

H12753

U.S. Department of Commerce  
National Oceanic and Atmospheric Administration  
National Ocean Survey

**DESCRIPTIVE REPORT**

Type of Survey: Navigable Area

Registry Number: H12753

**LOCALITY**

State(s): Alaska

General Locality: Bering Strait

Sub-locality: 30 NM North of Cape Prince of Wales

**2015**

CHIEF OF PARTY  
Andrew Orthmann

LIBRARY & ARCHIVES

Date:

**HYDROGRAPHIC TITLE SHEET**

**H12753**

**INSTRUCTIONS:** The Hydrographic Sheet should be accompanied by this form, filled in as completely as possible, when the sheet is forwarded to the Office.

State(s): **Alaska**

General Locality: **Bering Strait**

Sub-Locality: **30 NM North of Cape Prince of Wales**

Scale: **40000**

Dates of Survey: **07/04/2015 to 07/26/2015**

Instructions Dated: **05/05/2015**

Project Number: **OPR-S313-KR-15**

Field Unit: **Terrasond Limited**

Chief of Party: **Andrew Orthmann**

Soundings by: **Multibeam Echosounder Singlebeam Echosounder**

Imagery by:

Verification by: **Pacific Hydrographic Branch**

Soundings Acquired in: **meters at Mean Lower Low Water**

**Remarks:**

*The purpose of this survey is to provide contemporary surveys to update National Ocean Service (NOS) nautical charts. All separates are filed with the hydrographic data. Notes in red were generated during office processing. The processing branch concurs with all information and recommendations in the DR unless otherwise noted. Page numbering may be interrupted or non-sequential. All pertinent records for this survey, including the Descriptive Report, are archived at the National Centers for Environmental Information (NCEI) and can be retrieved via <http://www.ncei.noaa.gov/>.*

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## **Descriptive Report to Accompany Survey H12753**

Project: OPR-S313-KR-15

Locality: Bering Strait

Sublocality: 30 NM North of Cape Prince of Wales

Scale: 1:40000

July 2015 - July 2015

**Terrasond Limited**

Chief of Party: Andrew Orthmann

### **A. Area Surveyed**

A navigable area survey (H12753) was conducted in the area 30 NM North of Cape Prince of Wales, Alaska, in accordance with the NOAA, National Ocean Service, Statement of Work (SOW), OPR-S313-KR-15, dated March 13th, 2015, and Hydrographic Survey Project Instructions dated May 5th, 2015. Hydrographic survey data collection began July 4th, 2015 and ended July 26th, 2015.

The area is in a remote region just south of the Arctic circle. Sea ice covers the area for the majority of the year, with a limited ice-free season with open navigable water from approximately late June through October. Vessel traffic in the region primarily consists of barges serving communities along Alaska's north coast with fuel and supplies, freighters moving lead and zinc from Red Dog Mine to the north, and research vessels involved in Arctic studies. Traffic is relatively sparse but has been increasing in recent years along with economic and scientific interest in the Arctic.

The survey area is centered on Prince of Wales Shoal. This shoal is a relatively narrow ridge of sediment, covered 3 1/2 to 5 fathoms, which extends NNE from Cape Prince of Wales approximately 35 NM. The shoal is built and maintained by sediment transport caused by tidal current flow between the Arctic Ocean and the Pacific Ocean by way of the Bering Strait. The shoal is unmarked because of the ice conditions and remoteness of the locality.

Weather during the ice-free season is frequently inclement. The area is fully exposed in most directions and offers no anchorages or other protected areas. Rapidly changing wind and current conditions offshore of the shoal frequently cause confused and choppy seas which can be dangerous for small craft.

Multibeam echosounder (MBES) and single beam echosounder (SBES) operations were conducted in the area in accordance with the project instructions, which specified set line spacing SBES or MBES with backscatter. Requirements called for 200 m set line spacing SBES (or MBES) within the project extents, with no inshore limit.

## A.1 Survey Limits

Data were acquired within the following survey limits:

<b>Northwest Limit</b>	<b>Southeast Limit</b>
66° 9' 47.35" N 168° 2' 2.84" W	65° 59' 23.1" N 167° 40' 27" W

