

H11662

NOAA FORM 76-35A

U.S. DEPARTMENT OF COMMERCE  
NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION  
NATIONAL OCEAN SERVICE

## DESCRIPTIVE REPORT

*Type of Survey* ..... Hydrographic Lidar

*Field No.* ..... N/A

*Registry No.* ..... H11662

### LOCALITY

*State* ..... Alaska

*General Locality* ..... West of Prince of Wales Island

*Sublocality* ..... San Juan Bautista Island

.....  
2007  
.....

### CHIEF OF PARTY

.....  
Scott Ramsey  
.....

### LIBRARY & ARCHIVES

DATE .....

<p style="text-align: center;">U.S. DEPARTMENT OF COMMERCE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION</p> <p style="text-align: center;"><b>HYDROGRAPHIC TITLE SHEET</b></p>	<p>REGISTRY No</p> <p style="text-align: center;"><b>H11662</b></p>
<p><b>INSTRUCTIONS</b> – The Hydrographic Sheet should be accompanied by this form, filled in as completely as possible, when the sheet is forwarded to the Office.</p>	<p>FIELD No: N/A</p>
<p>State <u>Alaska</u></p> <p>General Locality <u>West of Prince of Wales Island</u></p> <p>Sub-Locality <u>San Juan Bautista Island</u></p> <p>Scale <u>1:10,000</u> Date of Survey <u>April 21 to June 23, 2007</u></p> <p>Instructions dated <u>3/15/2007</u> Project No. <u>OPR-O190-KRL-07</u></p> <p>Vessel <u>Tenix LADS Aircraft VH-LCL</u></p> <hr/> <p>Chief of party <u>Scott Ramsey</u></p> <p>Surveyed by <u>Tenix LADS</u></p> <p>Soundings by <u>Laser Airborne Depth Sounder</u></p> <p>SAR by <u>Toshi Wozumi</u> Compilation by <u>Katie Reser</u></p> <p>Soundings compiled in <u>Meters</u></p>	
<p>REMARKS: <u>All times are UTC. UTM Zone 8</u></p> <p><u>The purpose of this survey is to provide contemporary surveys to update National Ocean Service (NOS) nautical charts. All separates are filed with the hydrographic data. Revisions and end notes in red were generated during office processing. Page numbering may be interrupted or non sequential.</u></p> <hr/> <p><u>All pertinent records for this survey, including the Descriptive Report, are archived at the National Geophysical Data Center (NGDC) and can be retrieved via <a href="http://www.ngdc.noaa.gov/">http://www.ngdc.noaa.gov/</a>.</u></p>	

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**DESCRIPTIVE REPORT TO ACCOMPANY****HYDROGRAPHIC SURVEY H11662****SCALE 1:10,000, SURVEYED IN 2007****TENIX LADS AIRCRAFT, VH-LCL****TENIX LADS, INC. (TLI)****MARK SINCLAIR, HYDROGRAPHER****PROJECT****Project Number:** OPR-O190-KRL-07**Original:** DG 133C-06-CQ-0066**Date of Instructions:** March 15, 2007**Task Order:** T0001**Date of Supplemental Instructions:**

- December 3, 2007 – Email from Dave Schaff (NOAA COTR) indicating CO-OPS authorized use of the JOA final tide zoning correctors for the project area (refer to Appendix V).

**Registry Number:** H11662**Sheet:** D**A. AREA SURVEYED**

Survey operations covered five registered sheets over the OPR-O190- KRL-07 project area, West of Prince of Wales Island, AK (see Figure 1 and Figure 2).<sup>1</sup>

A total of 1969 lineal nautical miles were illuminated in the process of flying 298 main scheme survey lines. An additional 1052 lineal nautical miles were illuminated flying 155 reflines and 459 lineal nautical miles flying 77 crosslines / investigations. The total seabed area surveyed across the project area, from the 0m curve to lidar extinction depth, was 13 square nautical miles (see Appendix III for further information).

Between April 21 and June 23, 2007, the LADS Mk II aircraft conducted 20 sorties West of Prince of Wales Island, based out of Ketchikan. Two forward deployments to Kodiak occurred during this time to conduct survey operations in the OPR-P135-KRL-07 project area. On June 2, 2007, the main base of operations moved to Kodiak. Two forward deployments from Kodiak to Ketchikan were necessary to finalize data collection during June. The specific dates of data acquisition, hours flown and time on task were as follows:

<b>Date</b>	<b>Sortie No.</b>	<b>Hours Flown</b>	<b>Time on Task</b>
22-April-07 1		6:25	5:10
24-April-07 2		5:44	4:50
5-May-07 3		1:47 0:35	
7-May-07 4		5:50	4:55
8-May-07 5		5:25	4:20
9-May-07 6		6:05	5:05
10-May-07 7		5:25	4:03
12-May-07 9		5:20	4:08
14-May-07 10		3:03	1:37
15-May-07 11		3:10	2:15
17-May-07 12		6:15	5:03
18-May-07 13		4:32	3:36
23-May-07 14		1:55	0:46
27-May-07 15		5:53	4:41
28-May-07 17		3:18	2:22
28-May-07 18		6:30	5:37
31-May-07 19		2:35	1:10
13-June-07 22		6:00	5:15
15-June-07 23		7:30	5:45
23-June-07 29		4:27	3:50

**Table 1: Specific Dates of Data Acquisition**

Environmental factors such as water clarity, tide, wind strength and direction, daylight hours, cloud base height and clouds over high terrain influenced the area and duration of data acquisition on a daily basis. See Section B.2.3 for further details.

This Descriptive Report describes Sheet D, which covers the southwest corner of the project area, in the vicinity of San Juan Bautista Island (see Figure 2).

The sheet limits are as follows for Sheet D:

<b>H11662 (D)</b>	<b>Latitude (N)</b>	<b>Longitude (W)</b>
<b>NW corner</b>	55° 27' 59.44"	133° 22' 11.02"
<b>SW corner</b>	55° 23' 53.68"	133° 22' 21.14"
<b>SE corner</b>	55° 23' 45.34"	133° 12' 24.58"
<b>NE corner</b>	55° 27' 51.07"	133° 12' 13.43"



Figure 1 – General Locality of OPR-O190-KRL-07

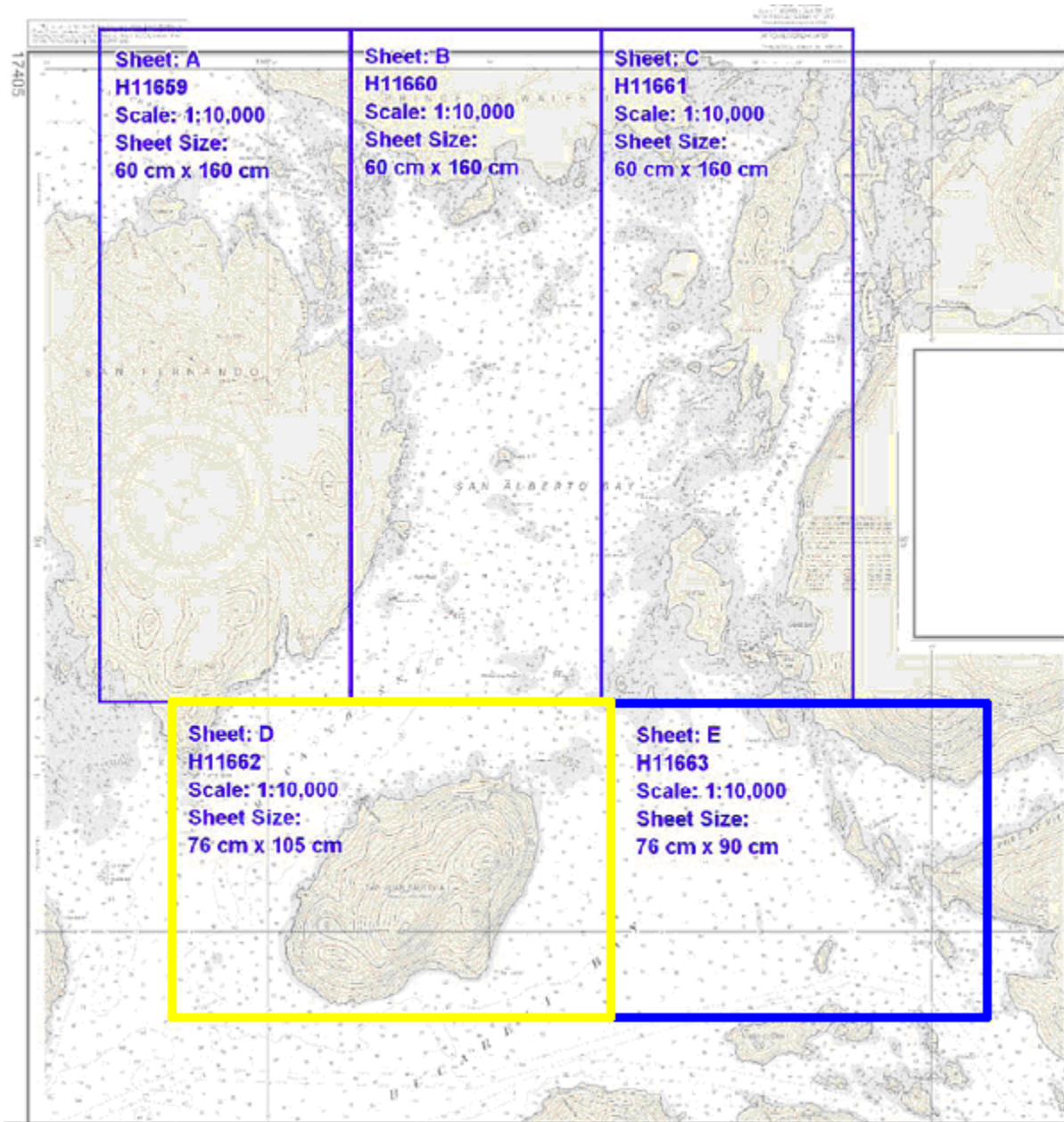


Figure 2 – Sub-Locality of H11662

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## **B. DATA ACQUISITION AND PROCESSING**

Refer to the Data Acquisition and Processing Report for a detailed description of the equipment, processing, and quality control procedures used during LADS surveys. A general description and items specific to this survey are discussed in the following sections.

### **B.1 EQUIPMENT**

Data collection was conducted using the LADS Mk II Airborne System (AS), data processing using the LADS Mk II Ground System (GS), and data visualization, quality control and final products using CARIS HIPS and SIPS 6.1 and CARIS BASE Editor 2.1.

#### *B.1.1 Airborne System*

The LADS Mk II AS platform consists of a De Havilland Dash 8-200 Series aircraft, which has a transit speed of 250kts at altitudes of up to 25,000ft, and an endurance of up to eight hours. Survey operations are conducted from heights between 1,200 and 2,200ft, at ground speeds of between 140 and 210kts. The aircraft is fitted with an Nd: YAG laser, which is eye safe in accordance with ANSI Z136.1-2000, American National Standard for Safe Use of Lasers. The laser operates at 900 Hertz from a stabilized platform to provide a number of different spot spacings across the seabed.

