were used for quality assurance. The files were processed using HPTools to summarize the start and end times of lines, distance traveled, average vessel speed, minimum number of satellites and maximum HDOP encountered. There were some incidences when the Hypack log was inadvertently turned off during the running of a line. In these instances, the lineal nautical mileage and speed were computed from the XTF files. The lines were then checked for the several conditions that could cause disqualification. Disqualification could be due to going to fast for the range scale used causing insufficient sounding density or inadequate GPS caused by less than 4 satellites or when the Horizontal Dilution of Precision (HDOP) was greater than 2.5.

Lines were also disqualified by the Caris HIPS operators if they were excessively noisy or had missing data due to improper filtering in the collection process.

Software Summary

SeaBat 6042 Software produced by Reson was used for all multibeam data acquisition. Caris Hips, a processing program developed by Universal System Ltd., was used for all multibeam post processing and quality assurance.

Program Name	Version	Date	Usage and Dates Used		
Reson/SeaBat 6042 NT	5.20 L	5/19/99	6/12/99 through completion. Multibeam data collection software		
Coastal Oceanographics, Inc/Hypack	8.9	4/16/96 5/19/98	Navigation and collection of quality control and statistical data.		
Tides and Currents	2.2	11/26/96	Predicted Tides		
Caris Hips	4.32b	4/16/99	Multibeam Data Processing.		
Caris Editor	4.31	8/26/98	Data Visualization, manipulation		
Caris Tools	4.31	9/3/98	Data Manipulation, Contouring		
Corpscon	5.11.01	2/2/99	Coordinate Conversion		
Geocalc	4	1993	Coordinate Conversion		
Trimble/DSMCHAT	3.2	94-96	Configure AgGPS120 GPS receiver		
Seapath	1.02.04	10/05/99	Seapath 200 Firmware		
Winzip	6.0	91-95	Compressing and transferring large data files		
Trimble/Probeacon		9/12/94	PC interface for AgGPS 120		
Power Desk Utilities 98	3.032	6/26/98	File management		
ACAD MAP 3	3	7/14/98	Drafting		
Quicksurf	5.1	6/26/97	Surface modeling, contouring		
Corpscon	5.11	6/10/98	Coordinate Conversion		
Wizard	5.07RF	3/4/98	Tide data down load, programming and calibration for the MicroTide tide gage		
Endeco 1150OPS		5/23/90	Tide data download, programming and calibration for the Endece		
Endeco 1150RPT Terra Surveys HPTools		2/28/91 5/98 – 10/98	tide gage Inhouse program for generation of line and gps quality statistics		
Microsoft SQL Server	6.5	8/19/97	Database server for storage and manipulation of sounding data.		
Terra Surveys Multibeam Suite		6/98 – 11/98	Suite of programs for transfer of data from Caris HIPS to SQI Server and tide adjustment, determination of acceptable data sounding suppression, trackline generation and export to Cari Editor.		
Seatex MRC	2.53	12/3/98	PC Interface to Seatex MRU-5		
Seapath Control Center	1.01.01		PC Interface to Seatex Seapath 200		
Microsoft Access	97		Database Management		
Microsoft Excel	97		Spreadsheet Program		
Microsoft Word	97		Word Processing Software		
Microsoft Visual Basic	6.0		Programming Language & Tools		
Windows NT Server	Server 4.0		Operating System		
Service Pack	4		Operating System		
MS-DOS	6.22		Operating System		
TEXTPAD32	V3.2.2		Text Viewing & Editing		
RCMCONF	V1.33	1997	Radio Modem Config Program		
SVP Process	1.00	5/24/99	SVP Program/Data Collection		
Windows NT Workstation	4.0		Operating System		

E. SONAR EQUIPMENT (Towed sidescan)

No SONAR equipment (towed sidescan) was used on this survey. - concur

F. SOUNDING EQUIPMENT ✓

The survey vessel, *Sea Ducer* was equipped with a Reson SeaBat 8101 multibeam echo sounder system (serial # 85100120). The system's two main components consist of a surface processor (serial # 13983) and transducer head (serial # 049710).

Soundings were recorded in meters and corrected for the speed of sound through water from multiple daily measurements of the water column profile (see Section G). Depths encountered in the survey range from 14.08 meters/7.7 fathoms (Latitude 60.776034° N, Longitude 151.433107° W), to 61.78 meters/33.8 fathoms (Latitude 60.685805° N, Longitude 151.581131° W), at MLLW based on verified tide data from the Nikiski Gage (945-5760).

Metric leadlines were used for depth comparison with the depth sounder. Leadlines were constructed from metric fiberglass survey tapes with 24 or 36 ounce lead balls attached such that the bottom of the ball was at the zero mark. Leadline comparisons were conducted a minimum of once weekly by simultaneously reading the draft marks on the sonar head pole, the leadline depth (typically 3-6 meters) and the depth from the 8101. The comparison was made with the formula:

Error = Leadline Depth - Draft - 8101 Depth

The multibeam did experience a fault during the survey. While checking raw data from the unit ("snapshots"), Reson engineers discovered a bad beam former on the starboard side. The unit was shipped to Reson in California on August 19, 1998, and was back in service on August 25, 1998. Reson's engineers found a broken trace on a circuit board controlling the beam forming for the four outermost beams on the starboard side. Those beams are not included in the smooth sheet.

Data analysis has revealed a slight frown shaped swath in the 8101. This feature first became apparent in reference surface analysis and sub-set editing in CARIS HDCS. The general trend is a raised surface in the middle of the swath. Part of this feature is a nipple effect (raised ridge) generated around nadir by several beams. The nipple effect was minimized in the field by lowering the sounder gain to its lowest level without losing data, but could not be eliminated. Terra Surveys, LLC and Reson have explored possible causes for these effects throughout the project by analyzing raw data directly from the 8101 sonar head ("snapshots"). The cause of the problem was not resolved at the time of this report, but Reson does not feel the sounder is out of specifications and the problem will not cause the accuracy of the data to be out of specifications.

G. Corrections to Soundings

The following methods were used to determine, evaluate and apply corrections to soundings.

Speed of sound through water

The velocity of sound through water was determined by a minimum of two casts per day with the following two instruments.

Velocimeter (sound velocity, temperature and depth profiler)	SVPlus (standard instrument with 50 dBar pressure sensor and 350 ms temperature sensor)					
Manufacturer	Applied Microsystems Ltd.					
Manufacturer	Sydney, British Columbia, Canada					
Serial number	3201					
Pressure Calibration	4/30/98 by Applied Microsystems Ltd.					
Temperature Calibration	4/29/98 by Applied Microsystems Ltd.					
Distilled Water Sound Calibration	4/20/98 by Applied Microsystems Ltd.					
Voltage Calibration	5/27/98 by Applied Microsystems Ltd.					

Velocimeter (sound velocity, temperature and depth profiler)	SVPlus (standard instrument with 50 dBar pressure sensor and 350 ms temperature sensor)						
Manufacturer	Applied Microsystems Ltd. Sydney, British Columbia, Canada						
Serial number	3259						
Pressure Calibration	4/30/98 by Applied Microsystems Ltd.						
Temperature Calibration	4/29/98 by Applied Microsystems Ltd.						
Distilled Water Sound Calibration	4/21/98 by Applied Microsystems Ltd.						
Battery Calibration	4/30/98 by Applied Microsystems Ltd.						

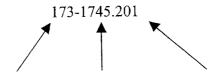
The following instrument was operated at the surface.

Velocimeter (sound velocity, temperature and depth profiler)	Smart SV&P (standard instrument with 50 dBar pressure sensor)					
Manufacturer	Applied Microsystems Ltd. Sydney, British Columbia, Canada					
Serial number	4177					
Pressure Calibration	6/10/98 by Applied Microsystems Ltd.					
Distilled Water Sound Calibration	4/20/98 by Applied Microsystems Ltd.					