*Table 1: Survey Limits*

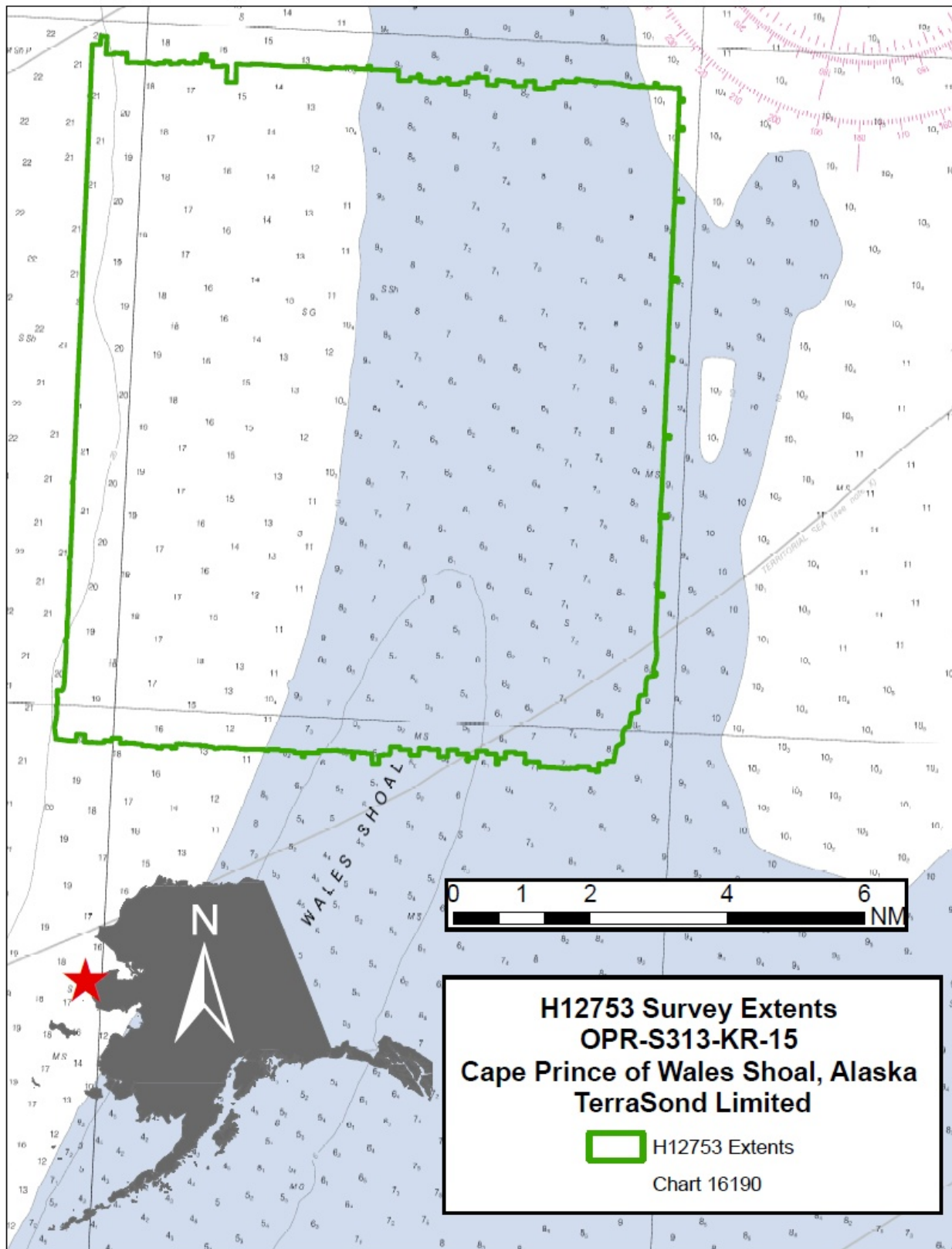


Figure 1: Survey extents and overview.

Survey limits were achieved.

## **A.2 Survey Purpose**

The purpose of the survey, as well as three adjacent surveys completed co-incidentally during project OPR-S313-KR-15, was to update NOS nautical charts in the general vicinity of the Bering Strait, addressing approximately 297 SQ NM of Priority 3 area identified in the NOAA Hydrographic Survey Priorities, 2012 edition.

The survey also addresses United States Coast Guard (USCG) requests for defining the extent of Cape Prince of Wales Shoal due to increased vessel traffic in the region. Prior to this survey, the degree to which the shoal may have shifted from the charted position was unknown, especially given that the best scale chart at the time of this survey (Chart 16190) is out of date, with source soundings acquired from 1940 to 1969.

## **A.3 Survey Quality**

The entire survey is adequate to supersede previous data.