Green laser pulses are scanned beneath the aircraft in a rectangular pattern. The pulses are reflected from the land, sea surface, within the water column and from the seabed. The height of the aircraft is determined by the infrared laser return, which is supplemented by the inertial height from the Attitude and Heading Reference System (AHRS) and a Global Positioning System (GPS) receiver. Real-time positioning is obtained by an Ashtech GG24 GPS receiver providing autonomous GPS, or is combined with WADGPS (Fugro Omnistar), to provide a differentially corrected position, when coverage is available. Ashtech Z12 GPS receivers are also provided as part of the AS and GS to log data on the aircraft and at a locally established GPS base station.

A digital camera was installed on the LADS Mk II system platform prior to commencement of this survey. This allowed high quality images to be captured in real-time, georeferenced and overlaid with the processed survey data. These images were also combined into a georeferenced image deliverable across the extent of the survey area. The specifications for the Redlake MegaPlus II ES 2020 digital camera are provided in the Data Acquisition and Processing Report.

#### *B.1.2 Ground System*

The LADS Mk II GS 'Gandalf' was used to conduct data processing in the field. Gandalf consists of a portable Compaq Alpha ES40 Series 3 processor server with 1 GB EEC RAM, 764 GB disk space, digital linear tape (DLT) drives and magazines, a digital audio tape (DAT) drive, a CD ROM drive, and is networked to up to 12 Compaq 1.5 GHz PCs and a HP 800ps Design Jet Plotter, printers and QC workstations. The GS supports survey planning, data processing, quality control and data export. The GS also includes a KGPS base station, which provides independent post-processed position and height data.



Quality control checks and editing of the data were conducted on GS 'Katrina', at the TLI office in Biloxi, MS, upon completion of the data collection phase of the survey.

## B.2 QUALITY CONTROL

### B.2.1 Quality Control Checks

The internal relative consistency of the survey data was checked with crossline depth comparisons and depth benchmark comparisons in San Alberto Bay, and dynamic position checks, navigation position checks and by observing position confidence quality factors on the GS. System integrity was checked, in an absolute sense, with depth benchmark comparisons in the Gulf of Esquibel, the local GPS base station site confirmation and the static position check.

#### B.2.1.1 Crosslines

No specific crosslines were planned due to the high number of investigation / additional coverage lines (77) flown perpendicular to main scheme survey runs (298). These additional lines were flown to achieve better coverage over off-lying rocks and adjacent to long stretches of coastline. Due to the complex nature of the seabed, just 5 of the 77 investigation lines were selected for depth comparison. These five lines exhibited good water clarity and generally low gradient slopes, enabling meaningful statistics to be calculated. Below are the overall depth comparison results for the 52 crossline / main scheme line intersections. A complete summary is presented in the Separates Report.

Total Number of Comparisons	Mean Depth Difference	Mean Standard Deviation
75406	-0.02 +/- 0.10	0.15 +/- 0.03

#### B.2.1.2 Depth Benchmarks

The depth benchmark area from the 2004 lidar survey in the Gulf of Esquibel (OPR-O167-KRL-04) was used to check the absolute depth accuracy of the LADS Mk II system for the H11662 survey. Following the first sortie, 2 additional benchmark areas were identified within the survey area, and were flown over during each subsequent sortie. These 2 benchmark areas were created in order to assess the consistency of the LADS Mk II system depth performance. Center coordinates for the benchmark areas are as follows:

##### Gulf of Esquibel Benchmark

Benchmark Name	Nominal Depth	UTM (N) Zone 8	
		Easting	Northing
BM_1	15m	586 250	6 172 300

##### San Alberto Bay Benchmark

Benchmark Name	Nominal Depth	UTM (N) Zone 8	
		Easting	Northing
BM_2	10m	614 071	6 149 352
BM_3	11m	614 495	6 148 854



Survey lines were attempted over each of the depth benchmark areas during each sortie. The soundings were reduced to MLLW using Craig final tides and Sitka verified tides with time and range correctors as specified in Section C.2.

The LADS survey data is compared against the gridded benchmark surface in the GS, and statistics are generated which include the number of points compared, the mean depth difference (MDD) and the standard deviation (SD) between the data sets. The benchmark comparison function compares the data against the benchmark surface, and as this data is unedited, it may contain noise normally removed during the validation process. These noisy outliers are flagged as the shoalest and deepest differences.

A summary of the average of the MDD and SD for all depth benchmark area comparisons is presented below. Refer to the Separates Report for detailed results of the depth benchmark comparison results.

#### Gulf of Esquibel Benchmark

<b>GS ID</b>	<b>BM Name</b>	<b>Nominal Depth</b>	<b>MDD</b>	<b>SD</b>
1	BM_1 15m		-0.17 +/- 0.08	0.28 +/- 0.10

#### San Alberto Bay Benchmark

<b>GS ID</b>	<b>BM Name</b>	<b>Nominal Depth</b>	<b>MDD</b>	<b>SD</b>
2	BM_2 10m		0.07 +/- 0.08	0.21 +/- 0.08
3	BM_3 11m		0.04 +/- 0.04	0.17 +/- 0.04

The depth benchmark comparison results and the crossline comparisons results are within expected tolerances and show that the LADS Mk II depth performance was within specifications throughout the survey period.

#### *B.2.1.3 Positioning Checks*

Two independent positioning systems were used during the survey. Real-time positions were determined by autonomous GPS. Post-processed KGPS positions were determined relative to a local GPS base station that was established by JOA on the rooftop of the Best Western Hotel in Ketchikan. The post-processed KGPS positions were applied to each sounding during processing and the KGPS height was used in the topographic datum filter.

Position checks were conducted prior to, during, and following data collection as follows:

- a. Local GPS Base Station Site Confirmation. A 24-hour certification of the local GPS base station established was conducted on April 20-21, 2007. The results reveal that the local GPS base station is free from site specific problems such as multipath and obstructions. Details are provided in the Horizontal and Vertical Control Report and scatter plots in the Separates Report.

- b. **Static Position Check.** Prior to commencing data collection, the coordinates of the aircraft GPS antenna were determined relative to three marks, which were surveyed by JOA on the tarmac at the Ketchikan Airport. Data was logged by each LADS Mark II positioning system while the aircraft was static, enabling the positions to be checked against the known GPS antenna point. The absolute accuracy of the post-processed KGPS solution during the static position check was 0.151m (95% confidence). The results and details of the static position check are enclosed in the Horizontal and Vertical Control Report and Separates Report.
- c. **Dynamic Position Check.** During each sortie, GPS data was logged on the aircraft and at the local GPS base station. This provided a check between the real-time and post-processed GPS positions. The mean difference between the real-time and post-processed positions was 2.109m, with an average SD of 0.302m. Details are provided in the Horizontal and Vertical Control Report.
- d. **Navigation Position Check.** Navigation checks were also conducted over a JOA coordinated point on the SE corner of the Petro Marine dock at Craig, AK. This enabled the known position of the structure to be checked against the downward-looking digital image. This provided a gross error check of position. The mean error in Eastings was 1.5 +/- 0.86m and -0.84 +/- 2.7m in the Northings. Further details are provided in the Separates Report.
- e. **Position Confidence.** The position quality was also monitored on the GS by checking a post-processed position confidence (C3), which is determined from the AS platform error, GPS error, and residual errors between the actual GPS positions and aircraft position, as determined from the line of best fit. No position anomalies were detected.

The position checks were within the expected tolerances and demonstrated that the positioning systems were functioning correctly throughout the survey period.

### *B.2.2 Uncertainty Values*

For this survey area, global horizontal and vertical uncertainties have been assigned based on the defined horizontal and vertical error budget, as stated in the Horizontal and Vertical Control Report. The assigned horizontal uncertainty is 2.52m and the assigned vertical uncertainty is 0.40m.

However, when the calculated grid node SD is greater than the assigned vertical uncertainty, the SD is used as the uncertainty value. This has occurred in areas of high relief, which is common throughout the survey area. In some cases the SD may exceed IHO Order-1 limits. This could be attributed to the seabed gradient and a 3m grid resolution being used.

### *B.2.3 Environmental Factors*

#### *B.2.3.1 Sea Conditions - Sea State, Waves, Swell, White Water*

The sea state ranged from 1 to 3 on the Beaufort Scale throughout the survey period, but was generally between states 1 and 2 in San Alberto Bay and between 2 and 3 in the northwest of the project area. White water was not a concern due to the protected nature of the survey area.

Calm seas were experienced on occasions, particularly in the northeast of the project area. Under such calm conditions the sea became glassy, which degraded the sea surface model, and resulted in gaps at nadir, where the sea surface returns were completely saturated and seabed returns attenuated.

Long period swell was not significant during the survey. However, an allowance has been made in the assessment of vertical accuracy.

#### *B.2.3.2 Water Clarity*

The water clarity in the survey area varied significantly during the period of data collection, and this required careful management to achieve the best possible seabed coverage across the project area. Water clarity varied from extremely poor to good. A total of 9 secchi disk reconnaissances were conducted throughout the survey area prior to and during survey flights, to determine optimal times of data collection and correlate water clarity with laser depth performance. Water clarity reconnaissance reports and secchi disk measurements can be found in the Separates Report.

#### *B.2.3.3 Kelp*

Kelp is one of the factors that increases the complexity of a particular survey area. It is one of the reasons why 200% coverage is recommended in Alaskan waters. Kelp reduces laser penetration and the resultant seabed coverage achieved by lidar. Kelp also increases the amount of data processing that is required and the amount of boatwork that is recommended, as described in Section D.2.1. Large areas of kelp exist throughout the survey area.

Kelp areas can be recognized in the data by the following indicators:

- Mid-water column returns are of low amplitude.
- Waveforms have poorly defined leading edges.
- Returns from the seabed are highly attenuated.
- Soundings in shallow water are very sparse.
- Soundings do not correlate with overlapping data from adjacent lines.

Kelp areas appear as data gaps in the BASE surface. In such areas of partial bottom coverage, kelp area polygons (WEDKLP) have been defined in the S-57 feature file at the boundaries of data gaps attributed to kelp. Where kelp is present, but seabed coverage was still achieved, kelp point objects (WEDKLP) have been defined in the S-57 feature file (US511662.000).

Rocks detected by the system in kelp areas may be difficult to discriminate as rock or kelp returns. When it is uncertain if the return is from rock or kelp, a decision whether the feature has 'least depth found' (LDF) by lidar is provided in Section D.1.6. If it is determined that the LDF on a significant feature has not been achieved by lidar, due to the presence of kelp, the item will appear as a feature for examination in the chart comparison file (H11662\_Inv.hob).

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#### *B.2.3.4 Topography*

The LADS Mk II system can measure topographic heights up to 50m elevation, subject to the depth / topographic logging window selected. For this survey, a 20m topographic height logging window was selected. As a result, the coastline was surveyed and elevations up to 20m were measured. During the processing stage, a maximum height of 5m above the sea surface was used to remove areas where large spruce trees grow near the high waterline. For areas of exposed rock that were greater than 5m above chart datum, the topographic heights were retained to ensure that the rock or islet height is correct. In areas where the Mean High Water (MHW) line could not be determined due to spruce trees, a 'gap tree' tag was inserted in the GS and with the use of the georeferenced imagery and exported tags, the MHW line has been dashed to indicate an approximate location.