Copies of the manufacturer's calibration reports are included in Appendix G. 🛨

The velocimeters were set at a sample rate of 15 samples per second during casts, and 1 sample per minute for the continuous monitoring of the work area. A daily log was kept to note any variance between the two velocimeters. Dual casts were done a minimum of once a day for comparison between velocimeters. During survey operations, either one of the *SVPlus* velocimeters or the *Smart SV&P* logged the sound velocity once per minute. The casts were taken as deep as possible and geographically distributed to satisfy the 95% anticipated water depth and represent local and diurnal variability. The velocimeters were manually initialized and downloaded using PROCOMM terminal software.

The sound velocity data file name convention follows:



Julian Day

Time of deployment

Velocimeter serial number

The naming convention incorporated the Julian day and UTC time as well as the serial number of the sensor. The office reductions then verified and reflected the true Julian day and UTC derived from the raw data header.

* Filed with the hydrographic data.

Example Raw Data header:

du 173-1745.201

SVPlus S/N 3201

New cast started on 06-23-98 at 01:50:52

Sample rate is 1 second

Depth increment 0.50

Sound velocity increment 0.00

Julian Date and Time

Julian Day and UTC file names will reflect an 8-hour difference or be the same depending on which naming convention was used. Regardless of the naming convention used, the correct Julian day was derived directly from the raw data, and applied to the soundings in CARIS from a continuous SVP file of all the casts.

Sound Velocity Data after conversion:

File Name: C201__173-1745

Section 1998	-174	1:50:52
	26.7	1477.21
	26.1	1477.22
	25.5	1477.2
	24.6	1477.18
	24.0	1477.17
	23.2	1477.16
	22.6	1477.16

The converted file names start with C (converted) and the serial number:

C201 173-1745.

Processing Procedures

The velocimeter raw pressure data was converted to depths in meters in a spreadsheet using Foronoff and Saunder's formula as provided by Applied Microsytems Ltd. The formula is as follows:

P=pressure in decibars

 $x=\sin(\text{latitude}/57.29578)$

 $X=x^2$

Gr=9.780318*(1+(0.0052788+0.0000236*X)*X+0.000001029*X

D=(((-0.0000000000000182*P+0.000000002279)*P+9.72659)*P

Depth=D/Gr

The formula was checked with latitudes for the north and south extent of the survey and the resulting depths varied by millimeters so an average was used. This method was also tested against the results of Applied Microsystems Ltd. *Total System Software* and found to be identical.

The data was then converted to a CARIS format where the profile corrections were applied to the soundings. CARIS applies the most recent velocity cast in the file so the newest correctors were always being used. The following Sound Velocity Profile Summary shows the casts, their positions and the maximum depths of each cast. See Appendix J for listings of each cast.

* Filed with the hydrographic data.

SOUND VELOCITY PROFILES SUMMARY

Comments					tube				1200	lube; Boat mounted 3/ v Probe														Tube	
On Line Monitoring					×			×	,	×														X	
File Used for Reduction in On Line Monitoring	Caris	comp192.svp	comp192.svp			comp192.svp		SV225-end.svp			SV225-end.svp						SV225-end.svp		SV225-end.svp		SV225-end.svp	SV225-end.svp			
	Depth	21.4	19.3	19.3		17.6		12.1	12.2		,		19.1	19.2			27.8	27.8	17.2		16.8	31.0	30.9	١.	
Longitude		151-20-09	151-20-07	151-20-07	Ref 2	151-19-50		151-18-58.1	151-18-58.1	WO1	,		151-19-48	151-19-48			151-24-26	151-24-26	151-27-08		151-19-17.2	151-24-35.3	151-24-35.3	Ref.& Patch	
Latitude		60-45-23	60-45-39	60-45-39	Ref 2	60-45-36		60-45-10.9	60-45-10.9	WOI	,		60-45-38	60-45-38			60-41-05	60-41-05	60-43-31		60-45-17.4	60-41-18	60-41-18	Ref.& Patch	
File Name		192-1535.201	192-1905.201	192-1905.259	192-60-0.201	192-2300.259		226-1710.259	226-1710.201	226-tube.177	227-0230.259		227-1700.259	227-1700.201	227-tube.177		238-2000.259	238-2000.201	239-0030.259		239-1700.259	239-1915.259	239-1915.201	239-tube.177	
Daily	Confidence		×	×				×	×								×	×				×	×		
Time	(UTC)	15:39:08	19:08:03			22:59:35		17:10:14			2:35:10						19:58:28		0:30:29		16:55:22	19:14:58			
Julian	Day	192	192	192	192	192		226	226	226	227		227	227	227		238	238	239		239	239	239	239	

Instrument Corrections

No special instrument corrections were made.

Corrections determined from bar checks and vertical casts.

Metric lead lines were used for depth comparison with the depth sounder. Lead lines were constructed from metric fiberglass survey tapes with 24 or 36-ounce lead balls attached such that the bottom of the ball was at the zero mark. Lead line comparisons were conducted a minimum of once weekly by simultaneously reading the draft marks on the sonar head pole, the lead line depth (typically 3-6 meters) and the depth from the 8101. The comparison was made with the formula:

Error = Lead line Depth - Draft - 8101 Depth

The lead lines are summarized below:

Date	Draft (m)	8101 Depth (m)	Lead Line (m)	Error (m)
15 August 1998	1.09	3.56	4.63	-0.02
JD 227	1.09	3.52	4.65	-0.04
14 Sept 1998 JD 257	1.09	1.00	2.03	+0.06
21 Sept 1998 JD 264	1.10	6.47	7.53	+0.04
11 October 1998 JD 284	1.05	5.83	6.92	+0.04

An alternate method of checking was used July 11th, August 29th, September 5th and 12th. The reduced nadir beam depth was compared to a reduced single beam echosounder. The data was corrected for offsets in both the horizontal and vertical planes. Sound velocity, heave, pitch, and roll corrections were also applied.

Date	8101 Depth (m)	ODOM Depth (m)	Vertical Offset (m)	Error (m)
11 July 1998 JD 192	16.35	16.91	0.53	0.03
29 August 1998 JD 241	27.89	28.45	0.53	0.03
5 Sept 1998 JD 249	26.96	27.42	0.53	0.06
12 Sept 1998 JD 255	21.74	22.24	0.53	0.03

Static Draft

A metric adhesive rod face was adhered to the sides of the hull and the multibeam pole for daily readings of the vessel draft. The tapes were calibrated to read the depth of the sonar head. The draft was recorded a minimum of once daily and usually twice. The draft readings were incorporated in a spreadsheet, which included the date and time, line name, engine rpm and draft. From the spreadsheet data and the measured offsets for the boat, the distance from the boat's reference point to the water line was computed for every line and utilized in the HIPS Vessel Configuration File (see following discussion of settlement for more detail).

Settlement

Measurements for the Squat and Settlement were conducted near East Forelands in the work area, using On The Fly Real Time Kinematic (OTF-RTK) GPS survey procedures. The measurements were conducted with two Trimble 7400MSi's on the Sea Ducer and a Trimble 4000SSi as a base station. Pacific Crest Radio modems were used to transmit the correctors to the vessel.

Two Trimble 7400MSi antennas were installed on the Sea Ducer. One antenna was installed near the bow and one on the aft swim deck, both on the centerline of the vessel. The relationship of these antennas to the vessel baseline was surveyed and recorded.

Three files were collected during each test; one ASCII file was recorded for each of the two Kinematic GPS Receivers. These files contained the National Marine Electronics Association (NMEA) "GGA" string, a GPS output string which contains the time, position, ellipsoid height, HDOP and mode. The third file was collected using Triton ISIS which logged the attitude information from the Seapath 200. The Sea Ducer's attitude and elevations were recorded at rest and at various RPM settings to determine vessel dynamics. The static data for the vessel at rest was observed as a baseline and used to correct for tide changes with a starting and ending tide. The results of the measurements were compiled in a spreadsheet. A graph depicting vessel settlement and speed at various RPM settings is shown on the following page. The vessel dynamics appear to react, as any small launch would be expected. At low RPMs (speed), the aft lowers, the bow rises, and the vessel settles into the water. As the RPM is increased the settlement increases to a point where the hull begins to plane. At the upper end of the useable survey speeds (RPM 2800 – 3000) the vessels reference point is actually 3-9 cm above its elevation at rest.