### A.4 Survey Coverage

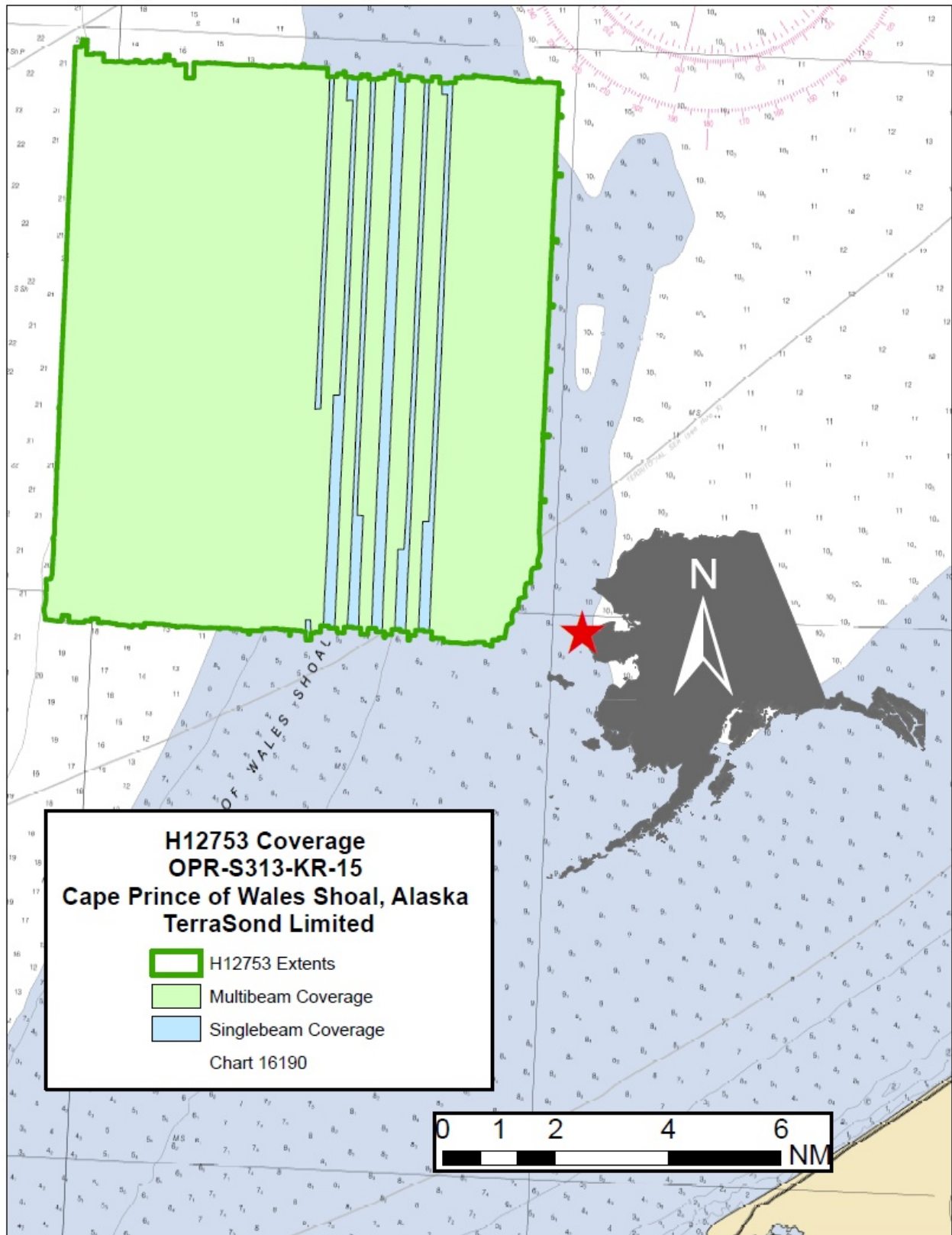


Figure 2: Survey overview showing coverage.

The 200 m spacing requirement for set line spacing within the survey extents was met.

Line splits on charted soundings were not conducted because the nature of the bottom in the area reduced the likelihood of pinnacles or shoals between lines.

*Line splits are required in for set line spacing surveys in accordance with section 5.2.2.3 of the HSSD. There was no correspondence indicating that this requirement was waived.*

## **A.5 Survey Statistics**

The following table lists the mainscheme and crossline acquisition mileage for this survey:

	<b>HULL ID</b>	<i>Qualifier 105</i>	<i>ASV- CT3</i>	<i>Total</i>
<b>LNM</b>	<b>SBES Mainscheme</b>	0	146	146
	<b>MBES Mainscheme</b>	742	0	742
	<b>Lidar Mainscheme</b>	0	0	0
	<b>SSS Mainscheme</b>	0	0	0
	<b>SBES/SSS Mainscheme</b>	0	0	0
	<b>MBES/SSS Mainscheme</b>	0	0	0
	<b>SBES/MBES Crosslines</b>	71	0	71
	<b>Lidar Crosslines</b>	0	0	0
<b>Number of Bottom Samples</b>				9
<b>Number of AWOIS Items Investigated</b>				0
<b>Number Maritime Boundary Points Investigated</b>				0
<b>Number of DPs</b>				0
<b>Number of Items Investigated by Dive Ops</b>				0
<b>Total SNM</b>				85

