

## C. VERTICAL AND HORIZONTAL CONTROL

Refer to the M-L906-KR-08 Horizontal and Vertical Control Report<sup>11</sup> for a detailed description of the horizontal and vertical control used on this survey. No deviations from the report occurred. A summary of the project's horizontal and vertical control follows.

### Horizontal Control

The horizontal control datum for this survey was the North American Datum of 1983 (NAD83).

For real-time DGPS corrections, a CSI MBX-3 unit was tuned to the Cape Mendocino, CA. USCG DGPS site. The unit output differentially corrected positions at 1 Hz to the (POS MV) 320 V4 where it was integrated with inertial data; and a position for the top-center of the IMU was generated. This position was logged concurrently with the bathymetry from WinFrog and the POS file by WinFrog PosMvLogger. It was later corrected for offsets to the multibeam echosounder (MBES) by CARIS HIPS in processing.

Final positioning, however, was done using post-processed kinematic (PPK) methods. Applanix POSpac software was used in conjunction with the POS files and local base station data to generate a higher accuracy position which was applied in processing, replacing the real-time position records.

See the M-L906-KR-08 Horizontal and Vertical Control Report for a more detailed description of PPK positioning methods used.

### Vertical Control

All sounding data were initially reduced to mean lower low water (MLLW) using preliminary tidal data. It should be noted that preliminary tides were used in the field for the initial stage of processing only.

**Table 2 – Tide Gauge**

Gauge	Location	Latitude	Longitude
9418767	North Spit, CA	40° 46.0' N	124° 13.0' W
9416841	Arena Cove, CA	38° 54.8' N	123° 42.4' W
9415020	Point Reyes, CA	37° 59.7' N	122° 58.6' W



Final tidal corrections were generated using PPK processing methods in conjunction with NOAA's VDATUM model and the CARIS GPSTide routine. Applanix POSPac software produced a smoothed best estimate of trajectory (SBET) file that, along with other data, contained GPS altitudes based on the NAD83 ellipsoid (GRS 80). The SBET altitudes were loaded into every line in CARIS HIPS, and HIPS' GPSTide routine was run to compute a GPS-based tide. The GPSTide routine used a VDatum NAD83 to MLLW offset grid to produce MLLW tide correctors. This grid is an XYZ text file and is included with the CARIS data under the tide directory.

See M-L906-KR-08 Horizontal and Vertical Control Report for a more detailed description of the GPSTide methods.