The daily draft readings, RPM values, and the reference point to water line distance for each line were recorded on the written line notes. A macro converted this information to a text file for insertion into the HIPS Vessel Configuration file.

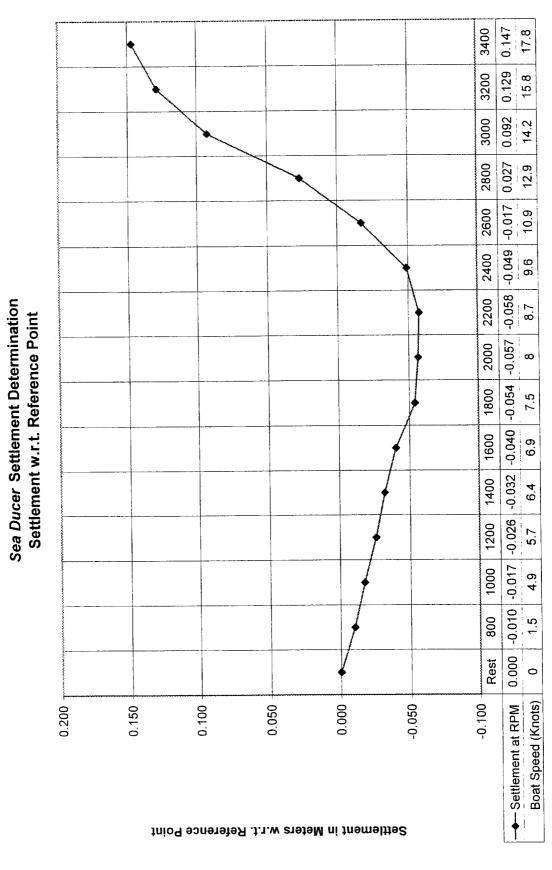
Vessel Configuration File (VCF)

An example of the Reference Point to Water Line entry in the VCF is as follows:

The entry above is for a day when the draft (of the sonar head) was 1.04 meters and the settlement is -0.026 for an engine RPM of 1200. The resulting waterline measurement is 0.41 meters. The equation used for computation of RP definition is:

RP Definition (Waterline) = SeaBat Elevation Offset - Draft + Settlement

Engine RPM



Heave, Roll and Pitch

The Seatex Seapath 200 sensor system was used to determine heave, roll and pitch as well as azimuth and position.

Manufacturer:	Seatex			
Model :	Seapath 200 m320-00			
Seapath Serial number:	0361			
Motion Reference Unit:	MRU-5			
MRU Serial number:	299cus			
Manufacturers stated accuracy:				
Heading:	0.05° 1σ (4 meter baseline)			
Roll and Pitch:	0.05° 1σ			
Heave:	0.05 meters 1σ			
Position Accuracy:	2 meters 2σ			

Tide Correctors

In accordance with section 6.1 of the statement of work, the NOS tide station at Nikiski, Alaska (945-5760) was used as the source for the MLLW datum for this project. No supplemental gauges were installed. The unverified (preliminary) 6-minute data was downloaded from NOS database via the Internet and applied during the CARIS post processing routine. A height corrector of -6.067 meters was applied to the preliminary data to reference tides to MLLW (per contractor's note at web site http://www.opsd.nos.noaa.gov/aknote.html). No zoning was applied to the preliminary data.

Verified 6-minute tides were acquired from NOS after the survey was completed. The verified tide data was downloaded from the Ocean Products and Services Division (OPSD) World Wide Web site (http://www.opsd.nos.noaa.gov). The time and height tidal zoning correctors listed in Appendix E were applied during transfer of the soundings from CARIS to the SQL Server Database. After determining the tidal zone for each profile, the associated soundings were adjusted for the final tide.

H. Control Stations

The horizontal control datum for this project is North American Datum of 1983 (NAD 83). All software, comparisons of junctions and prior surveys referenced NAD 83.

The U.S. Coast Guard Differential Navigation Beacons at Kenai, Kodiak and Cape Hinchinbrook were used during hydrographic survey operations for horizontal positions and confidence checks. The NGS second order control station, NIK, was used as a DGPS performance check site. NAD 83 Geographic Coordinates for these horizontal control stations are found in Appendix C.

No control was set during this survey.

* Filed with the hydrographie data.

I. Hydrographic Position Control

Position Accuracy

Differential Global Positioning System (DGPS) provided the basis of hydrographic positions throughout the survey. The total horizontal positional error falls within 10 meters at the 95% confidence level for all features in this project. A fixed-point DGPS Performance Check was performed to confirm this accuracy standard and a graphical analysis of the check is included in Appendix H. **

In addition to the accuracy of the DGPS system, the accuracy of the sounding position depends on the following:

Characteristics of the multibeam system
Depth of water
Accuracy of heave, pitch, roll, and heading measurements
Accuracy that latencies are accounted for and applied
Accuracy and reliability of the of Sound Velocity Profile (SVP)

Position Control

Differential GPS (DGPS) provided hydrographic position control throughout this survey. The following stations were used for project control:

Reference station	NGS	CORS ID	USCG DGPS	Horizontal
	PID		Beacon Frequency	Order
Kenai 1 CORS L1 Phase Center	AB6390	Kenai_19960131	310 kHz	CORS
Kodiak I CORS L1 Phase Center	AB6391	Kod1_19960201	313 KHz	CORS
Cape Hinchinbrook Light	UV3680	-	292 KHz	THIRD
NIK	TT0543	-	-	SECOND

The United States Coast Guard (USCG) Differential Global Positioning System (DGPS) Beacons at Kenai, Kodiak and Cape Hinchinbrook Light were used during hydrographic operations for horizontal positions and confidence checks. Control station "NIK" was used as a DGPS performance check site.

* Filed with the hydrographic data.

DGPS Performance Check

The National Geodetic Service (NGS) station "NIK" was used as a fixed-point DGPS performance check site during a 24 hour observation period. The USCG Kenai DGPS beacon was checked against the fixed position of "NIK". A Trimble Ag120 DGPS receiver, capable of receiving beacon correctors in the Radio Technical Commission Marine (RTCM) format was placed on control station "NIK". It computed a differentially corrected position at a rate of one per second and output a National Marine Electronics Association (NMEA 0183) "GGA" message once per second to a logging computer. The computed position was compared to the control point's published position. A graphical analysis of this data is found in Appendix H. **

The Kenai, Kodiak and Cape Hinchinbrook Light USCG differential navigation beacons were used for horizontal survey positions and confidence checks during hydrographic operations. A confidence check was performed by simultaneously receiving positions on the vessel from two different beacons. When Kenai correctors were used for primary positioning, Kodiak was used as a confidence check. When Kenai was down for maintenance, September 14-22, 1998, Kodiak correctors were used for primary positioning and Cape Hinchinbrook Light was used as a confidence check. The high bulkhead walls at Sea Ducer's Arness Dock berth precluded setting a fixed point for confidence checks because the satellites were blocked. A fixed confidence checkpoint was established at the Kenai River launch ramp for use also. Data supporting the confidence checks and the positioning criteria can be found in Appendix H. **

Positioning Equipment

The following GPS equipment was used:

Equipment Location	Type of Receiver/Antenna	Receiver serial No.	Compact Dome Antenna serial No.
Primary	Ag120/Trimble	0220061863	0220661841
Aft	SEATEX/Trimble	Seapath-2497011	0220110175
Backup	Ag120/Trimble	0220061678	0220061769
Forward	SEATEX/Trimble	Seapath-2497011	0220109126

Refer to diagrams included in Section C (Vessels) for the instrument locations on the Sea Ducer. - Attached to this report.