*Table 2: Hydrographic Survey Statistics*

The following table lists the specific dates of data acquisition for this survey:

<b>Survey Dates</b>	<b>Day of the Year</b>
07/04/2015	185
07/05/2015	186
07/06/2015	187
07/07/2015	188
07/08/2015	189
07/11/2015	192
07/12/2015	193
07/14/2015	195
07/15/2015	196
07/16/2015	197
07/17/2015	198
07/22/2015	203
07/25/2015	206
07/26/2015	207

*Table 3: Dates of Hydrography*

## **B. Data Acquisition and Processing**

### **B.1 Equipment and Vessels**

Refer to the Data Acquisition and Processing Report (DAPR) for a complete description of data acquisition and processing systems, survey vessels, quality control procedures, and data processing methods. Additional information to supplement sounding and survey data and any deviations from the DAPR are discussed in the following sections.

### B.1.1 Vessels

The following vessels were used for data acquisition during this survey:

<b>Hull ID</b>	<i><b>Qualifier 105</b></i>	<i><b>ASV-CT3</b></i>
<b>LOA</b>	32 meters	3.5 meters
<b>Draft</b>	1.8 meters	0.3 meters

*Table 4: Vessels Used*

The Qualifier 105 (Q105) is a 32 m aluminum hull vessel owned and operated by Support Vessels of Alaska. The Q105 acquired all multibeam data and provided housing and facilities for on-site data processing. The vessel also collected bottom samples, deployed BMPG tide gauges, and deployed/recovered the ASV-CT3 vessel as necessary.

The ASV-CT3 is a 3.5 m aluminum hull Autonomous Surface Vessel (ASV) owned and operated by ASV Global. The ASV was operated in an unmanned but monitored mode, collecting SBES data in close vicinity to the Q105 when weather conditions allowed. The ASV collected a minority of the mileage on this project because weather conditions were usually not conducive to its operations, deployment, or recovery. Note that a general-interest report regarding the ASV titled "ASV\_Operations\_Summary\_Report\_TerraSond\_2015" was submitted to NOAA separately; it is included in the Appendix II subdirectory.

## B.1.2 Equipment

The following major systems were used for data acquisition during this survey:

<b>Manufacturer</b>	<b>Model</b>	<b>Type</b>
Teledyne Odom	Echotrac CV100	SBES
Teledyne Reson	Seabat 7101	MBES
Applanix	POSMV 320 V5	Positioning and Attitude
AML Oceanographic	MinosX with Xchange Sensors	Sound Speed Profiler
Hemisphere	Vector V113 GPS Compass	Positioning and Attitude
Valeport	Rapid SVT 200Bar	Sound Speed Profiler
Teledyne Oceanscience	RapidCAST	Sound Speed Profiler Deployment System
Trimble	5700	Base Station
Trimble	5700	Positioning
Sea-Bird Electronics	SBE 26+	Submerged Tide Gauge
AML Oceanographic	MinosX with Xchange Sensors	Conductivity and Temperature Gauges

*Table 5: Major Systems Used*

Equipment configurations and operations as well as data acquisition and processing are described in the DAPR.

## B.2 Quality Control

### B.2.1 Crosslines

Crosslines acquired for this survey totaled 8% of mainscheme acquisition.

Crosslines were acquired to meet or exceed the 8% of mainscheme requirements required in the HSSD.

Effort was made to ensure crosslines were geographically distributed across the survey area. Crosslines were run perpendicular to mainscheme lines whenever possible to ensure higher quality nadir beams crossed lower quality outer beams. Multibeam lines intersected SBES lines as an additional cross-system/vessel check.

The crossline analysis was conducted using CARIS HIPS “QC Report” routine. Each crossline was selected and run through the process, which calculated the depth difference between each accepted crossline sounding and a QC BASE (CUBE-type) surface’s depth layer created from the mainscheme data. QC BASE surfaces

were created with the same CUBE parameters and resolutions as the final BASE surfaces, with the important distinction that the QC BASE surfaces did not include crosslines so as to not bias the QC report results. Differences in depth were grouped by beam number and statistics computed, which included the percentage of soundings with differences from the BASE surface falling within IHO Order 1. When at least 95% of the sounding differences exceed IHO Order 1, the crossline was considered to “pass,” but when less than 95% of the soundings compare within IHO Order 1, the crossline was considered to “fail.”

Agreement between the BASE surfaces and crossline soundings is excellent. All crossline comparisons pass with 95% (or more) of soundings comparing to within IHO Order 1.

Note that this sheet included a section of SBES mainscheme, which was intersected by MBES crosslines. The SBES surface versus MBES crossline sounding agreement is also excellent, passing with 95% (or more) of soundings comparing to within IHO Order 1.