The maximum topographic heights achieved in this area are limited by the topographic logging window and by spruce tree foliage. This can be seen as gaps in the BASE surface, indicating areas of no coverage in the center of islands and along the coastline. As a result of the restricted topographic window and spruce trees, some island heights will exist above the delivered survey data range.

#### *B.2.3.5 High Ground*

For this survey high ground was a significant issue, and the majority of the northeastern survey lines were flown at 2,200ft. Low cloud coverage was often prevalent along the edge of high terrain. During periods of adverse weather, lines were flown around San Juan Bautista Island or through the middle of the survey area at altitudes between 1,200 and 1,600ft, below the cloud ceiling.

#### *B.2.3.6 Wind*

Survey operations were conducted in wind strengths of up to 20kts during the survey. In general, the wind strength during sorties was between 5 and 15kts from the SW. In certain areas, wind strengths above 10kts generated turbulence that made data collection difficult. In circumstances when wind speeds were forecast to be greater than 20kts, no flights were planned due to the possibility of dangerous levels of turbulence.

#### *B.2.3.7 Cloud*

Low cloud coverage and rain was a significant factor during the survey. The wind direction affected the cloud base in the survey area. For example, in southerly or easterly conditions a low cloud base was experienced. Poor weather was monitored using, and decisions on the flying program were based on:

- Real-time satellite imagery
- Radar data
- Aviation reports
- Reports from local contacts in Craig
- Pilot weather reports
- Images viewed from a webcam located S of Craig

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Two Internet sites proved to be invaluable for forecasting the weather. An aviation site, <http://adds.aviationweather.gov>, provided METAR data, actual wind speed and direction, cloud base and satellite cloud data. The observations were updated every twenty minutes. A NOAA weather site, <http://pafc.arh.noaa.gov>, provided aviation and general weather forecasts.

#### *B.2.4 Data Coverage and Object Detection*

##### *B.2.4.1 Nature of the Seabed*

The nature of the seabed surrounding San Juan Bautista Island is quite complex. The coastlines of San Juan Bautista Island, San Fernando Island and a number of small islands are covered with spruce trees, which made the delineation of the MHW line difficult in some areas.

Throughout the sheet there are numerous rocks, islets and shoals, often surrounded by thick areas of kelp. Typically, kelp grows from the MLLW line to 10m water depth. It is often visible on, or just below the sea surface, in the downward-looking digital imagery. Most gaps in lidar data coverage, in less than 10m depth, are directly attributed to the presence of kelp.

The seabed gradient is generally high along the San Juan Island and SE San Fernando Island coastlines, with the seabed dropping to beyond 20m depth quickly. In the northeast area of the sheet, in the vicinity of Balandra Island, there are a number of shoals, with a relatively low gradient seabed between them. In this area the seabed has gently undulating slopes.

##### *B.2.4.2 Data Coverage*

The survey area was illuminated at 4x4m laser spot spacing, resulting in a 192m swath width. Mainlines of sounding were spaced at 85m, which provided the required 200% coverage.

The gain levels automatically set by the AS accommodate for changes in the sea surface, water column and seabed conditions. In some areas, after long overlapped passages, low gain levels were initialized when passing back over the water. Where this has been identified in the data, these lines were re-flown from the opposite direction to improve the coverage. In some inshore areas, reciprocal lines could not be flown due to the proximity of high ground at the start / end of the line. This adversely affected seabed coverage along some coastlines.

The raw laser waveform returns from the areas that were covered with kelp are considerably attenuated. In order to detect the seabed in such areas, the threshold in the GS was lowered to detect pulses with low signal-to-noise ratios (SNR). This often enabled the seabed depth to be extracted from the waveform, but also resulted in increased false bottom detects, which in turn increased data validation times.

The variable water clarity observed throughout the survey period resulted in maximum lidar extinction depths of 25m for the project, but typically, full seabed coverage to 20m depth was achieved for H11662.

#### *B.2.4.3 Object Detection*

At the sea surface the footprint of the laser beam is approximately 2.5m in diameter. As the beam passes through the water column, it slowly diverges due to scattering. It should be noted that at 4x4m laser spot spacing, there is a gap of 1.0 to 1.5m between the illuminated area of adjacent soundings at the sea surface. There is a possibility that small objects in shallow water along the coastline may fall between consecutive 4x4m soundings, and not be detected. A description of the Bottom Object Detection (BOD) algorithm used in data processing is presented in the Data Acquisition and Processing Report.

### **B.3 CORRECTIONS TO SOUNDINGS**

Refer to the Data Acquisition and Processing Report for a description of corrections to soundings. There were no deviations from the corrections described therein.

### **B.4 DATA PROCESSING**

#### *B.4.1 Data Management*

The database is identified as follows:

<b>Database Name</b>	<b>Sub-Locality</b>	<b>Sheet</b>
07_POW	San Juan Bautista Island	D

A detailed table of survey line identifiers is presented in the Data Acquisition and Processing Report.

#### *B.4.2 Data Processing Sites*

The data acquired during survey flights was processed at the operating site in Ketchikan following each sortie. During the final two forward deployments to Ketchikan in June, a copy of the raw survey data was made following each sortie and the backups were sent to the main base of field operations at Kodiak for processing. Final validation, checking, approving, reports and products were conducted at the office in Biloxi, MS. The quality control of the data was done using CARIS software and was conducted in the Biloxi, MS office.

#### *B.4.3 CARIS BASE Surface*

One BASE surface covers the entire survey area. The Shal layer of the BASE Surface should be used as the official hydrographic record of the survey. A grid resolution of 3m was used for the BASE surface. Grid resolution does not change relative to depth, as the laser pulse footprint stays relatively constant regardless of depth, and the laser spot spacing is constant irrespective of aircraft altitude. The 3m grid provides the largest amount of detail that can be supported by the lidar density.

#### *B.4.4 Gap and Feature Tagging*

During data processing on the GS, the operators have the ability to assign S-57 and user-defined tags to gaps and features in the data. This enables accurate delineation and attribution of unsurveyed polygons for the S-57 feature file (US511662.000).

For this survey, the following user-defined tags were used to delineate the seaward extent of gaps in the lidar seabed coverage, typically at a 50m interval:

GK	Bathymetry data gap due to kelp.
GS	Bathymetry / topography data gap due to the secondary exclusion zone (SEZ).
GTR	Topography data gap due to the detection of foliage in spruce trees.

Detailed descriptions of these gaps in seabed coverage are presented in Section B.8 of the Data Acquisition and Processing Report.

The following tags were used in the GS for features that require further examination:

FEK	Feature for examination in kelp, as the least depth has not been determined.
FERK	Feature for examination of a submerged rock, as the least depth has not been determined, or a higher density of data is required to adequately define the feature.
FERA	Feature for examination of a rock awash, as the feature has not been surveyed adequately due to the presence of white water.
FEDR	Feature for examination of a drying rock, as a higher density of data is required to adequately define the potentially drying feature.
FE	Feature for examination, generally in deep water, as the least depth has not been found due to poor water clarity.

The tags associated with features requiring further examination have been compiled in the H11662\_Inv.hob file, and each have been given certain priority and a suggested examination method for the undertaking of additional boatwork.

In most cases the least depth has deemed not to be found on a feature and it requires further examination by boat to determine the least depth.

#### *B.4.5 Georeferenced Imagery*

Digital imagery was captured on each sortie. The imagery was used in the validating, checking, and approval stages of survey data cleaning. The images were also combined to produce a georeferenced mosaic of the survey area.

#### *B.4.6 Progress Sketches*

Progress sketches were provided to NOAA on a monthly basis. The final progress sketch can be found in Appendix III.

#### *B.4.7 Deliverables Data Formats*

Data is provided in the following formats:

- Digital S-57 feature file
- CARIS BASE surface
- CARIS features for investigation and chart comparison files in .hob format



- CARIS compatible data – CAF Form at – LADS soundings and waveforms, which can be imported into CARIS HIPS
- CARIS compatible data – HDCS Form at – LADS soundings in CARIS HIPS native format
- Tidal data provided in ASCII, .xls and .csv formats
- Digital georeferenced image in .tif / .tiff format

Refer to the Data Acquisition and Processing Report for specific details.

## C. VERTICAL AND HORIZONTAL CONTROL

Refer to the Horizontal and Vertical Control Report for a detailed description of the horizontal and vertical control used during this survey. A summary of horizontal and vertical control used for the survey follows.

### C.1 VERTICAL CONTROL

Vertical control for the survey was based on the Mean Lower Low Water (MLLW) tidal datum. A temporary gauge installed by John Oswald and Associates (JOA) at Craig, AK served as vertical control for the project area.

Station details are as follows:

Gauge	Location	WGS84	
		Latitude	Longitude
9450551	Craig Petro-Marine dock	55° 29.3' N	133° 08.5' W

### C.2 ZONING

NOAA initially supplied tide zones and correctors relative to Sitka (9451600) in the Statement of Work (SOW), covering the extent of the survey area. During field operations tide data for the National Water Level Observation Network (NWLON) station at Sitka was downloaded from the CO-OPS website and these preliminary tide values were used to reduce depth soundings.

Following data acquisition JOA supplied verified tides for the temporary Craig gauge and new time and range correctors were computed for the tide zone areas provided in the SOW. The new zone correctors relative to the subordinate gauge at Craig were approved for final tide reduction by CO-OPS and these supplemental instructions are provided at Appendix V. The final tide zone parameters are presented in the table below:

Tide Zone	GS Identifier	Time Corrector	Range Corrector	Reference Station
SA227	TA1	+0 minutes	x 1.03	9450551
SA228	TA2	+0 minutes	x 1.02	9450551
SA229	TA3	+6 minutes	x 1.00	9450551
SA250	TA4	+0 minutes	x 1.00	9450551
SA227A	TA5	-12 minutes	x 1.06	9451600

For final tide application, the time and range correctors were applied to the smoothed tidal data provided by JOA. Soundings were then reduced to MLLW using these corrected tides. An analysis of depth benchmark and crossline comparisons, and overlaps of the mainlines of sounding concluded that final tide zoning was adequate.

Tide zone SA227A was created to reduce soundings over the LADS depth benchmark in the Gulf of Esquibel, in order to check vertical accuracy performance at the beginning and throughout the survey period. Time and range correctors for this tide zone were sourced from the SOW for OPR-O167-KRL-04, conducted by TLI in 2004. It was necessary to create this additional tide zone, outside the survey area, to compare reduced depth soundings in 2007 to the same vertical datum used to establish the depth benchmark area in 2004.

The derived value for the difference between MLLW and MHW at the Craig subordinate tide gauge is 2.842m. From the final zoning, a range factor of 1.00 was applicable for Sheet D, resulting in a MHW value of 2.84m.

### C.3 HORIZONTAL CONTROL

Data collection and processing were conducted on the AS and GS in World Geodetic System (WGS84) on Universal Transverse Mercator (Northern Hemisphere) projection UTM (N) in Zone 8, Central Meridian 135 ° W. This data was post-processed and all soundings are positioned relative to the North American Datum 1983 (NAD83). All units are in meters.

#### C.3.1 LADS Local GPS Base Station – Ketchikan

Real-time positions were determined using an Ashtech GG24 GPS receiver on the aircraft, operating in autonomous GPS mode. A local GPS base station was established by JOA on the roof of the Best Western Hotel in Ketchikan, AK on April 10, 2007, in order to post-process KGPS positions following survey flights.

