C3. Horizontal Control

The horizontal datum for this project is NAD83. Differential GPS (DGPS) corrections were received from the U.S. Coast Guard (USCG) beacon at Driver, Virginia (301 kHz) or from the secondary beacon at Annapolis, MD (289 kHz). Some DGPS outages from the primary beacon occurred during survey operations. The system was set up to automatically switch to the secondary beacon when the primary signal was lost. All of the primary navigation data were collected in DGPS mode. Additionally, during acquisition GPS base stations were constructed and logged data simultaneously with acquisition to provide post-processed IAKAR navigation solutions.

Navigation and attitude data were post-processed using Applanix POSPac MMS software, which produced an IAKAR navigation solution relative to NAD83. The real-time navigation and attitude logged during acquisition was overwritten with post-processed data during HIPS processing. Post-processed navigation, attitude and GPS heights were applied to all HIPS data though only the navigation and attitude were used in the creation of the survey deliverables. As discussed in the DAPR, post-processed GPS heights were used to compute a GPS tide using an ellipsoid to MLLW separation file created using VDatum. Though present for each survey line GPS Tides were not applied to the survey data during the merge process (the Apply GPS Tides box was not checked during merge in Caris HIPS) and are for reference only. Further discussion on the computation of GPS tides and the creation of the separation model can be found in the pending *OPR-E349-KR-09 Ellipsoid Referenced Survey Deliverables**.

Submitted with original field records.