Refer to Separate II: Digital Data for the detailed Crossline QC Reports.

### B.2.2 Uncertainty

The following survey specific parameters were used for this survey:

Measured	Zoning
0 meters	0 meters

*Table 6: Survey Specific Tide TPU Values*

Hull ID	Measured - CTD	Measured - MVP	Surface
Qualifier 105	0 meters/second	2.111 meters/second	0.025 meters/second
ASV-CT3	0 meters/second	2.111 meters/second	0 meters/second

*Table 7: Survey Specific Sound Speed TPU Values*

All soundings were assigned a horizontal and vertical value for estimated total propagated uncertainty (TPU). Tidal error (measured and zoning) was computed using the "real-time" values in the tide zone definition file (ZDF). The parameters and methods used for computation of sounding uncertainty are detailed in the project DAPR. The ASV-CT3 uses identical uncertainty values for measured sound speed as the Q105 because the Q105 performed all sound speed casts on the project.

The BASE surfaces were finalized in CARIS HIPS so that the final uncertainty value for each grid cell is the greater of either standard deviation or uncertainty. The uncertainty layer of the final surface was then examined for areas of uncertainty that exceeded IHO Order 1.

Uncertainty for the SBES surface ranged from 0.28 m to 0.40 m. Uncertainty for the MBES surface ranged from 0.13 m to 0.59 m. Few exceeded IHO Order 1.

Highest uncertainties were found in areas of varying bottom topography such as slopes and sand waves where high standard deviations are caused by the wide depth ranges of soundings contributing to each grid cell, outer edges of multibeam swathes without adjacent line overlap, and areas exhibiting sound speed or motion artifact error. Despite elevated TPU values for these grid cells, the data is within specifications.

*Table 6 incorrectly implies TPU values for Tide Measured and Tide Zoning were 0-meters. For this survey, the field unit used a realtime method to apply tide TPU values. All of the tidal uncertainties have been dealt with appropriately and the data is adequate to supersede charted data in the common area.*

### **B.2.3 Junctions**

This survey junctions with two contemporary surveys: H12754 and H12752. Both were conducted concurrent with this survey.

Junctions were compared by creating difference surfaces in CARIS HIPS. 4-m resolution CUBE BASE surfaces were generated for each survey, and then differenced. Results were extracted and analyzed.