The derived NAD83 coordinates for the local GPS base station are:

NAD83		UTM (N) Zone 8		
Latitude (N)	Longitude (W)	Easting (m)	Northing (m)	Ellipsoidal Height (m)
55° 21' 18.1747"	131° 41' 28.1482"	709 747.774	6 139 286.936	12.85

Post-processed KGPS positions were determined offline using data logged at the local GPS base station and on the aircraft. This data was processed with Ashtech PNAV software to calculate both a DGPS and KGPS position solution for the survey flights. The post-processed KGPS positions were imported into the GS and applied to all soundings. This provided increased sounding position accuracy from the real-time autonomous GPS.

## D. RESULTS AND RECOMMENDATIONS

The results for the H11662 survey are submitted separately to this Descriptive Report as the S-57 feature file, BASE surface, CARIS .hob files, georeferenced imagery, Chart Comparison Spreadsheet, etc. on the USB hard drive. Refer to Appendix II of the Data Acquisition and Processing Report for a list of all the deliverable files from H11662.

Below is a table listing the S-57 feature objects found in the S-57 feature file (US511662.000):

S-57 Object Class	S-57 Object Acronym	Geometry	Description	Spatial Attribute	Attribute 1	Attribute 2	Attribute 3	Attribute 4	Comments
Coastline	COALNE	L	The high waterline. Where depth equals 0 relative to MHW.	Quality of position (QUAPOS)	Category of Coastline (CATCOA)				The spatial attribute QUAPOS is used when coastline is interpolated from the (GTR) tags or the georeferenced imagery.
Depth Contour	DEPCNT	L	The approximate location of the line of equal depth. Also referred to as a depth curve.		Value of depth contour (VALDCO)				Tenix is only responsible for defining the 0m curve.
Land Area	LNDARE	P	The solid portion of the Earth's surface, as opposed to sea, water.						Used for defining islet point features.
Land Elevation	LNDELV	P	The vertical distance of a point or level measured from a specified vertical datum.		Elevation (ELEVAT)				Used for defining islet heights related to MLLW.
Underwater / Awash Rock	UWTROC	P	A concreted mass of stony material or coral which dries, is awash or is below the water surface.		Water level effect (WATLEV)	Quality of sounding measurement (QUASOU)	Technique of sounding measurement (TECSOU)	Value of sounding (VALSOU)	
Weed / Kelp	WEDKLP	P, A	Usually large, blade-shaped or vine-like brown algae.		Category of weed / kelp (CATWED)				Polygon limits defined using the (GK) tags exported from the GS. Kelp point features defined using the (GKP) tags exported from the GS and georeferenced imagery.

S-57 Object Class	S-57 Object Acronym	Geometry	Description	Spatial Attribute	Attribute 1	Attribute 2	Attribute 3	Attribute 4	Comments
Unsurveyed Areas	UNSARE	A	Unsurveyed area.		Information (INFORM)				Used to define gaps in data coverage. INFORM has been identified as SEZ (GS) tags.
<i>Meta Objects</i>									
Coverage	M_COVR	A	A geographical area that describes the coverage and the extent of spatial objects.		Category of coverage (CATCOV)				M_COVR: CATCOV = 1 polygons define the extents of good LIDAR data coverage.
Quality of Data	M_QUAL	A	An area within which a uniform assessment of the quality of the data exists.		Category of zone of confidence in data (CATZOC)				

**Table 2: S-57 Attribution for the S-57 feature file (US511662.000)**

Recommendations for registry number H11662 are divided into 2 components:

1. Recommended charting action, primarily for MCD.
2. Recommended further boatwork to sufficiently junction with lidar seabed coverage and examine uncertain lidar features.

Recommendations for charting action for registry number H11662 are provided in Sections D.1.1 to D.1.6 below. The Chart Comparison Spreadsheet has historically been one of the sources for the lidar features for examination list. In order to provide just one list of features for examination to field units, the Chart Comparison Spreadsheet has had some minor adjustments for this survey (H11662\_ChartComp.xls). All features that appear in the chart comparison, but have not accurately had least depth determined by lidar, appear in the features for examination file. Where the least depth has not been found by lidar, no recommended charting action has been specified. Instead, a vessel-based verification method is suggested. The determination of least depth is at the discretion of the ships conducting junctioning / investigations and their results should be reported for charting action to MCD in due course. Recommendations for ship junctioning and investigations are provided in Section D.2.1. In order to minimize the historical double handling of reporting uncertain lidar soundings on features, the features for examination are now contained exclusively in the CARIS .hob file (H11662\_Inv.hob). The features for examination have been prioritized with respect to multibeam junctioning, investigating features in 'coastal' foul areas and within the NALL.

A summary of charting actions and investigations is provided in Section D.2.2.

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## D.1 CHART COMPARISON

H11662 LADS survey deliverables were compared to:

ENC US5AK4BM Edition 1 and ENC US5AK4CM Edition 2, compiled from Raster Chart 17405 15<sup>th</sup> Edition. ENC update application date October 18, 2007, at scale 1:40,000.

This chart was downloaded from the NOAA Office of Coast Survey – NOAA Electronic Navigational Charts download website on October 23, 2007.  
(<http://chartmaker.ned.noaa.gov/mcd/ENC/download.htm>)

Recommendations for charting action are described in Sections D.1.4 to D.1.6.

### *D.1.1 Dangers to Navigation*

Danger to Navigation (DTON) reports were submitted to Pacific Hydrographic Branch (PHB) from the field and during deliverables compilation. The first DTON submission from the field coincided with the delivery of the monthly progress at the end of May 2007. The second DTON submission from the field coincided with the delivery of the monthly progress sketch at the end of June 2007. Final DTON recommendations were provided to PHB, as part of the preliminary survey delivery, in November 2007. Refer to Appendix I for the recommended DTON submissions to PHB and MCD.

A description of each DTON for H11662 is provided below:

- Item number 1 is a 0.0m Rk Awash located on the E coast of San Juan Bautista Island, approximately 2400m NNE of Point Miliflores. Submitted from the field.
- Item number 2 is a 12.6m Rk located in the vicinity of a charted 40m sounding on the NW coast of San Juan Bautista Island, approximately 850m SW of Point Eugennia. Submitted from the field.
- Item number 3 is a 12.0m Rk located in the vicinity of a charted 18.2m sounding on the NW coast of San Juan Bautista Island, approximately 300m W of Point Eugennia. Submitted from the field.
- Item number 4 is a 2.3m Rk located to the S of San Fernando Island, approximately 450m W of Point Amargura. Submitted from the field.
- Item number 5 is a 9.9m Rk located to the S of San Fernando Island, approximately 800m SSW of Point Amargura. Submitted from the field.
- Item number 6 is a 0.3m Rk Awash located to the S of San Fernando Island, approximately 400m WSW of Point Amargura.
- Item number 7 is 6.3m Rk located to the S of San Fernando Island, approximately 500m SSW of Point Amargura.
- Item number 8 is a 10.8m Rk located to the S of San Fernando Island, approximately 500m SW of Point Amargura.
- Item number 9 is a 3.6m Rk located to the S coast of San Juan Bautista Island, approximately 100m S of Point Miliflores.

*D.1.2 AWOIS*

No AWOIS were assigned to this Task Order.

*D.1.3 Aids to Navigation*

One Aid to Navigation was detected by lidar in the survey area for H11662:

Buoy Name	Charted Position		Average Surveyed Position		Difference In Position (m)	Lidar Hits
	Latitude (N)	Longitude (W)	Latitude (N)	Longitude (W)		
Point Amargura Ledge Buoy 1	55° 26' 34.88"	133° 21' 41.58"	55° 26' 35.79"	133° 21' 41.79"	28	5

*D.1.4 Charted Depths and Features*

Registry number H11662 covers part of NOAA raster chart 17405, including San Juan Bautista Island, Balandra Island in the NE and Point Amargura on the S coast of San Fernando Island in the NW. From the Source Diagram, the area covered by survey area H11662 was covered by NOS surveys between 1900 and 1939, and 1940 and 1969, presumably by leadline and single beam echo sounder. Partial bottom coverage was achieved. The chart in this area was not comprehensively surveyed, with the coastline and some significant rocks and islets along the coast portrayed.

The area surveyed is represented by the BASE surface and S-57 feature file in considerably more detail than is currently shown on the chart. The following general recommendations are relevant:

- a. Coastline. The generalized charted coastline agrees fairly well with the surveyed coastline for the larger islands and islets. The surveyed coastline differs from the charted position by a maximum of 35m in some parts of the survey area. There are a few locations where the charted coastline has been surveyed as drying shelf. It is recommended that the coastline on the chart be amended to match the LADS surveyed and extrapolated MHW line.
- b. Inshore Islets. A large number of islets have been surveyed close to the coastline. Generally, there is good agreement between the charted data and the surveyed data. It is recommended that the chart be amended to match the LADS survey deliverables. Where significant these islets are detailed in the Chart Comparison Spreadsheet in Section D.1.6.
- c. Rocks. Many rocks and drying rocks have been surveyed along the coastline, which are not presently shown on the chart. It is recommended that the chart be amended to match the LADS survey deliverables. Where significant, these rocks are detailed in the Chart Comparison Spreadsheet in Section D.1.6.



### D.1.5 Detailed Chart Comparison

In addition to the general recommendations above, some 79 specific differences between the chart and the LADS survey have been identified and are described in Section D.1.6. An expanded version of the spreadsheet is included digitally on the USB hard drive (H11662\_ChartComp.xls). A CARIS .hob file containing just the chart comparison items has also been compiled and is provided as part of survey deliverables (H11662\_ChartComp.hob). The attribution methodology for this file is presented below:

S-57 Object Class	S-57 Object Acronym	Geometry	Description	Attribute 1	Attribute 2	Attribute 3	Attribute 4
Nautical publication information	M_NPUB P		Used to relate additional nautical information or publications to the data	INFORM (used for storing a unique chart comparison ID)	NINFOM (used for storing the charting recommendation)	PUBREF (used for storing a reference to a Feature for Investigation)	PICREP (used for storing a link to waveform screen captures)

The chart comparison was conducted by reviewing the chart, the LADS survey deliverables and the digital georeferenced imagery. For each item identified, screen dumps of the Local Area Display, Raw Waveform Display and Digital Image Window were extracted from the LADS Mk II GS.

These have been reviewed in order to make the following assessments:

- a. Type of Feature
- b. Kelp Area
- c. Least Depth Found
- d. Charting Recommendation
- e. Remarks

When the least depth has been adequately surveyed by lidar, the LDF Column is populated with a 'Y' for yes. The charting recommendation for a feature that has an adequately surveyed least depth will be either 'Insert' for a new feature, 'Replace' for an amendment to an existing charted feature or 'Remove' for a disproved charted feature.

When the least depth has NOT been found by lidar (populated with an 'N'), the chart comparison number has been used as the identifier within the S-57 feature file that contains the features for examination. If a chart comparison item had previously been identified as a feature for examination during data processing, a reference is made in the 'Remarks' column to the S-57 feature for examination item. For all chart comparison items that have not had least depth surveyed adequately, a suggested boatwork examination method acronym has been assigned. The description of these is provided in Section D.2.1.4.