Difficulties that degraded the expected position accuracy included insufficient satellite coverage near oilrigs and multipath on very calm waters. Tracklines around oilrigs were run at an angle to the main scheme tracklines in order to insure sufficient satellite visibility and good geometry. A choke ring collar was mounted on the receiver's antenna

* Filed with the hydrographic data

to reduce multipath from flat, calm water. HDOP spikes due to atmospheric conditions or satellite constellation configurations were rare. Spikes that did occur were caught either in the field and no further data was collected or by the quality control procedures in the office using the recorded data. There were no unusual atmospheric conditions that affected data quality. The only malfunctions involving positioning equipment were the result of power outages. Surveying would continue when power was restored.

Systematic errors were resolved during pre-survey testing with configuration modifications to the AgGPS120, Reson, and Seatex Seapath 200 systems until results proved reasonable. Detailed configuration settings are listed in Appendix G. *\formula \text{-}

Prior to field season, all sensor locations were established and a precise conventional survey of the vessel was performed utilizing a Theodolite / EDM and steel chain. From this, sensor offsets, stationing and elevations were determined and applied to the appropriate sensor or processing stage. The origin point (RP) of the vessel was called CL3 and the position of the multibeam sonar transducer was called Seabat 8101.

J. SHORELINE

Not applicable - concur

K. Crosslines

Following reduction of the sounding data a DTM was created in the Caris Editor. First the soundings within the database that had not been rejected either in editing or in the database due to footprint size, angle or beam number were gridded on a 1 meter interval. Gridding involved extracting and averaging soundings within each 1 meter by 1 meter area and averaging the depths. A record was then output with the average depth and the coordinates for the center of the cell. This set of records comprised 52.9 million points and was imported to the Caris Editor. A regular DTM was created using a 5 meter cell size and a radius of 5 meters. Each cell within the regular DTM was a weighted average of the soundings within a 5 meter radius of the cell center. Weighting within the radius was based on the distance from the center of the cell with closer soundings given higher weights. After a DTM was made each crossline was compared to the DTM four ways. The acceptable soundings (not rejected) were compared by beam number and by angle. Then the soundings not rejected in HDCS but unusable due to having a footprint too large or an excessive launch angle were compared to the DTM using both launch angle and beam number.

An artifact in the swath was found in parts of the data where the swath appeared to be "cupped". When this appeared the outer beams of the swath were lower than the center. The source of the "cupping" was not determined although it could be related to either bottom material type or power and gain settings of the Reson 8101 sounder. The "cupping" did not degrade the data used for coverage and the smooth sheet to the degree that the data became unacceptable.

The accuracy required for this survey was that 90% of the soundings used have an error of 0.3 meters or 1% of water depth whichever is greater. An equivalent error budget is allowed for water level corrections for a total error budget of 0.6 meters or 2%, whichever is greater. The table below summarizes the crossline statistics. The columns labeled 90% are either the largest angle or outboard beam numbers which had 90% or greater compliance with the required accuracy.

Refer to the report "Crosslines" for the statistics found in this process. The file naming indicates the line name, whether the data was accepted or rejected and whether organized by angle or beam number. An example is:

1580002 a b

1580002 would be the line name.

The first character indicates whether the soundings are $\underline{\mathbf{A}}$ ccepted or $\underline{\mathbf{R}}$ ejected.

The second character indicates whether the data is grouped by $\underline{\mathbf{B}}$ eam number or $\underline{\mathbf{A}}$ ngle.

For data organized by angle, user number 1 contains soundings with an angle between 0° and 1° , user number 2 has soundings with an angle between 1° and 2° and so on.

For data organized by beam, the user number equals the Reson 8101 beam number.

The statistics are summarized below:

					0-30 N	/leters	90%	> 30 M	1eters	90%
Line Name	Number of Soundings		Max Depth	Std Dev Center	Angle From Nadir	Port Beam	Stbd Beam	Angle From Nadir	Port Beam	Stbd Beam
2520026	681,436	17.50	50.24	0.19	53°	17	83	55°	12	84
2520027	976,422	19.12	44.31	0.18	54°	15	83	54°	17	85
2530000	142,688	20.42	27.64	0.12	60°	13	91	NA	NA	NA
2530001	886,801	18.67	45.04	0.18	60°	12	83	57°	10	84
2530002	965,585	18.30	49.41	0.18	65°	9	94	61°	12	93
2530003	1,043,103	10.47	51.31	0.18	65°	9	93	60°	12	90
2530004	1,254,205	16.92	47.68	0.20	64°	10	94	57°	14	92
2540001	240,011	19.72	52.10	0.24	66°	8	96	66°	8	90
2540002	410,513	15.41	52.25	0.16	72°	5	99	60°	. 10	90
2540005	131,342	18.95	51.49	0.15	69°	7	97	57°	10	90
2540006	191,136	22.90	50.46	0.25	57°	13	87	59°	12	90
2540007	178,377	23.01	46.66	0.22	45°	25	87	60°	9	85
2540008	268,806	19.73	59.44	0.15	55°	9	83	56°	16	86
2540009	258,352	25.76	61.06	0.38	-	14	36	-	_	_
2540013	1,086,159	14.40	43.77	0.23	63°	15	95	63°	10	93
2540014	1,211,752	17.03	43.77	0.23	60°	15	90	59°	13	91

L. Junctions See Eval Report, section L.

Survey H-10833 was compared with survey H-10802, a 1:10,000 scale survey covering the area immediately to the east of the southern arm of H-10833 and with survey H-10819, a 1:10,000 scale survey covering the area immediately to the south of the main body of H-10833. Agreement between the surveys was very good with the majority of the soundings agreeing within 0.2 fathoms. No adjustment or reconciliation is necessary.

M. Comparison with Prior Surveys V See Eval Report, section M. Not applicable. Not required by contract.

N. Comparison with the Chart & See Evaluation Report, section O.

This survey was compared in Autocad Map to the following charts:

Chart	Scale	Edition	Date
16662	1:100,000	4 th	August 31, 1996
16662 Inset	1:50,000	4 th	August 31, 1996

General agreement between the chart and inset on the chart and this survey was good although some changes in the edges of the shoal areas was detected. This survey also found a number of rocks not noted on the chart. This is probably the result of the high sounding density of this survey. As a result the soundings found tended to both match the chart and contain higher and lower values within the same area of the chart. Survey limits of the unset.

Though no sidescan was collected over the area we are able to detect the location of the pipelines which connect the Dillon, Shell-A and Shell-C oil platforms since they are visible as linear anomalies in the DTM. We checked the location of the pipelines against the corridor shown on the chart and found the pipe to be on the extreme west edge of the corridor which heads north from Dillon to Shell-C. The pipe departs the corridor to the west at the southern limit of this survey. The platforms are depicted on the chart in their correct locations. The pipeline from Shell-C to Shell-A was found to depart the corridor to the east approximately 1000 meters north of Shell-C. In the remainder of this section the pipeline is located up to 160 meters east of the corridor until it rejoins at Shell-A. These location differences have been reported in separate Danger to Navigation reports. The corridor north of Shell-A contains 2 parallel pipelines that were found to be entirely inside the corridor. Near the northernmost point in this survey the pipelines became undetectable near a large rocky formation. The corridor that connects Shell-A southeastwards to the shore was found to contain two parallel pipelines entirely within the corridor. These pipelines are located along the northern edge of the corridor.

The following pages lists the positions of the Drill Rigs, and significant angle points of the located pipelines where they depart from the charted corridor. The next page lists charted soundings around which shoaler (or deeper) soundings were found.

Drill Rig Positions H-10833

Shell-A

Lat. 60°47'42.737" N Long. 151°29'52.087" W Northing

6740912.369

Easting

581765.2927

Shell-C

Lat. 60°45'48.365" N Long. 151°30'15.495" W Northing Easting 6737366.332

581492.0279

^{*}Positions given in NAD 83; UTM Zone 5 coordinates are in meters. Corpscon was used in the conversion.