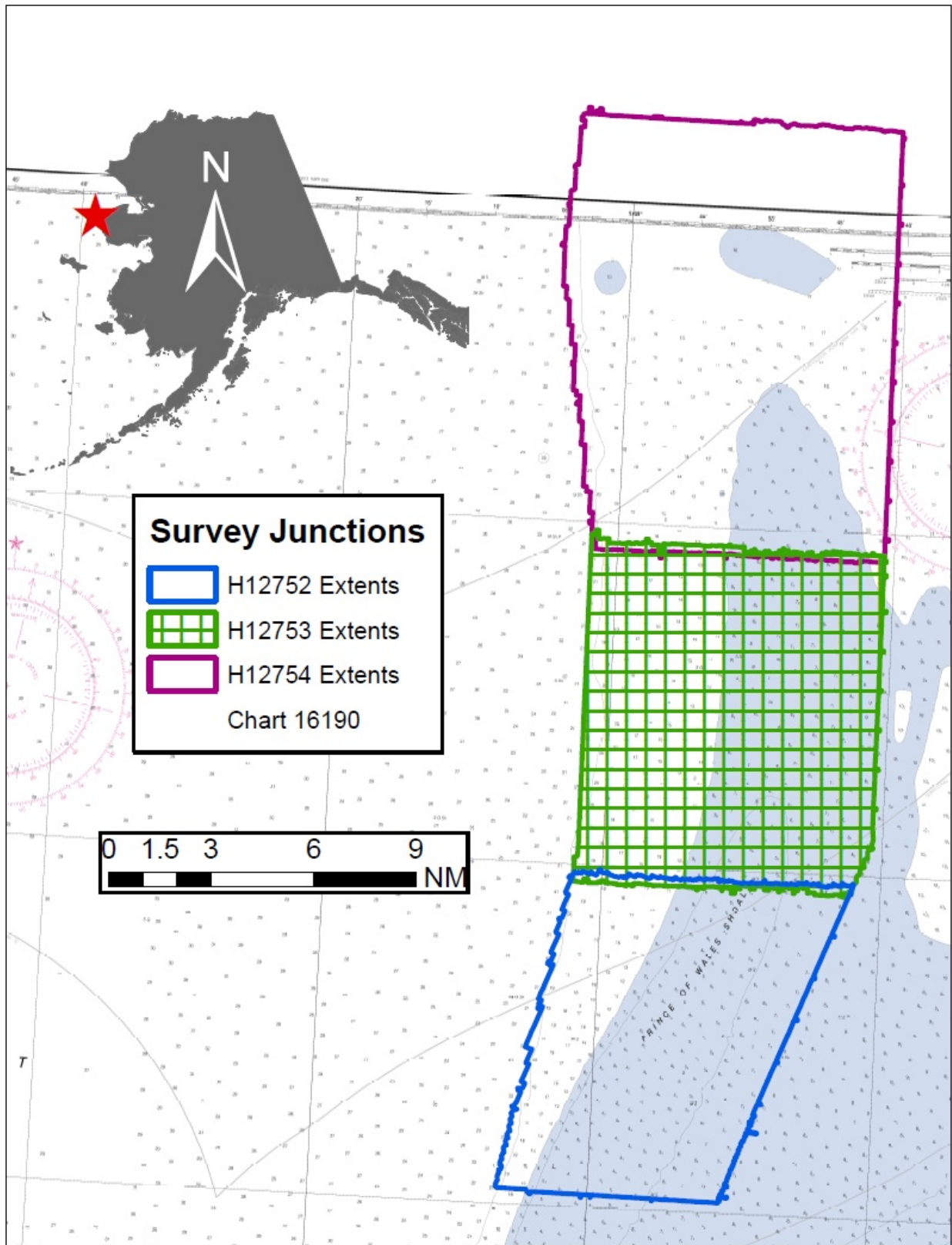


Figure 3: Survey junctions with this sheet.

The following junctions were made with this survey:

Registry Number	Scale	Year	Field Unit	Relative Location
H12752	1:40000	2015	TerraSond	S
H12754	1:40000	2015	TerraSond	N

*Table 8: Junctioning Surveys*

### H12752

Agreement is excellent, averaging 0.003 m, with a standard deviation of 0.069 m, and differences falling in a range of -0.388 to 0.363 m.

### H12754

Agreement is excellent, comparing to within 0.048 m on average, with a standard deviation of 0.072 m, and differences falling in a range of -0.487 to 0.342 m.

## **B.2.4 Sonar QC Checks**

Echosounder confidence checks consisting of bar checks, lead lines, and acoustic comparisons between vessels were undertaken on this project.

Two bar checks were completed for the MBES on the Q105, while one bar check was completed for the SBES system on the ASV-CT3. Bar checks served as a check on both real-time as well as processed depth accuracy, and were also used to determine and refine the sonar acoustic center offsets. Results were excellent, with processed sonar depths comparing on average to 0.033 m (or better) of the actual bar depth for MBES, and to 0.015 m for SBES.

Lead line comparisons were also undertaken. Over the course of the project, two were completed for the MBES on the Q105 and one was completed for the SBES on the ASV-CT3. Processed sonar results versus depth measured by lead line were 0.051 m or better for the MBES, and 0.046 m for the SBES. Results were deemed acceptable given the variables associated with lead line checks.

During acquisition, care was taken to ensure significant overlap between the two survey vessels for comparison purposes. Q105 MBES lines commonly intersect ASV-CT3 SBES data, and in several instances the Q105 surveyed completely over ASV-CT3 lines, creating ample comparable data. To compare the echosounder data, CARIS BASE surfaces at 4 m resolution were created for each vessel, and differenced from each other. The difference surfaces were exported to text and analyzed. Project wide, the MBES data

agrees with the SBES data to 0.012 m on average, with a standard deviation of 0.051 m, with the MBES data slightly shoaler. The maximum difference was 0.426 m, and minimum difference was -0.238 m.

Refer to the bar check and lead line logs available in Separate I: Acquisition and Processing Logs for specific results. Refer to the project DAPR for more information regarding QC checks methodology.

## **B.2.5 Equipment Effectiveness**

### 7101 Beam Pattern

A distinct beam pattern was obvious in the data set in certain areas, with a fuzziness or “horn” like features on both sides of nadir on multibeam swaths, coinciding with the bottom detection shift from phase to amplitude detection. The pattern is common with Reson 8101/7101 multibeam echosounders in certain bottom types. Power and range settings were adjusted in acquisition to minimize the issue, with little effect. However, the “horns,” which can be as great as 0.20 m in height, appear to be largely ignored by the CUBE algorithm during surface creation, with minimal to no effect on the final surfaces.

### ASV-CT3 Pitch and Roll

Pitch and roll records were logged aboard the the ASV-CT3 using a Hemisphere Vector V113, but were not applied to the SBES data. Although pitch and roll corrections are not required by the HSSD for SBES data, application to the SBES data was attempted on a test set of SBES data in order to minimize effects of motion (especially pitch) on the SBES soundings, but resulted in no noticeable benefit. Therefore, roll and pitch were not applied to the SBES data by way of setting the sensors to "Apply=NO" in the CARIS HVF.