Each chart comparison was categorized as follows:

1. New shoal found
2. Charted shoal disproved / not found

The fields in the Chart Comparison Spreadsheet have been developed from experience learned and feedback received from previous lidar surveys in Alaska, witnessing survey operations aboard NOAA ship Rainier, from meetings at PHB and UNH and the 2007 NOAA Field Procedures Workshop. They have been designed for ease of use and to minimize double handling of data and transcription. Continued feedback is welcomed in order to develop these formats to achieve further efficiencies in data handling.

## D.1.6 Chart Comparison Spreadsheet

Sequence No	Shoal No	Category	CHARTED			SURVEYED			Type of Feature	Kelp Area	Least Depth Found	Charting Recommendation	Remarks
			Charted Depth (meters)	NAD 83 Latitude N (degrees)	NAD 83 Longitude W (degrees)	Surveyed Depth (meters)	NAD 83 Latitude N (DMS)	NAD 83 Longitude W (DMS)					
1 D	2	2	Drying Rk	55° 27' 10.77"	133° 21' 50.28"				Slope	N	Y	Remove	Not detected by lidar, not observed in georeferenced imagery.
2	D5	2	Islet	55° 26' 59.26"	133° 21' 41.25"	-2.93	55° 26' 59.1342"	133° 21' 40.14"	Drying Rk	Y Y		Replace	
3	D6	1				-3.20	55° 26' 59.3646"	133° 21' 37.5462"	Drying Rk	Y Y		Insert	
4	D7	1				3.29	55° 27' 0.2052"	133° 22' 2.7462"	Rk	Y	Y	Insert	
5	D8	2	3.1	55° 26' 55.51"	133° 21' 58.62"	0.34	55° 26' 55.2005"	133° 21' 59.9782"	Rk Awash	Y N		VV	Possible rock awash in kelp. Refer to FERAD1. See Danger to Navigation report. Item 6.
6	D9	1				2.84	55° 26' 57.5372"	133° 21' 59.0537"	Rk	Y	N	BV	Possible Rk in kelp.
7	D10	1				2.04	55° 26' 53.7565"	133° 21' 59.9522"	Rk	Y	N	BV	Possible Rk in kelp.
8	D11	2	14.6	55° 26' 38.75"	133° 21' 54.67"	11.62	55° 26' 38.8867"	133° 21' 54.275"	Rk	N	Y	Replace	
9	D12	2	8.5	55° 26' 45.55"	133° 21' 47.2"	6.32	55° 26' 44.6388"	133° 21' 48.5219"	Rk	Y	Y	Replace	See Danger to Navigation report. Item 7.
10 D	13	2	25.6	55° 26' 42"	133° 21' 28.28"	18.92	55° 26' 40.7249"	133° 21' 29.9701"	Rk	N	N	JV	Sparse lidar coverage in deep water. Refer to FED1.
11	D14	2	31.0	55° 26' 34.09"	133° 21' 37.08"	18.70	55° 26' 36.6176"	133° 21' 39.2386"	Rk	N	Y	Replace	
12 D	15	2	Drying Rk	55° 27' 9.77"	133° 21' 26.98"				Slope	Y	Y	Remove	Not detected by lidar, not observed in georeferenced imagery.
13	D19	2	25.6	55° 26' 50.73"	133° 18' 9.55"	7.61	55° 26' 52.6895"	133° 18' 10.8702"	Rk	N	Y	Replace	
14	D21	2	4 islets	55° 26' 50.56"	133° 17' 58.58"				Slope	Y	Y	Remove	4 charted islets not detected by lidar, not observed in digital imagery.

## Shoal Categories

1-New Shoal Found

2-Charted Shoal Disproved / Not Found

Sequence No	Shoal No	Category	CHARTED			SURVEYED			Type of Feature	Kelp Area	Least Depth Found	Charting Recommendation	Remarks	
			Charted Depth (meters)	NAD 83 Latitude N (degrees)	NAD 83 Longitude W (degrees)	Surveyed Depth (meters)	NAD 83 Latitude N (DMS)	NAD 83 Longitude W (DMS)						
15	D22	2	12.8	55° 26' 47.14"	133° 17' 56.96"	2.62	55° 26' 48.0343"	133° 17' 57.0631"	Rk	Y	Y	Replace	All items covered by 4x4m laser spot spacing at 200% lidar coverage.	
16	D23	2	20.1	55° 26' 49.45"	133° 17' 48.5"	14.93	55° 26' 51.14"	133° 17' 49.097"	Rk	N	Y	Replace		
17	D24	1				-0.39	55° 26' 42.4734"	133° 17' 56.6023"	Rk Awash	Y	Y	Insert		
18	D 25	2	Drying Rk	55° 26' 41.17"	133° 17' 39.04"				Beach	N	Y	Remove		Note: Charted drying rock surveyed as beach.
19	D26	1				-1.21	55° 26' 45.6522"	133° 17' 27.9668"	Drying Rk	Y	Y	Insert		
20	D27	2	16.4	55° 26' 48.49"	133° 16' 39.13"	7.28	55° 26' 48.4012"	133° 16' 42.1874"	Rk	Y	Y	Replace		
21	D28	2	14.6	55° 26' 59.67"	133° 16' 8.26"	7.12	55° 26' 58.1287"	133° 16' 5.6435"	Rk	Y	Y	Replace		
22	D29	2	16.4	55° 26' 55.67"	133° 16' 20.75"	10.75	55° 26' 56.0188"	133° 16' 16.9648"	Rk	N	Y	Replace		
23	D 31	1				5.36	55° 26' 58.1708"	133° 16' 0.5286"	Rk	Y	Y	Insert		
24	D32	2	20.1	55° 27' 3.05"	133° 15' 51.16"	16.42	55° 27' 1.0793"	133° 15' 49.0684"	Rk	N	Y	Replace		
25	D33	1				-2.26	55° 26' 55.586"	133° 15' 42.1794"	Drying Rk	Y	Y	Insert		
26	D35	1				0.03	55° 26' 43.4188"	133° 13' 58.5898"	Rk Awash	Y	Y	Insert		
27	D36	2	18.2	55° 26' 47.56"	133° 13' 21.78"	15.50	55° 26' 47.0357"	133° 13' 23.1337"	Rk	N	Y	Replace		
28	D37	1				-2.87	55° 27' 7.0189"	133° 13' 9.8051"	Drying Rk	Y	Y	Insert		
29	D38	1				-1.57	55° 25' 31.615"	133° 14' 10.2023"	Drying Rk	Y	Y	Insert		
30	D39	2	35.0	55° 25' 19.96"	133° 14' 6.56"	19.25	55° 25' 21.3967"	133° 14' 10.8604"	Rk	N	Y	Replace		

## Shoal Categories

1-New Shoal Found

2-Charted Shoal Disproved / Not Found

Sequence No	Shoal No	Category	CHARTED			SURVEYED			Type of Feature	Kelp Area	Least Depth Found	Charting Recommendation	Remarks
			Charted Depth (meters)	NAD 83 Latitude N (degrees)	NAD 83 Longitude W (degrees)	Surveyed Depth (meters)	NAD 83 Latitude N (DMS)	NAD 83 Longitude W (DMS)					
31	D42	1				-0.81	55° 24' 22.1134"	133° 15' 17.0888"	Drying Rk	Y Y		Insert	
32 D	43	2	Drying Rk	55° 24' 23.65"	133° 15' 39.25"				Slope	Y	Y	Remove	Not detected by lidar, not observed in georeferenced imagery.
33	D45	2	Islet	55° 24' 4.53"	133° 18' 3.09"				Slope	N	Y	Remove	Not detected by lidar, not observed in georeferenced imagery.
34	D46	2	Islet	55° 24' 3.72"	133° 18' 17.29"				Coast	Y	Y	Remove	Note: Charted islet surveyed as coastline
35	D47	1				3.75	55° 24' 4.3603"	133° 18' 32.6502"	Rk	Y	Y	Insert	
36	D50	1				-2.63	55° 24' 30.8646"	133° 19' 26.184"	Drying Rk	Y Y		Insert	
37	D52	1				-0.55	55° 24' 36.5152"	133° 19' 30.9263"	Rk Awash	Y Y		Insert	
38	D53	2	18.2	55° 24' 35.75"	133° 19' 38.06"	7.31	55° 24' 37.2699"	133° 19' 35.8391"	Rk	Y	Y	Replace	
39	D54	2	35.0	55° 24' 33.97"	133° 21' 5.86"	16.14	55° 24' 36.8543"	133° 21' 5.0533"	Rk	N	N	JV	Sparse lidar coverage in deep water.
40	D57	1				-1.82	55° 24' 43.1658"	133° 19' 35.4767"	Drying Rk	Y Y		Insert	
41	D60	1				4.76	55° 25' 0.1675"	133° 19' 35.396"	Rk	Y	Y	Insert	
42	D62	1				-2.39	55° 25' 21.8662"	133° 19' 18.9962"	Drying Rk	Y Y		Insert	
43	D63	1				-1.59	55° 25' 50.488"	133° 18' 49.595"	Drying Rk	Y Y		Insert	
44 D	65	2	Drying Rk	55° 26' 21.18"	133° 18' 15.23"	-3.60	55° 26' 20.526"	133° 18' 15.6298"	Islet	N	Y	Replace	
45 D	66	2	Drying Rk	55° 26' 21.01"	133° 18' 8.62"				Drying Shelf	Y Y		Remove	Note: Charted drying rock surveyed as drying shelf.