Item	Latitude	Longitude	Comment
Single Pipeline	60°45′13.529″N	151°30'39.836"W	Southern limit of survey, west of corridor
Pipeline Junction	60°45'48.383"N	151°30'15.505"W	Junction at Shell-C
Single Pipeline	60°46′19.027″N	151°29'59.615"W	Pipeline departs corridor to the east
Single Pipeline	60°47'29.573"N	151°29'34.563"W	Outside of corridor SE of Shell-A
Pipeline Junction	60°47'42.766"N	151°29'52.347"W	Junction at Shell-A

Latitude Comment on agreement with Chart	60° 46' 33.724" N 151° 25' 59.183" W Near 8 Fathom Chart 74	60° 47' 13.942" N 151° 27' 03.734" W Rock near 13 fathom Chart 103 RK	60° 46' 16.129" N 151° 28' 23.273" W Near 11 Fathom Chart 94	60° 46' 48.112" N 151° 29' 04.889" W Near 10 Fathom 1 Foot Chart 95 in vicinty	60° 46' 04.810" N 151° 31' 54.304" W Near 10 Fathom 3 Feet Chart 105 in vicinity	60° 47' 16.535" N 151° 31' 51.104" W Near 11 Fathom Chart 103 in vicinity	60° 47' 38.755" N 151° 31' 22.298" W Near 23 Fathom Chart 19	60° 47' 22.818" N 151° 32' 29.756" W Near 17 Fathom Chart 11	60° 47' 21.639" N 151° 32' 37.865" W On 20 Fathom curve Chart area as shown on 55	60° 48' 26.647" N 151° 28' 54.829" W Well outside 20 Fathom curve chard area as shown		60° 43' 58.222" N 151° 34' 17.665" W On 20 fathom curve Chart axes as a limit of
H-10833 Depth in Fathoms	7.7	10.5	9.7	13.8 60°	14.0 60°	14.9 60°	19.6	11.8 60°	24.0 60°	20.0	30.0	27.0

O. Not Used by Contractor $\sqrt{}$

P. Aids to Navigation \checkmark

There were no Aids to Navigation found in this survey. — concor

Q. Statistics \checkmark

The following list of statistics applies to surveying performed from the *Sea Ducer*, the only vessel used on this survey.

971.30
0
15.2
22
247,249,979
24,044
0
63
97
0
1
0

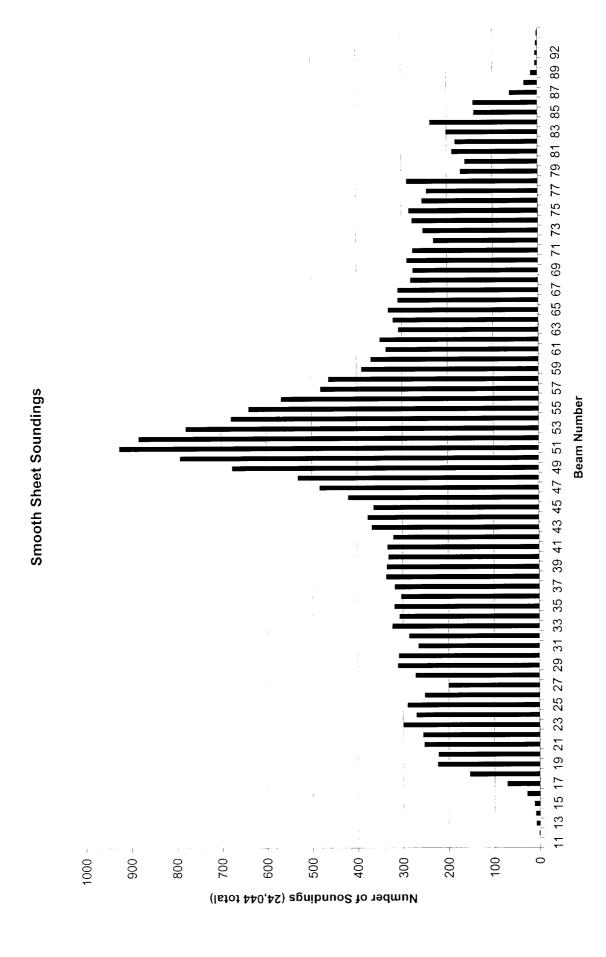
R. Miscellaneous V

This survey found the general location and depths over the shoal to be very similar to the chart. The smooth sheet soundings were analyzed for the number of soundings representing each beam on the Reson 8101 and are included below.

and are included on the following pages.

Reson 8101
Beam # v.s. # of sounds on smooth sheet

<u>Beam</u>	Beam Count	<u>Beam</u>	Beam Count
11	1	52 53	777
12	7	53	677
13	8	54	638
14	11	55 56	566
15	27	56	479
16	71	57 50	461
17	153	58	388
18	223	59	367
19	222	60	334
20	252	61	347
21	255	62	306
22	298	63	318
23	269	64	329
24	289	65	307
25	251	66	307
26	199	67	279
27	271	68	274
28	310	69	287
29	308	70	274
30	265	71	228
31	285	72	251
32	322	73	275
33	306	74	282
34	317	75	253
35	302	76	243
36	316	77	287
37	335	78	169
38	333	79	159
39	330	80	187
40	332	81	180
41	319	82	200
42	366	83	235
43	375	84	139
44	362	85	140
45	418	86	60
46	481	87	28
47	529	88	14
48	675	89	4
49	790	90	4
50	924	92	2
		94	1
		Total	24044



S. Recommendations

We are unaware of any planned activities involving construction or dredging within or adjacent to this area.



May 21, 1999

ADVANCE INFORMATION

Commander (OAN) Seventeenth Coast Guard District P.O. Box 25517 Juneau, Alaska 99802-5517

Reference:

NOAA Survey Number

Contract Number

H-10833

OPR-P367-KR

Dear Sir:

While conducting hydrographic survey operations for the approaches to Nikiski, Alaska (NOAA survey H-10833), Terra Surveys, LLC found shoal soundings and rocks either uncharted or shown deeper than this survey indicates. Attached is the Danger to Navigation Report and a section of chart 16662 indicating the position of these dangers.

Differential GPS and multibeam sonar were used to determine the position and depth. These data are preliminary and subject to office review.

Sincerely,

Terra Surveys, LLC

Thomas S. Newman, PLS

Partner

Enclosures

Cc:

Gary Nelson

NOAA (COTR)



REPORT OF DANGER TO NAVIGATION

Hydrographic Survey Registry:

H-10833

ADVANCE INFORMATION

State:

Alaska

General Locality:

Cook Inlet

Sublocality:

Northern Approach to Port of Nikiski

Project Number:

OPR-P367-KR

The following items were found during hydrographic survey operations:

Objects Discovered: Rocks and Shoal Soundings

Shoal soundings and rocks were found within the survey area, the most significant of which are listed below.

All items listed were corrected to Mean Lower Low Water using observed tide correctors and affect charts:

Chart Number

Edition (Number / Date)