## **B.2.6 Factors Affecting Soundings**

### Sound Speed Error

A general downward or upward across-track cupping in multibeam data, indicative of sound speed error, is present periodically in the data set. The sound speed error adversely affected outer beams by up to 0.20 m in places. To minimize the error, sound speed profiles were collected in sets every two hours during multibeam operations, and filters were used in processing to remove the outermost beams. The effect of sound speed error on final surfaces is relatively minor, normally not exceeding 0.10 m, and is within specifications.

*The outer beams of the MBES lines were rejected in swath editor to account for the SS errors. In some cases, good data was rejected.*

### Motion Artifact

Motion artifact is occasionally visible in the final multibeam surfaces. This is the result of uncompensated effects of motion, particularly due to roll. Poor sea states (normally seas 1.5 m or greater) were common on this project and were the primary contributor. A survey-grade, high-end Applanix POSMV 320 V5

was used for motion compensation but residual error within the manufacturer specifications for the system remains nonetheless. The problem was addressed in processing by identifying lines with the greatest error and iteratively applying more aggressive outer beam filters, in some instances rejecting beams greater than 50 degrees either side of nadir. No adjustments to line spacing were made in acquisition to compensate for the rejected outer beam data because as a set-spaced survey, complete coverage was not required. Following the additional filtering the effect on the final surface is 0.20 m or less, which is within specifications.

### ASV-CT3 Pitch and Roll

As described previously, corrections for pitch and roll were not applied to ASV-CT3 data. This sometimes results in downward "spikes" in the SBES data where the sounder erroneously digitized the depth as deeper than actual due to angle of the transducer relative to the seafloor while the vessel was pitching. To a lesser extent roll similarly affects the data. The relatively large (4 m) grid cell size used for the final BASE surfaces smooths and mitigates the effect of the error. Despite the apparent error the gridded SBES data passes crossline analysis, and compares to overlapping MBES data to 0.012 m on average with a low standard deviation of 0.051 m, and is within specifications.

### Tide Error

Periodic vertical offsets or "busts", indicative of tide error, is present sporadically in the data set. The majority of lines show excellent matchup with crosslines, but busts of up to 0.15 m are occasionally present and attributable to tide error. The observed amount of tide error was deemed acceptable given that it was not possible for the project tide station and zoning gauges to capture all water level changes across the survey area, especially in this wide open region where winds frequently have more effect on water levels than the daily lunar and solar cycles. Despite the error, data is within specifications.

## **B.2.7 Sound Speed Methods**

Sound Speed Cast Frequency: 2 hours

Sound speed profiles were acquired aboard the Q105 while underway with an Oceanscience RapidCAST system, which utilized a Valeport sound speed profiler. Normally two or three profile "casts" were taken along a survey line, with casts near the beginning, end, and middle of the line (depending on line length), in order to capture spatial variance across the area. The set was then repeated on an interval of approximately two hours in order to capture temporal variance. The sound speed sensor was lowered as close as possible to the seafloor, and then retracted to the vessel and downloaded.

The ASV-CT3 vessel was not equipped to collect sound speed profiles. Instead, the profile data collected aboard the Q105 was used to correct all ASV-CT3 SBES data. This was possible because the ASV-CT3 worked simultaneously and in close proximity (usually within 200 m) of the Q105 at all times.

Up and down portions of the profiles were averaged and a combined profile at a standardized 0.10 m depth increment was output to CARIS SVP format with time and position. Sound speed profiles were applied with the "nearest in distance within time" method in CARIS HIPS, with time set to two hours for multibeam and four hours for single beam.

## **B.2.8 Coverage Equipment and Methods**

Set line spacing requirements called for 200 m spaced lines within the survey extents.

Line plans were defined in CAD software prior to the commencement of survey operations and were executed line by line during acquisition. Two line sets were available, with north-south and east-west orientations, which provided options for line direction depending on prevailing weather conditions.

Refer to the project DAPR for additional methods used to meet coverage requirements.

## **B.3 Echo Sounding Corrections**

### **B.3.1 Corrections to Echo Soundings**

Corrections applied to echo soundings are detailed in the project DAPR. No deviations occurred.

### **B.3.2 Calibrations**

Calibrations were undertaken as described in the DAPR; no deviations occurred.

## **B.4 Backscatter**

Multibeam backscatter was logged during this survey, but not processed. The vessel Q105 multibeam DB and XTF files contain the backscatter records.

## **B.5 Data Processing**

### **B.5.1 Software Updates**

There were no software configuration changes after the DAPR was submitted.