Shoal Categories

1-New Shoal Found

2-Charted Shoal Disproved / Not Found

Sequence No	Shoal No	Category	CHARTED			SURVEYED			Type of Feature	Kelp Area	Least Depth Found	Charting Recommendation	Remarks
			Charted Depth (meters)	NAD 83 Latitude N (degrees)	NAD 83 Longitude W (degrees)	Surveyed Depth (meters)	NAD 83 Latitude N (DMS)	NAD 83 Longitude W (DMS)					
46	D67	1				-2.37	55° 26' 24.3881"	133° 18' 7.2965"	Drying Rk	Y Y		Insert	
47	D68	2	Drying Rk	55° 26' 25.27"	133° 18' 5.17"	-3.60	55° 26' 25.0523"	133° 18' 4.8946"	Islet	Y	Y	Replace	
48	D69	2	Drying Rk	55° 26' 30.7"	133° 18' 4.28"				Slope	Y	Y	Remove	Not detected by lidar, not observed in georeferenced imagery.
49	D70	2	Islet	55° 26' 37.75"	133° 17' 56.78"				Coast	Y	Y	Remove	Note: Charted islet surveyed as coastline.
50	D71	2	Islet	55° 26' 40.27"	133° 17' 57.88"	-2.99	55° 26' 40.2738"	133° 17' 57.8774"	Drying Rk	Y Y		Replace	
51	D72	2	27.2	55° 26' 44.16"	133° 18' 8.5"	14.53	55° 26' 43.6693"	133° 18' 6.6744"	Rk	N	Y	Replace	
52	D74	2	21.9	55° 26' 34.41"	133° 18' 12.23"	12.16	55° 26' 36.258"	133° 18' 6.8173"	Rk	N	Y	Replace	
53	D75	1				5.02	55° 25' 31.7226"	133° 14' 0.8844"	Rk	Y	N	BV	Possible Rk in kelp.
54	D76	1				4.33	55° 27' 4.6768"	133° 22' 3.7535"	Rk	N	Y	Insert	
55	D77	2	20.1	55° 26' 50.1"	133° 22' 2.96"	10.82	55° 26' 51.4316"	133° 22' 1.542"	Rk	N	Y	Replace	See Danger to Navigation report. Item 8.
56	D78	1				8.20	55° 26' 39.9595"	133° 21' 51.3122"	Rk	Y	Y	Insert	
57	D79	1				12.54	55° 26' 43.7834"	133° 21' 43.1647"	Rk	N	Y	Insert	
58	D80	1				23.88	55° 27' 12.2455"	133° 15' 57.4981"	Shoal	N	Y	Insert	
59	D81	1				20.58	55° 27' 17.9372"	133° 14' 53.7112"	Shoal	N	Y	Insert	
60	D82	1				10.22	55° 26' 58.3991"	133° 13' 15.155"	Rk	N	Y	Insert	
61	D83	1				13.68	55° 26' 55.4464"	133° 14' 4.2374"	Rk	Y	N	BV	Possible small object on seabed. Refer to FED2.
62	D84	2	16.4	55° 26' 59.26"	133° 15' 54.44"	7.61	55° 26' 57.9779"	133° 15' 53.8963"	Rk	Y	Y	Replace	
63	D85	1				11.87	55° 26' 50.888"	133° 18' 16.6385"	Rk	N	Y	Insert	
64	D86	1				15.93	55° 26' 37.8834"	133° 18' 16.7216"	Rk	N	Y	Insert	

## Shoal Categories

1-New Shoal Found

2-Charted Shoal Disproved / Not Found

Sequence No	Shoal No	Category	CHARTED			SURVEYED			Type of Feature	Kelp Area	Least Depth Found	Charting Recommendation	Remarks	
			Charted Depth (meters)	NAD 83 Latitude N (degrees)	NAD 83 Longitude W (degrees)	Surveyed Depth (meters)	NAD 83 Latitude N (DMS)	NAD 83 Longitude W (DMS)						
65	D87	1				20.10	55° 26' 34.5772"	133° 18' 22.8668"	Rk	N	Y	Insert	All items covered by 4x4m laser spot spacing at 200% lidar coverage.	
66	D88	1				1.35	55° 25' 55.029"	133° 18' 47.3148"	Rk	Y	Y	Insert		
67	D89	1				19.48	55° 25' 37.6981"	133° 13' 54.8285"	Shoal	N	N	JV		Sparse lidar coverage in deep water. Refer to FERKD1.
68	D90	1				1.87	55° 25' 23.749"	133° 19' 22.4159"	Rk	Y	N	VV		Possible Rk in kelp.
69	D91	1				10.80	55° 25' 27.0318"	133° 14' 10.1483"	Rk	N	Y	Insert		
70	D92	1				20.09	55° 25' 25.0774"	133° 14' 4.6774"	Rk	N	N	JV		Sparse lidar coverage in deep water.
71	D93	1				3.62	55° 24' 20.4664"	133° 15' 14.8133"	Rk	Y	Y	Insert		See Danger to Navigation report. Item 9.
72	D94	1				3.83	55° 24' 22.7092"	133° 15' 7.7702"	Rk	Y	Y	Insert		
73	D96	1				9.90	55° 26' 35.8685"	133° 21' 54.0446"	Rk	N	Y	Insert		See Danger to Navigation report. Item 5. DTON submitted from field.
74	D97	1				12.60	55° 26' 22.0186"	133° 18' 23.3514"	Rk	N	Y	Insert		See Danger to Navigation report. Item 2. DTON submitted from field.
75	D98	1				11.98	55° 26' 40.8908"	133° 18' 11.4667"	Rk	N	Y	Insert		See Danger to Navigation report. Item 3. DTON submitted from field.
76	D99	1				2.33	55° 27' 2.6435"	133° 22' 1.7436"	Rk	Y	Y	Insert		See Danger to Navigation report. Item 4. DTON submitted from field.
77	D100	1				0.06	55° 25' 30.5159"	133° 14' 5.9856"	Rk Awash	Y Y		Insert		See Danger to Navigation report. Item 1. DTON submitted from field.
78	D101	2	21.9	55° 26' 52.22"	133° 17' 56.17"	11.86	55° 26' 51.3985"	133° 17' 54.6277"	Rk	N	Y	Replace		
79	D102	2	18.2	55° 26' 39.78"	133° 18' 15.86"	13.60	55° 26' 39.633"	133° 18' 13.9543"	Rk	N	Y	Replace		

**Table 3: Chart Comparison Spreadsheet**

Shoal Categories  
 1-New Shoal Found  
 2-Charted Shoal Disproved / Not Found



## D.2 ADDITIONAL RESULTS

### D.2.1 Supplemental Information for Boatwork

For the H11662 survey, the supplemental information for further boatwork was compiled by:

1. Defining the seaward limit of good lidar seabed coverage as a M\_COVR, CATCOV=1 polygon.
2. Reviewing the features for investigation compiled during data processing and adding the uncertain soundings identified during the chart comparison to this examination list.
3. Prioritizing all features for investigation with respect to the M\_COVR polygon and dangers to safe vessel-based examination.
4. Recommending the vessel-based method of disproving ‘suspicious’ lidar features or confirming ‘real’ lidar feature detections and determining least depth.

#### D.2.1.1 Seaward Limit of Lidar Coverage

The survey area H11662 consists of a number of islands, islets and many kelp covered submerged rocks close to the coast. Heavy kelp is present throughout the survey area, especially around the sheltered islands and islets. As a result of periods of poor water clarity experienced during lidar data acquisition and the presence of heavy kelp, several areas across the sheet have poor seabed coverage. This is reflected by gaps in the BASE surface rendered as part of the survey deliverables.

In particular, the areas of poor lidar seabed coverage include:

- Along most of the SE coast of San Fernando Island, due to kelp.
- SW of Point Amargura, at position 55° 26' 54" N, 133° 21' 57" W, due to kelp.
- S of Point Amargura, at position 55° 26' 38" N, 133° 21' 43" W, due to kelp.
- On the NW coast of San Juan Island, due to poor water clarity, at positions:
  - 55° 25' 38" N, 133° 19' 10" W.
  - 55° 26' 01" N, 133° 18' 42" W.
  - 55° 26' 29" N, 133° 18' 08" W.
  - 55° 26' 44" N, 133° 17' 37" W.
  - 55° 26' 46" N, 133° 17' 03" W.
- Along most of the coast of San Juan Bautista Island, due to kelp.
- On the NE coast of San Juan Bautista Island, at position 55° 26' 51" N, 133° 14' 14" W, due to poor water clarity.
- Along most of the S and SE coasts of San Juan Bautista Island, due to poor water clarity.

Traditionally, the suggested lidar-ship junctioning polyline was drawn too far to seaward, across areas of sparse, ‘noisy’ lidar coverage. For this survey, the polyline submitted as an S-57 M\_COVR CATCOV=1 polygon is the seaward extent of good lidar coverage. When there

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is poor lidar coverage due to poor water clarity, the presence of kelp, or expansive white water, the polyline has been drawn just to seaward of the MLLW line. It should be noted that TLI is not providing a recommended junctioning line. The determination of where multibeam survey lines need to be conducted is at the discretion of the PHB and the ships conducting the junctioning.

When planning multibeam junctioning with lidar seabed coverage, the NALL and the following must be taken into consideration:

- Lidar / georeferenced imagery derived MHW line, MLLW line.
- Drying, awash and shallow features detected by lidar.
- Features for examination.
- ‘Unsurveyed’ polygons due to kelp, poor water clarity and the SEZ.

These are all provided in the S-57 feature file (US511662.000) or the H11662\_Inv.hob file for H11662.

The areas of good lidar seabed coverage include:

- S and SW of Point Amargura Island, in the NW of the sheet.
- Along most of the N coast of San Juan Bautista Island.
- In the vicinity of Balandra Island.
- Around San Juanito Island.
- Along the SW coast of San Juan Bautista Island.

The seaward limit of good lidar data coverage has been described by the S-57 feature object M\_COVR in the S-57 feature file (US511662.000).

#### *D.2.1.2 Lidar Features Requiring Further Investigation*

A list of uncertain lidar soundings was collated during data processing and is presented in an S-57 feature file. For example, some detections on isolated rocks in thick kelp beds were difficult to correctly classify as either rock or kelp.

Tagging in the GS was used to flag features for which the least depth has not been found. Typically this meant that there were less than 4 supporting soundings, within 0.5 – 1.0m of the depth, on the primary and overlapping lines. These tags were then exported from the GS and compiled in CARIS BASE Editor. Features for examination have been captured within the H11662\_Inv.hob as M\_NPUB feature objects. Where these features correlate with an item listed in the Chart Comparison Spreadsheet, a reference has been made in the H11662\_Inv.hob file. The S-57 attribution methodology for lidar features requiring further investigation is presented below:

S-57 Object Class	S-57 Object Acronym	Geometry	Description	Attribute 1	Attribute 2	Attribute 3	Attribute 4
Nautical publication information	M_NPUB P		Used to relate additional nautical information or publications to the data.	INFORM (used for storing a unique Feature for Investigation ID)	NINFOM (used for storing the recommended examination method)	PUBREF (used for storing a reference to a Chart Comparison)	PICREP (used for storing a link to waveform screen captures)

Refer to Section B.4.4 for the descriptions of the GS tagging philosophy used for all lidar seabed coverage gaps and recommended features for investigation.

In circumstances where least depth has not been found over a significant feature, a recommendation for investigation by boat for 16 uncertain soundings has been made in the CARIS H11662\_Inv.hob file. All features in the chart comparison that have not had least depth adequately surveyed also appear in this file.

#### D.2.1.3 Prioritization of Features Requiring Further Investigation

All features for investigation have been assigned a priority, based on location with respect to the lidar coverage polyline, the coastal foul areas, and the NALL. In addition, they have been attributed with a recommended examination method, as specified in the following section. The priorities are assigned using the following table:

Priority	Location w.r.t. Polyline	Coastal Foul Area / NALL	Examination Method	Remarks
1 Seaward		No	Typically BV or VV / BV for shallow features	MUST be examined prior to multibeam junctioning.
2 Inshore		No NALL Possibly within Foul	Typically BV or VV / BV for shallow features	Investigation at ships discretion. Typically for uncertain shallow features.
3	Inshore / Seaward	NALL Coastal kelp	VV / BV	Investigation at ships discretion. Typically for drying rocks or rocks awash.
4 Seaward		No	JV	Can be safely navigated over during multibeam. Post acquisition comparison required.
5	Inshore / Seaward	Generally No	Typically BV or VV / BV for shallow features	Doubtful sounding. Possibly floating kelp / whale or fish strikes.

Note: All features recommended for investigation are reported as possible hazards when conducting survey work by boat.