16662

5 / July 05, 1997

16663

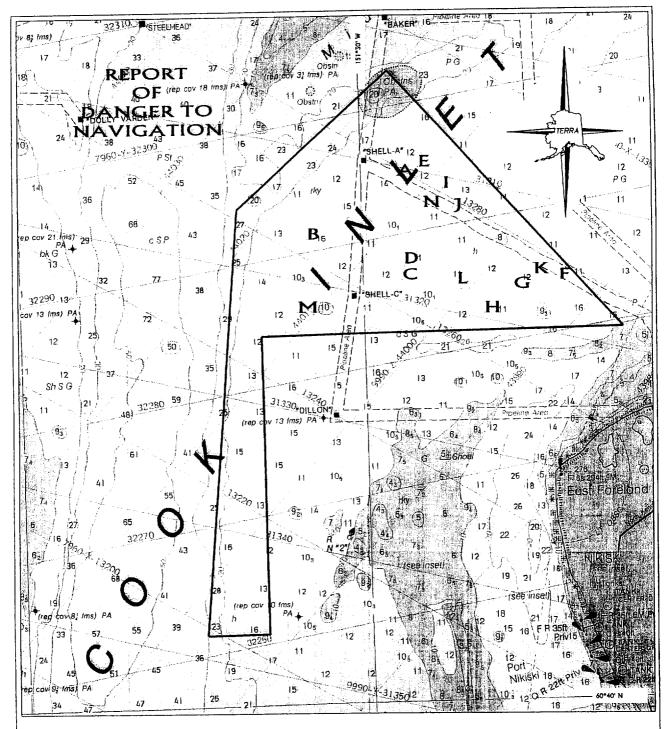
5 / July 12, 1996

16660

27 / April 19, 1997

Geographic Position

ITEM	Description	RADIUS	RE	PORTED	DEI	PTH	CHARTED HORIZ DATUM	LATITUDE	LONGITUDE
Α	sounding	N/A	10	Fathoms	3	Feet	NAD 83	60 47' 28.545" N	151 28' 57.361" W
В	sounding	N/A	10	Fathoms	5	Feet	NAD 83	60 46' 36.835" N	151 31' 36.530" W
С	sounding	N/A	9	Fathoms	5	Feet	NAD 83	60 45' 59.793" N	151 28' 52.269" W
D	sounding	N/A	9	Fathoms	5	Feet	NAD 83	60 46' 11.138" N	151 28' 48.353" W
E	sounding	N/A	10	Fathoms	4	Feet	NAD 83	60 47' 35.411" N	151 28' 19.988" W
F	rock	N/A	10	Fathoms	2	Feet	NAD 83	60 46' 03.804" N	151 24" 17.412" W
G	rock	N/A	10	Fathoms	2	Feet	NAD 83	60 45' 48.645" N	151 25' 22.187" W
Н	sounding	N/A	9	Fathoms	5	Feet	NAD 83	60 45' 29.457" N	151 26' 32.070" W
1	sounding	N/A	10	Fathoms	4	Feet	NAD 83	60 47' 17.007" N	151 27' 37.858" W
J	rock	N/A	9	Fathoms	4	Feet	NAD 83	60 47' 00.373" N	151 27' 21.415" W
K	rock	N/A	9	Fathoms	5	Feet	NAD 83	60 46' 03.920" N	151 24' 50.214" W
L	rock	N/A	9	Fathoms	2	Feet	NAD 83	60 45' 50.468" N	151 27' 11.065" W
M	rock	N/A	9	Fathoms	2	Feet	№Ф 83	60 45' 34.366" N	151 31' 56.483" W
Ν	rock	N/A	9	Fathoms	5	Feet	№Ф 83	60 47' 04.791" N	151 27' 58.082" W



OPR-P367-KR H-10833 Northern Approach to Port of Nikiski

Surveyed By Terra Surveys, LLC Lead Hydrographer: Robert Kohut

Survey Vessel: Sea Ducer Chart 16662 5th Ed., July 5, 1997

Scale of Sketch: 1:100,000 Scale of Survey 1:10,000 REFER TO ACCOMPANYING TEXT FOR ITEM DETAILS

ADVANCE INFORMATION



ADVANCE INFORMATION

May 21, 1999

Commander (OAN)
Seventeenth Coast Guard District
P.O. Box 25517
Juneau, Alaska 99802-5517

Reference:

NOAA Survey Number

Contract Number

H-10833

OPR-P367-KR

Dear Sir:

While conducting hydrographic survey operations for the approaches to Nikiski, Alaska (NOAA survey H-10819), Terra Surveys, LLC found a pipeline outside of its charted corridor. Attached is the Danger to Navigation Report and a section of chart 16662 indicating the position of these pipelines.

Differential GPS and multibeam sonar were used to determine the position of the pipelines. These data are preliminary and subject to office review.

Sincerely,

Terra Surveys, LLC

Thomas S. Newman, PLS

Partner

Enclosures

Cc:

Gary Nelson

NOAA (COTR)

ADVANCE INFORMATION



REPORT OF DANGER TO NAVIGATION

Hydrographic Survey Registry:

H-10833

State:

Alaska

General Locality:

Cook Inlet

Sublocality:

Northern Approach to Port of Nikiski

Project Number:

OPR-P367-KR

The following items were found during hydrographic survey operations:

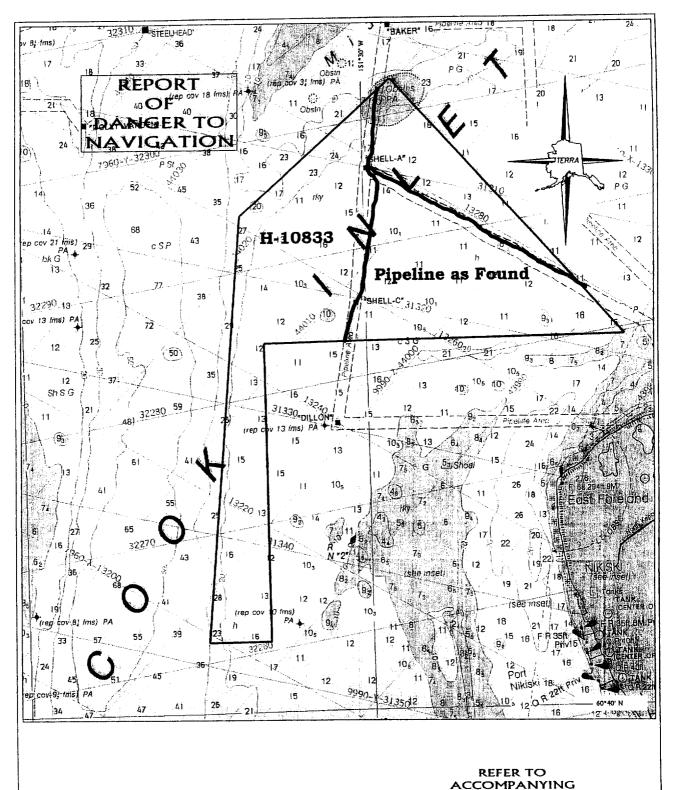
Objects Discovered: Pipeline outside its charted corridor.

Within the survey area bounded by Latitude 60°45.0'N and 60°49'N and Longitudes 151°22.5'W and 151°34.0'W a pipeline which connects Shell-A and Shell-C was found outside its charted corridor. The pipeline was detected as much as 160 meters to the east of the corridor in this section. In addition, the pipeline was detected to the west of the corridor in the section between Shell-A and Dillon at the southern edge of this survey.

This affects charts:

Chart Number	Edition (Number / Date)
16662	5 / July 05, 1997
16663	5 / July 12, 1996
16660	27 / April 19, 1997

Route of single pipeline from Southern Limit of survey to Shell-A Platform:								
Item	Latitude	Longitude	Comment					
Single Pipeline	60°45'13.529"N	151°30′39.836″W	Southern limit of survey, west of corridor					
Pipeline Junction	60°45'48.383"N	151°30'15.505"W	Junction at Shell-C					
Single Pipeline	60°46'19.027"N	151°29'59.615"W	Pipeline departs corridor to the east					
Single Pipeline	60°47'29.573"N	151°29'34.563"W	Outside of corridor SE of Shell-A					
Pipeline Junction	60°47'42.766"N	151°29'52.347"W	Junction at Shell-A					



OPR-P367-KR H-10833

Northern Approach to Port of Nikiski Surveyed By Terra Surveys, LLC Lead Hydrographer: Robert Kohut Survey Vessel: Sea Ducer Chart 16662 5th Ed., July 5, 1997 Scale of Sketch: 1:100,000 Scale of Survey 1:10,000

Nautical Miles ADVANCE INFORMATION

TEXT FOR ITEM
DETAILS

2

3



LETTER OF APPROVAL

REGISTRY NO. H-10833

This report and the accompanying smooth sheet are respectfully submitted.

Field operations contributing to the accomplishment of survey H-10833 were conducted under my direct supervision with frequent checks of progress and adequacy. This report and smooth sheets have been closely reviewed and are considered complete and adequate as per the Statement of Work.