**Table 4: Prioritization Hierarchy for Features Requiring Further Investigation**

#### *D.2.1.4 Recommended Examination Method of Features Requiring Further Investigation*

Each feature for investigation has been attributed with a recommended examination method, based on the general depth around the feature, the least depth as detected by lidar and the nature of the feature (kelp, white water etc.). The examination methods are categorized as follows:

<b>Acronym</b>	<b>Examination Method</b>
VV	Visual Verification - may be hazardous to approach even with shallow draft vessel running single beam.
VV / BV	Visual Verification required prior to Bathymetric Verification - potentially shoaler than 3m depth.
BV	Bathymetric Verification, generally greater than 3m depth.
JV Junctioning	Verification, generally greater than 6m depth.

**Table 5: Recommended Examination Methods for Features Requiring Further Investigation**

#### *D.2.1.5 Recommended Junctioning with Unsurveyed Lidar Areas*

The ‘unsurveyed’ gaps in lidar seabed coverage are defined as polygons in the S-57 feature file. They were constructed utilizing the export of the operator assigned gap tags covered in Section B.4.4. In the case of ‘unsurveyed’ areas for kelp, and SEZ, junctioning is not recommended for the obvious risks to surface vessels.

#### *D.2.1.6 Comparison with prior Surveys*

Comparison with prior surveys was not required under this Task Order. See Section D.1 for comparison to the nautical charts.

*D.2.2 Summary of Charting Actions and Investigations – H11662**D.2.2.1 Summary of Charting Actions – H11662*

Total number of new significant islets recommended for insertion on chart: 0

Total number of new significant drying rocks recommended for insertion on chart: 11

Total number of new significant rocks awash recommended for insertion on chart: 4

Total number of new significant rocks recommended for insertion on chart: 19

Total number of charted features disproved by lidar (Remove): 10

Total number of charted features recommended for amendment by lidar (Replace): 23

Total number of chart comparison items requiring further investigation: 10

Total number of DTONs submitted to PHB during data acquisition: 5

Total number of DTONs submitted to PHB during data processing: 4

**Total number of DTONs submitted to PHB for H11662: 9**

*D.2.2.2 Summary of Lidar Features Requiring Further Investigation – H11662*

Total number of Priority 1 investigations identified: 0

Total number of Priority 2 investigations identified: 7

Total number of Priority 3 investigations identified: 5

Total number of Priority 4 investigations identified: 4

Total number of Priority 5 investigations identified: 0

Total number of investigations recommended during data processing: 8

Total number of investigations recommended from georeferenced imagery review: 2

Total number of investigations recommended from chart comparison compilation: 6

**Total number of recommended feature investigations: 16**

**E. APPROVAL SHEET****LETTER OF APPROVAL – OPR-O190-KRL-07**

This report and the accompanying LADS survey deliverables are respectfully submitted.

Field operations contributing to the accomplishment of this survey were conducted under my direct supervision with frequent personal checks of progress and adequacy. This report and the accompanying LADS survey deliverables have been closely reviewed and are considered complete and adequate as per the Statement of Work.

Report \_\_\_\_\_

Submission Date

Descriptive Report – H11662

December 20, 2007



Mark Sinclair  
Hydrographer  
Tenix LADS, Incorporated

Date December 20, 2007

**Revisions and Corrections During Office Processing and Certification**

<sup>1</sup> The LIDAR survey referenced in this Descriptive Report has been applied to the multibeam surveys it junctions with. No stand-alone LIDAR information was compiled to the HCell. For information concerning the compilation of LIDAR features and soundings see the Descriptive Reports for multibeam surveys H12026 and H12030. LIDAR does not meet IHO object detection requirements. LIDAR was not used to supersede shoaler charted soundings or to disprove charted features.

The Data Acquisition and Processing Report and Horizontal and Vertical Control Report have been filed with the project records.



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## APPENDIX I – DANGERS TO NAVIGATION

### DTONS Submitted to PHB

#### I.1.1 Danger to Navigation Report

Hydrographic Survey Registry Number: H11662

State: Alaska

Locality: West of Prince of Wales Island

Sub-locality: San Juan Bautista Island

Project Number: OPR-O190-KRL-07

Survey Dates: April – June 2007

Depths are in meters and reduced to Mean Lower Low Water using final verified tides. Drying heights are in meters relative to MLLW. Positions are based on the NAD83 horizontal datum. All times and dates are relative to UTC.

Number	Edition	Date	Scale
US5AK4BM 1	<sup>st</sup> 10	/18/07	1:40,000
US5AK4CM 2	<sup>nd</sup> 07	/23/07	1:40,000

The following items were found during hydrographic survey operations:

No.	Feature	Depth	Latitude (N)	Longitude (W)	Time, Date, Year	Investigate
1 R	k Awash	0.0	55° 25' 30.53"	133° 14' 05.81"	02:10:38, May 28	No
2 Rk		12.6	55° 26' 22.05"	133° 18' 23.48"	22:29:50, May 10	No
3 Rk		12.0	55° 26' 40.91"	133° 18' 11.51"	22:29:42, May 10	No
4 R	k	2.3	55° 27' 02.68"	133° 22' 01.93"	21:53:48, May 7	No
5 R	k	9.9	55° 26' 35.80"	133° 21' 53.86"	01:56:57, June 14	No
6	Rk Awash	0.3	55° 26' 55.2"	133° 21' 59.98"	21:53:45, May 7	Yes

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<b>No.</b>	<b>Feature</b>	<b>Depth</b>	<b>Latitude (N)</b>	<b>Longitude (W)</b>	<b>Time, Date, Year</b>	<b>Investigate</b>
7	Rk	6.3	55° 26' 44.64"	133° 21' 48.52"	22:26:52, May 12	No
8	Rk	10.8	55° 26' 51.43"	133° 22' 1.54"	22:05:56, May 7	No
9	Rk	3.6	55° 24' 20.47"	133° 15' 14.81"	23:31:40, May 9	No

**COMMENTS:** Final verified tides have been applied from the Craig tide gauge (9450551). The shoals were found using LIDAR. DTON items 1 through 5 were submitted during data acquisition from the field while DTON items 6 through 9 were submitted following data processing from the Biloxi office.

Questions concerning this report should be directed to the Survey Manager, Mr. Scott Ramsay, in the Tenix LADS Inc. office in Biloxi, MS. at (228) 594 6800.

**DTONS Submitted to MCD****I.1.2 Danger to Navigation Report**

<b>Hydrographic Survey Registry Number:</b>	H11662
<b>State:</b>	Alaska
<b>Locality:</b>	West of Prince of Wales Island
<b>Sub-locality:</b>	San Juan Bautista Island
<b>Project Number:</b>	OPR-O190-KRL-07
<b>Survey Start Date:</b>	April 22, 2007

Depths are in fathoms and feet reduced to Mean Lower Low Water using verified tides. Positions are based on the NAD83 horizontal datum. All times and dates are relative to UTC.

**Charts Affected**

<b>Number</b>	<b>Version</b>	<b>Date</b>	<b>Scale</b>
17400 17	th Ed	March, 2007	1:229,376
17405	14th Ed	October, 2000	1:40,000
17406 7	th Ed	February, 2004	1:40,000

The following items were found during hydrographic survey operations:

<b>No.</b>	<b>Feature</b>	<b>Depth</b>	<b>Latitude (N)</b>	<b>Longitude (W)</b>	<b>Time and Date</b>
1	Awa sh	0	55° 25' 30.53"	133° 14' 05.81"	02:10:38, May 28
2	R k	6 <sub>5</sub> 55	° 26' 22.05"	133° 18' 23.48"	22:29:50, May 10
3	R k	6 <sub>3</sub> 55	° 26' 40.91"	133° 18' 11.51"	22:29:42, May 10
4	R k	1 <sub>2</sub> 55	° 27' 02.68"	133° 22' 01.93"	21:53:48, May 7

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(This is a second addendum to the report submitted on June 22, 2007)

No.	Feature	Depth	Latitude (N)	Longitude (W)	Time and Date
1	Awash	0 <sub>1</sub>	55° 26' 55.2"	133° 21' 59.98"	21:53:45, May 7
2	Rk	3 <sub>2</sub>	55° 26' 44.64"	133° 21' 48.52"	22:26:52, May 12
3	Rk	5 <sub>5</sub>	55° 26' 51.43"	133° 22' 1.54"	22:05:56, May 7
4	Rk	2	55° 24' 20.47"	133° 15' 14.81"	23:31:40, May 9

**Comments:** The report was compiled by Tenix LADS Inc. and reviewed by PHB. Questions concerning this report should be directed to the Chief, Pacific Hydrographic Branch at (206) 526-6835.

**APPENDIX II – SURVEY FEATURE REPORT**

No AWOIS were assigned to this task order.

**APPENDIX III – FINAL PROGRESS SKETCH****FINAL PROGRESS SKETCH**

April 21 – June 23, 2007

**OPR-O190-KRL-07**

West of Prince of Wales Island, AK

Tenix LADS, Inc.

Scott Ramsay, Project Manager

The Tenix LADS aircraft arrived in Ketchikan on April 20, 2007. The site mobilization was undertaken on April 21, 2007, and Ketchikan remained the main base of operations through April and May. The first survey flight was conducted in the West of Prince of Wales Island, AK project area on April 22, 2007. A total of 20 sorties were flown in the project area, with the final flight occurring on June 23, 2007. A total of 4 transit flights to Kodiak were conducted in support of operations for OPR-P135-KRL-07 Southeast of Kodiak Island, AK.

Of the 20 survey flights, 13.5 were deemed fully effective. The remaining flights were sorties aborted prematurely for adverse environmental conditions such as low cloud, high turbulence or marginal water clarity in the survey area, or due to system problems.

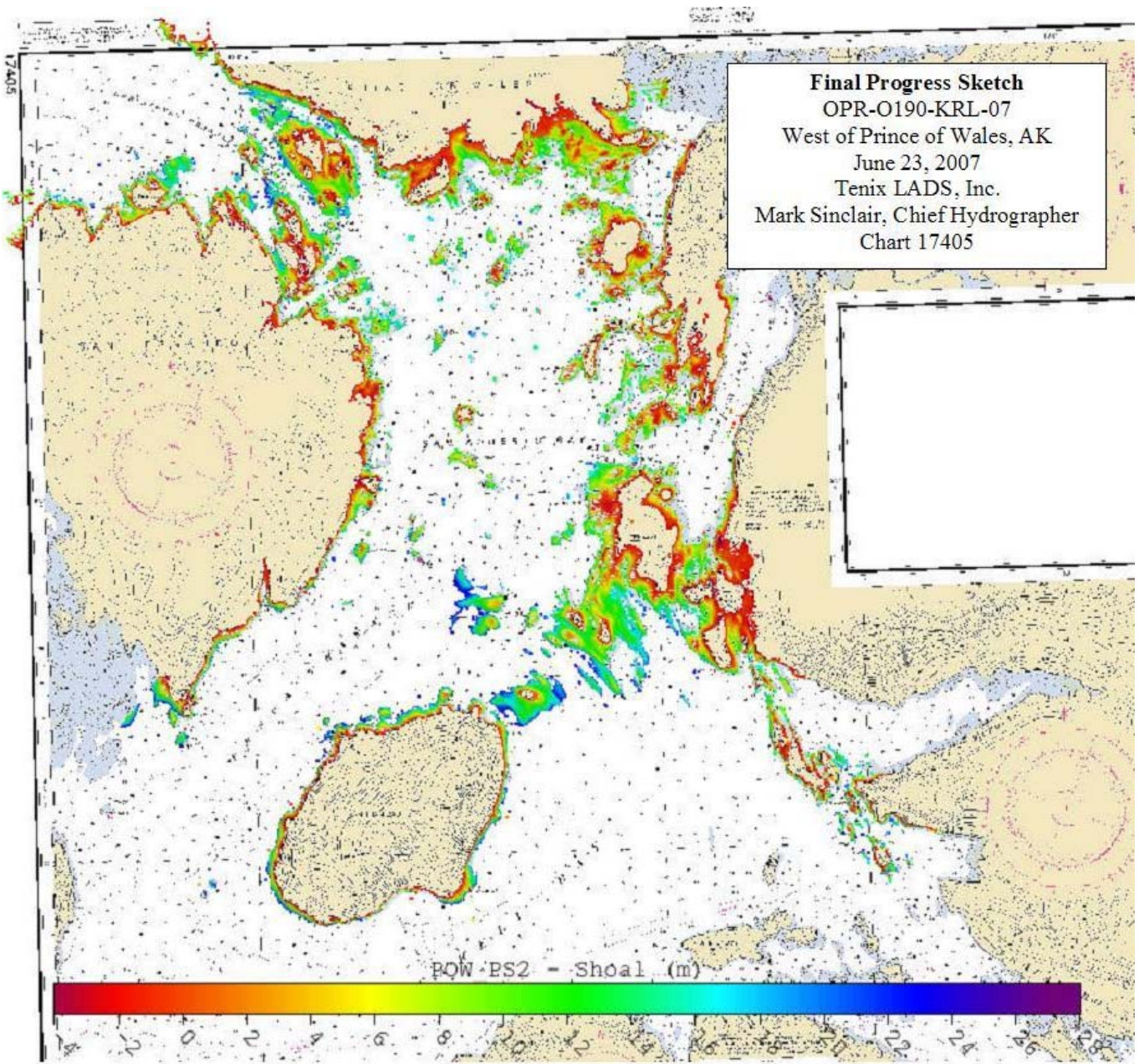
The area covered is 13SNM, from the 0m contour to lidar extinction depth (generally 15m), at 200% coverage.

<b>OPR-O190-KRL-07 (Ketchikan Base in April and May)</b>	<b>April</b>	<b>May</b>	<b>June</b>	<b>Total 2007</b>	<b>Total Planned</b>	<b>% Complete</b>
<b>Days on project</b>	6	22 7 3		5	26	135%
<b>Days mobilization</b>	1 0		0 1		1	100%
<b>Survey flights</b>	2	15 3 2		0	10	200%
<b>Transit flights (to Kodiak)</b>	1 1		2 4		4	100%
<b>No flight - weather</b>	2	8 1		11		
<b>No flight - water quality</b>	0 1		1 2			
<b>Linear nautical miles flown</b>	555	2247 6	78 3	480	2433	143%
<b>Area surveyed (nm<sup>2</sup>)</b>	1 *	9 *	3 *	13 *	17 **	76%

<b>OPR-O190-KRL-07 (Ketchikan Base in April and May)</b>	<b>April</b>	<b>May</b>	<b>June</b>	<b>Total 2007</b>	<b>Total Planned</b>	<b>% Complete</b>
<b>Aircraft flown hours</b>	12:35 6	7:03 17:	57 9	7:15 7	0:00	139%
<b>Aircraft on task hours</b>	10:00 5	0:13 14:	50 7	5:03 5	6:30	133%
<b>Hours lost to weather</b>	0:00 1	:46	0:00	1:46		
<b>Hours lost to system</b>	1:00 3	:20	1:30	5:50		
<b>Effective flights conducted</b>				13.5 1	0	135%
<b>Average time on task per effective flight</b>				4:26 5	:39	79%
<b>Survey lines flown</b>				530 375		141%

\*Area surveyed value derived from CARIS BASE surface at June 23, from 0m to lidar extinction depth

\*\* Total planned area sourced from OPR-O190-KRL-07 Statement of Work, Attachment #2



**Progress Sketch OPR-O190-KRL-07 at June 23, 2007**



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## APPENDIX IV – TIDES AND WATER LEVELS

### Abstract of Times of Hydrography

Start and End times refer to tidal applications requirement.

Time on Task indicates actual time of task in the survey area. All times and dates are in UTC.

### 07\_4POW

Date	JD	Sortie	Start Time	End Time	Tide Duration	Time on Task
22-Apr-07 1	12	1	16:05	21:45	5:40	5:10
24-Apr-07 1	14	2	20:35	01:25	4:50	4:50
5-May-07 1	25	3	16:10	16:45	0:35	0:35
7-May-07 1	27	4	17:20	22:15	4:55	4:55
8-May-07 1	28	5	23:43	04:03	4:20	4:20
9-May-07 1	29	6	22:33	03:38	5:05	5:05
10-May-07 1	30	7	19:14	23:17	4:03	4:03
12-May-07 1	32	9	21:27	01:35	4:08	4:08
14-May-07 1	34	10	17:13	18:50	1:37	1:37
15-May-07 1	35	11	18:46	21:00	2:14	2:15
17-May-07 1	37	12	15:18	20:21	5:03	5:03
18-May-07 1	38	13	15:40	19:16	3:36	3:36
23-May-07 1	43	14	20:12	20:58	0:46	0:46
27-May-07 1	47	15	23:13	03:54	4:41	4:41
28-May-07 1	48	17	18:13	20:35	2:22	2:22
28-May-07 1	48	18	22:35	04:12	5:37	5:37
31-May-07 1	51	19	21:20	22:30	1:10	1:10
13-Jun-07 16	4	22	22:10	03:25	5:15	5:15
15-Jun-07 16	6	23	19:25	02:10	6:45	5:45
23-Jun-07 17	4	29	00:30	04:20	3:50	3:50

**TIDAL DATUMS**

Tidal datums at SITKA, BARONOF ISLAND, SITKA SOUND based on:

LENGTH OF SERIES: 19 Years  
 TIME PERIOD: January 1983 – December 2001  
 TIDAL EPOCH: 1983 – 2001  
 CONTROL TIDE STATION:

Elevations of tidal datums referred to Mean Lower Low Water (MLLW), in METERS:

HIGHEST OBSERVED WATER LEVEL (11/02/1948) = 4.534  
 MEAN HIGHER HIGH WATER (MHHW) = 3.029  
 MEAN HIGH WATER (MHW) = 2.791  
 MEAN TIDE LEVEL (MTL) = 1.618  
 MEAN SEA LEVEL (MSL) = 1.610  
 MEAN LOW WATER (MLW) = 0.445  
 MEAN LOWER LOW WATER (MLLW) = 0.000  
 LOWEST OBSERVED WATER LEVEL (01/01/1991) = -1.224

**TIDAL DATUMS**

Tidal datums for Craig Subordinate Gauge based on:

LENGTH OF SERIES: 78 Days  
 TIME PERIOD: April 17 – July 3, 2007  
 CONTROL TIDE STATION: Sitka, AK 9451600

Elevations of tidal datums referred to Mean Lower Low Water (MLLW), in METERS:

MEAN HIGHER HIGH WATER (MHHW) = 3.099  
 MEAN HIGH WATER (MHW) = 2.842  
 MEAN TIDE LEVEL (MTL) = 1.630  
 MEAN LOW WATER (MLW) = 0.419  
 MEAN LOWER LOW WATER (MLLW) = 0.000

## APPENDIX V – SUPPLEMENTAL SURVEY RECORDS AND CORRESPONDENCE

### Correspondence Regarding Final Tide Zoning

#### RAMSAY Scott

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**From:** David.Scharff [David.Scharff@noaa.gov]  
**Sent:** Monday, December 03, 2007 8:04 AM  
**To:** RAMSAY Scott  
**Subject:** Tide station: 9450551  
**Attachments:** David\_Scharff.vcf



David\_Scharff.vcf  
(430 B)

Scott,

The tide model based on use of 9450551 has been reviewed and approved by CO-OPS. The data from this station may be applied to OPR-0190-KRL-07 even though the Statement of Work indicates 9450543.

Regards,  
Dave

**RAMSAY Scott**

**From:** RAMSAY Scott  
**Sent:** Wednesday, August 08, 2007 11:27 AM  
**To:** Dave Scharff (E-mail)  
**Cc:** HAWKINS Michael; NEWSHAM Harry; GUILFORD James  
**Subject:** JOA Craig zoning

**Attachments:** 9450551 Craig Revised Zoning.txt



9450551 Craig  
Revised Zoning.L...

Dave,

Please find attached the JOA provided zoning for the Craig gauge. I am assuming the dimensions of the tide zone areas do not change even though a new gauge at Craig has been introduced into the tidal model, but there are new range and time correctors for the zones based on the Craig smoothed tide readings.

JOA has indicated the Craig gauge reference number is 9450551 in the attached file, but in the SOW it is listed as 9450543.

Could you please confirm with COOPS that the JOA tide zoning for the Craig gauge is applicable for final tide application and inform us of the correct gauge reference number for Craig.

Regards,  
Scott

-----Original Message-----

**From:** HAWKINS Michael  
**Sent:** Wednesday, August 08, 2007 9:00 AM  
**To:** NEWSHAM Harry; RAMSAY Scott  
**Cc:** GUILFORD James  
**Subject:** FW: Craig zoning

Harry,

Here are the new time and range correctors from Eric at JOA, I leave them in you trusted hands.

Mick.

-----Original Message-----

**From:** Erik Oppegard [mailto:eroppegard@acsalaska.net]  
**Sent:** Tuesday, 7 August 2007 10:25 PM  
**To:** HAWKINS Michael  
**Cc:** John Oswald  
**Subject:** Re: Craig zoning

Here you go, the revised zoning based on Craig, AK. I did not change the zone shapes, so your coordinate file will remain the same. Just need to update zone references to the attached file.

Erik

HAWKINS Michael wrote:

> That's pretty much what we did. They didn't give us exact coordinates. So we would draw

9450551 Craig Revised Zoning

JOA revised zoning.

This file was created based on a 1 month TBYT from Sitka to Craig.

The mean time difference = -9min, (-6min used for zoning)

The range ratio = 1.03

NOAA zone shapes remain the same, reference station changed to Craig 9450551

EO 8/7/07

Zone	Time corrector (mins)	Range Ratio	Reference Station
SA227	0	1.03	9450551
SA228	0	1.02	9450551
SA229	6	1.00	9450551
SA230	0	1.00	9450551

APPROVAL SHEET  
H11662

The survey evaluation and verification has been conducted according to branch processing procedures and the HCell compiled per the latest OCS HCell Specifications.

The survey and associated records have been inspected with regard to survey coverage, delineation of the depth curves, development of critical depths, S-57 classification and attribution of soundings and features, cartographic characterization, and verification or disapproval of charted data within the survey limits. The survey records and digital data comply with OCS requirements except where noted in the Descriptive Report and are adequate to supersede prior surveys and nautical charts in the common area.

I have reviewed the HCell, accompanying data, and reports. This survey and accompanying digital data meet or exceed OCS requirements and standards for products in support of nautical charting except where noted in the Descriptive Report.