Thomas S. Newman Hydrographer Terra Surveys, LLC July 17th, 2000

NOAA FORM 76-155 U.S. DEPARTMENT OF COMMERCE SURVEY NUMBER NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION **GEOGRAPHIC NAMES** H-10833 P.O. GUIDE OR MAP Bu ho. Con D. E ou Canton E E ON LOCAL MAPS G RAPATLAS H U.S. LIGHT LIST Name on Survey ALASKA (title) χ χ 1 COOK INLET χ Χ 2 NIKISKI (title) χ χ 3 ASSESSED OF SELECT 5 6 Test Person Way 14 NOV 7 8 9 10 11 12 13 15 16 17 18 19 20 21 22 23 24 25

NOAA FORM 76-155 SUPERSEDES C&GS 197

NOAA FORM 77	2.07/U)			II S DEDADTME	NT OF COMMERCE	DECICEDY MUMBI	-n 1
(9 - 83)							en
				STATISTICS		H-10883	
RECORDS AC	COMPANYING SU	RVEY: To be	completed who	en survey is processed			
RECORD DESCRIPTION AMOUNT					RECORD DESCRIPT	TION	AMOUNT
SMOOTH SHEET SMOOTH C					VERLAYS: POS., ARC	C, EXCESS	2
DESCRIPTIVE	REPORT			FIELD SHEE	ETS AND OTHER OVE	ERLAYS	
DESCRIP- TION	DEPTH/POS RECORDS		RIZ. CONT. SONAR- ECORDS GRAMS		PRINTOUTS	ABSTRACTS/ SOURCE DOCUMENTS	·
ACCORDION FILES							
ENVELOPES							
VOLUMES							
CAHIERS							
BOXES							
SHORELINE (DATA ///////						
SHORELINE MA	PS (List):						
PHOTOBATHYM	ETRIC MAPS (List):						
	HYDROGRAPHER (List):						
SPECIAL REP		660 1.1		/F /O.7			
NAUTICAL CH	HARTS (LIST): 16	662, 4t	h Ed., 7		071117450	-	
		The following		FICE PROCESSING AC e submitted with the c	STIVITIES artographer's report on the su	ırvey	
	PROCESS	SING ACTIV	/ITY			AMOUNTS	
					VERIFICATION	EVALUATION	TOTALS
POSITIONS ON SI	HEET		,		<i>\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\</i>		
POSITIONS REVIS	SED				·		
SOUNDINGS REV	ISED						
CONTROL STATIC	ONS REVISED						
						TIME-HOURS	
					VERIFICATION	EVALUATION	TOTALS
PRE-PROCESSING	G EXAMINATION				15.0	-	15.0
VERIFICATION OF	CONTROL						
VERIFICATION OF	POSITIONS						
VERIFICATION OF	SOUNDINGS						
VERIFICATION OF	JUNCTIONS						
APPLICATION OF	PHOTOBATHYMETRY						
SHORELINE APPL	ICATION/VERIFICATION						
COMPILATION OF	SMOOTH SHEET	••			139.0		139.0
COMITICATION OF					1		
	TH PRIOR SURVEYS AN	D CHARTS					
COMPARISON WI	TH PRIOR SURVEYS AND			,			
COMPARISON WI		ORDS	ť	,			

GEOGRAPHIC NAMES OTHER! (Chart Compilation) 43.0 43.0 154.0 85.0 239.0 'USE OTHER SIDE OF FORM FOR REMARKS TOTALS Ending Date 5/25/00 Pre-processing Examination by G.Nelson Beginning Date 5/9/00 Verification of Field Data by
G. Nelson, D. Hill, B. Mihailov

'erification Check by Lee Winduts Ending Date 11/20/00 Time (Hours) 154 Evaluation and Analysis by
B. Mihailov

Action by

Section by

Mirylates Time (Hours) /510 Ending Date 4/16/0/ Ending Date 11/30/00 Time (Hours) 42.0 Time (Hours) 3,0 Ending Date of 16/0/

EVALUATION REPORT

H-10833

A. PROJECT

Survey H10833 was conducted under contract 50-DGCN-8-90021 awarded on April 10, 1998. A Statement of Work (SOW), dated November 28, 1997 contains specific requirements. The purpose of this contract is to provide NOAA with modern, accurate hydrographic survey data with which to update the existing nautical charts of the area.

This survey was conducted by Terra Surveys, LLC of Palmer, Alaska, which is hereafter referred to as the hydrographer. Specific information pertaining to this contractor may be obtained from NOS Hydrographic Survey Division (N/CS35)

B. AREA SURVEYED

The survey area is adequately described in the hydrographer's report. Page-size plots of the charted area depicting the limits of supersession accompany this report as Attachment 1.

Depths range from 7.7 to 33 fathoms. Bottom characteristics are sand, gravel and pebbles

C. SURVEY VESSELS

The hydrographer's report contains information relating to survey vessels.

D. AUTOMATED DATA ACQUISITION AND PROCESSING

Hydrographic data were acquired using a Reson SEABAT 8101 shallow water multibeam system. Data acquisition and processing procedures employed in the field have been adequately documented in the hydrographer's report, section D.

Office review of survey data and the preliminary smooth sheet was accomplished at the Pacific Hydrographic Branch. The final smooth sheet was compiled with MicroStation 95.

The smooth sheet drawing is filed in the MicroStation format, i.e., dgn extension. A copy of this file has been forwarded to the Hydrographic Surveys Division and a backup copy retained at PHB.

The drawing files necessarily contain information that is not part of the CARIS/HIPS data set such as geographic names text, line-type data, and minor symbolization. In addition, those soundings deleted from the drawing for clarity purposes remain unrevised in the CARIS/HIPS digital files to preserve the integrity of the original hydrographic data set. Cartographic codes used to describe the digital data are those authorized by the NOS Hydrographic Surveys Specifications and Deliverables.

The data are plotted using a Universal Transverse Mercator projection and are depicted on a single sheet.

E. SONAR EQUIPMENT

Towed side scan sonar was not utilized during this survey.

F. SOUNDING EQUIPMENT

Sounding equipment has been adequately addressed in the hydrographer's report.

G. CORRECTIONS TO SOUNDINGS

Soundings have been reduced to Mean Lower Low Water (MLLW), with verified tide data obtained from the Ocean Products and Services Division (OPSD) Home Page "Hydro Hot List". The approved tide correctors are zoned from Nikiski, Alaska, gage 945-5760. Further information concerning tides can be found in section G of the hydrographer's report.

Other sounding reducers include corrections for static draft, dynamic draft, sound velocity, heave, roll and pitch. These reducers have been reviewed and are consistent with NOS specifications.

H. CONTROL STATIONS

The positions of horizontal control stations used during hydrographic operations are established by Terra Surveys, LLC based on NAD 83.

The smooth sheet is annotated with an NAD27 adjustment tick based on values determined with the NGS program NADCON. Geographic positions based on NAD27 may be plotted on the smooth sheet utilizing the NAD 83 projection by applying the following corrections.

Latitude: -2.019 seconds (-62.484 meters) Longitude: 8.074 seconds (122.303 meters)

I. HYDROGRAPHIC POSITION CONTROL

Hydrographic position control has been adequately discussed in the hydrographer's report.

J. SHORELINE

There is no shoreline within the limits of survey H-10833.

K. CROSSLINES

Crosslines are adequately discussed in the hydrographer's report.

L. JUNCTIONS

Survey H-10833 junctions with the following surveys

Survey	<u>Year</u>	Scale	<u>Area</u>	
H-10802	1998	1:10,000	East	
H-10819	1998	1:10,000	South	

The junctions with surveys H-10802 and H-10819 have not formally been completed since these surveys have been processed and forwarded for charting. However, a comparison with the present survey reveals good agreement. A few depths have been transferred to the present survey in order to better delineate the bottom configuration. "Adjoins" notes has been added to the smooth sheet to reflect this situation.

M. COMPARISON WITH PRIOR SURVEYS

Survey	Year	<u>Scale</u>	<u>Datum</u>
H-9541	1975	1:20,000	NAD 27
H-9619	1976	1:20,000	NAD 27
H-9621	1976	1:20,000	NAD 27

Prior survey H-9541, H-9619 and H-9621 covers the entire area of the present survey area. The present survey was compared to digital copies of the prior surveys. The registration of these prior surveys to the present survey was good. The legibility of the digital copies was good. Sounding agreement is good with the present survey depths shoaler by 1 to 2 fathoms. Some of this difference is caused by the adjusted vertical datum in Cook Inlet; see section G for further information of the datum adjustment. These differences are attributed to greater sounding coverage and the new vertical datum adjustment as well as the natural erosion and deposition of bottom sediments in the area.

Survey H-10833 is adequate to supersede the prior surveys within the common area.

H10833ER.doc 2

N. ITEM INVESTIGATIONS

No AWOIS items were specifically assigned for this survey. However, during office processing AWOIS item 52426 was evaluated.

O. COMPARISON WITH CHART

Survey H-10833 was compared with the following chart.

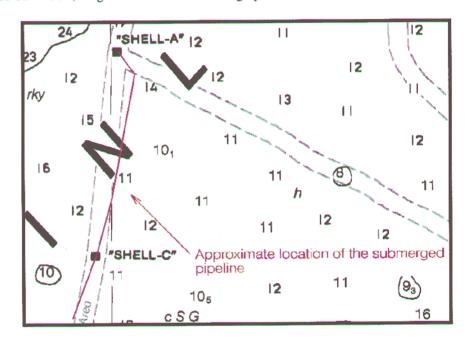
Chart	Edition	<u>Date</u>	Scale
16662	5 th	July 5, 1997	1:100,000 and 1:50,000

a. Hydrography

Charted hydrography originates with the previously discussed prior survey. The prior surveys have been adequately addressed in section M and require no further discussion.

Charted miscellaneous source data has been satisfactorily addressed during survey operations, with the exception of AWOIS item 52426.

The limits of the submerged pipeline charted between latitude 60/45/13N. longitude 151/30/40W and latitude 60/47/42N, longitude 151/29/52W, should be revised as the result of this survey. Multibeam coverage of the area reveals that the pipeline falls outside of the charted pipeline area limits. Consideration should be made on revising the submerged pipeline limits to cover the pipeline between latitude 60/45/13N, longitude 151/30/40W and latitude 60/47/30N, longitude 151/29/35W. See graphic below.



AWOIS 52426: The limits of the Obstruction PA was not fully covered by multibeam, therefore it should be retained as charted.

With the exception of the above, survey H-10833 is adequate to supersede charted hydrography within the area of coverage.

b. Dangers To Navigation

Fifteen dangers to navigation were discovered during survey operations and reported to the USCG on March 21, 1999. Copies of these reports are attached. No additional dangers were found during office processing

P. ADEQUACY OF SURVEY

The hydrography contained on survey H10833 is adequate to:

- a. delineate the bottom configuration, determine least depths, and draw the required depth curves;
- b. reveal there are no significant discrepancies or anomalies requiring further investigation; and
- c. show the survey was properly controlled and soundings are correctly plotted.

With the exception of the following the hydrographic records and reports received for processing are adequate and conform to the requirements of the NOS Hydrographic Surveys Specifications and Deliverables. dated November 29, 1997 and Statement of Work, dated November 28, 1997.

The descriptive report format does not follow the section labeling scheme specified in the Specs and Deliverables, section 8.1.3. This includes the identification of appendices.

Q. AIDS TO NAVIGATION

There are no fixed and floating aids to navigation within the survey area.

There were no features of landmark value located within the area of this survey.

R. STATISTICS

Statistics are itemized in the hydrographer's report.

S. MISCELLANEOUS

Miscellaneous information is discussed in the hydrographer's report. No additional miscellaneous items were noted during office processing.

T. RECOMMENDATIONS

This is a good hydrographic survey.

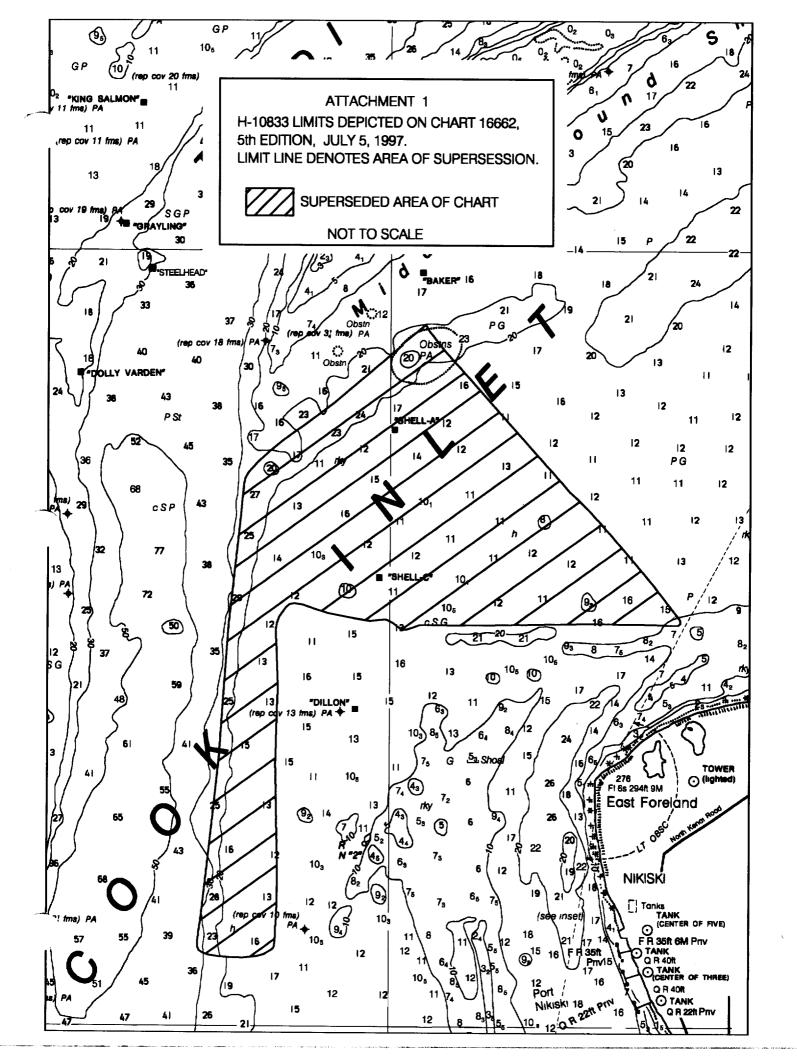
U. REFERRAL TO REPORTS

Referral to reports is discussed in the hydrographer's report.

Bob Mihailov Cartographer

Bo Miharfar

H10833ER.doc



APPROVAL SHEET H-10833

Initial Approvals:

The completed survey has been inspected with regard to survey coverage, delineation of the depth curves, development of critical depths, cartographic symbolization, comparison with prior surveys and verification or disproval of charted data. The survey records and digital data comply with NOS requirements except where noted in the Evaluation Report.

Date: 5/23/01

Ponnis Hill, Chief, Cartographic Team
Pacific Hydrographic Branch

I have reviewed the smooth sheet, accompanying data, and reports. This survey and accompanying digital data meet or exceed NOS requirements and standards for products in support of nautical charting except where noted in the Evaluation Report.

James C. Gardner

Contain NOAA

Chief/Pacific Hydrographic Branch

Final Approval

Approved:

Samuel De Bow Captain, NOAA

Chief, Hydrographic Surveys Division

MARINE CHART BRANCH

RECORD OF APPLICATION TO CHARTS

FILE WITH DESCRIPTIVE REPORT OF SURVEY NO. H-10833

INSTRUCTIONS

A basic hydrographic or topographic survey supersedes all information of like nature on the uncorrected chart.

- 1. Letter all information.
- 2. In "Remarks" column cross out words that do not apply.
- 3. Give reasons for deviations, if any, from recommendations made under "Comparison with Charts" in the Review.

CHART	DATE	CARTOGRAPHER	REMARKS
6662	12/5/00	B. Mihzilov	Full Part Before After Marine Center Approval Signed Via Full application
			Full Part Begiore After Marine Center Approval Signed Via Full application Drawing No. of sndgs & Features from Smooth Sheet.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
			Full Part Before After Marine Center Approval Signed Via
			Drawing No.
		-	· · · · · · · · · · · · · · · · · · ·