The following Feature Object Catalog was used: V5.3.2

There were no software configuration changes after the DAPR was submitted.

## B.5.2 Surfaces

The following surfaces and/or BAGs were submitted to the Processing Branch:

Surface Name	Surface Type	Resolution	Depth Range	Surface Parameter	Purpose
H12753_MB_4m_MLLW	MBES	4 meters	0 meters - 40 meters	NOAA_4m	Set-spaced MBES
H12753_SB_4m_MLLW	SBES	4 meters	0 meters - 40 meters	NOAA_4m	Set-spaced SBES

*Table 9: Submitted Surfaces*

The final depth information for this survey was submitted as two CARIS BASE surfaces which best represented the seafloor at the time of the 2015 survey. The surfaces were created from fully processed soundings with all final corrections applied.

The MBES surface was created using CUBE parameters that ensured a maximum sounding propagation distance of the grid resolution divided by  $\sqrt{2}$ . The SBES surface was created as a Uncertainty surface. A resolution of 4 m was selected for both surfaces based on the requirements for set-spaced surveys described in the HSSD. Surfaces were finalized, and designated soundings were applied where applicable. Horizontal projection was selected as UTM Zone 3 North, NAD 1983.

Notes:

- \* Any non-final surfaces submitted with the survey deliverables are interim products and are marked with "nonFinal" in their filename(s).
- \* 4 m resolution was used per HSSD requirements for Set Line Spacing. All depths were less than 40 m.

A CARIS HOB file was submitted (H12753\_FFF.HOB) with the survey deliverables as well. The final feature file (FFF) contains meta-data and other data not readily represented by the final surfaces, including bottom samples. Each object is encoded with mandatory S-57 attributes, additional attributes, and NOAA Extended Attributes (V#5.3.2).

Refer to the DAPR for more detailed discussion of the steps followed when acquiring and processing the 2015 survey data.

***The first sentence of the second paragraph is simply describing the NOAA 4m CUBE Parameters. The grid resolution is divided by the square root of 2.***

## C. Vertical and Horizontal Control

Additional information discussing the vertical or horizontal control for this survey can be found in the accompanying HVCR.

### C.1 Vertical Control

The vertical datum for this project is Mean Lower Low Water.

#### Standard Vertical Control Methods Used:

Discrete Zoning

The following subordinate water level stations were established for this survey:

Station Name	Station ID
Outside Lopp Lagoon	9469515

*Table 10: Subordinate Tide Stations*

File Name	Status
9469515.tid	Final Approved

*Table 11: Water Level Files (.tid)*

File Name	Status
S313KR2015CORP_20151008.zdf	Final

*Table 12: Tide Correctors (.zdf or .tc)*

In addition to the subordinate tide station installed to support the project, submerged BMPG (bottom mounted pressure gauges) were also deployed throughout the survey area to capture zoning characteristics. Data from all stations were used to derive the tide zones.

## C.2 Horizontal Control

The horizontal datum for this project is NAD83.

The projection used for this project is UTM Zone 3N.

The following PPK methods were used for horizontal control:

### Single Base

The project base continuously logged GPS data at 1 Hz and was utilized to post-process position data in Applanix POSPac software. All real-time positions for both vessels were replaced in processing with post-processed kinematic (PPK) solutions.

The following user installed stations were used for horizontal control:

HVCR Site ID	Base Station ID
0056	Outside Lopp Lagoon

*Table 13: User Installed Base Stations*

## D. Results and Recommendations

### D.1 Chart Comparison

The chart comparison was performed by examining all Raster Navigational Charts (RNCs) and Electronic Navigational Charts (ENCs) that intersect the survey area.

The chart comparison was accomplished by overlaying the finalized BASE surfaces with shoal-biased soundings, and final feature file on the charts in CARIS HIPS. The general agreement between charted soundings and survey soundings was then examined and a more detailed comparison was undertaken for any shoals or other dangerous features. In areas where a large scale chart overlapped with a small scale chart, only the larger scale chart was examined. Results are shown in the following sections.

It is recommended that this survey supersede charted data where they overlap.

USCG Notice to Mariners (NM) and USCG Local Notice to Mariners were checked for updates affecting the area. None were found that were issued subsequent to issuance date of the project instructions.



### D.1.1 Raster Charts

The following are the largest scale raster charts, which cover the survey area:

<b>Chart</b>	<b>Scale</b>	<b>Edition</b>	<b>Edition Date</b>	<b>LNМ Date</b>	<b>NM Date</b>
16190	1:100000	1	05/2013	10/20/2015	10/17/2015

*Table 14: Largest Scale Raster Charts*

#### 16190

Sounding agreement is excellent. All charted soundings agree to this survey to 1 fathom or better. See figure below.

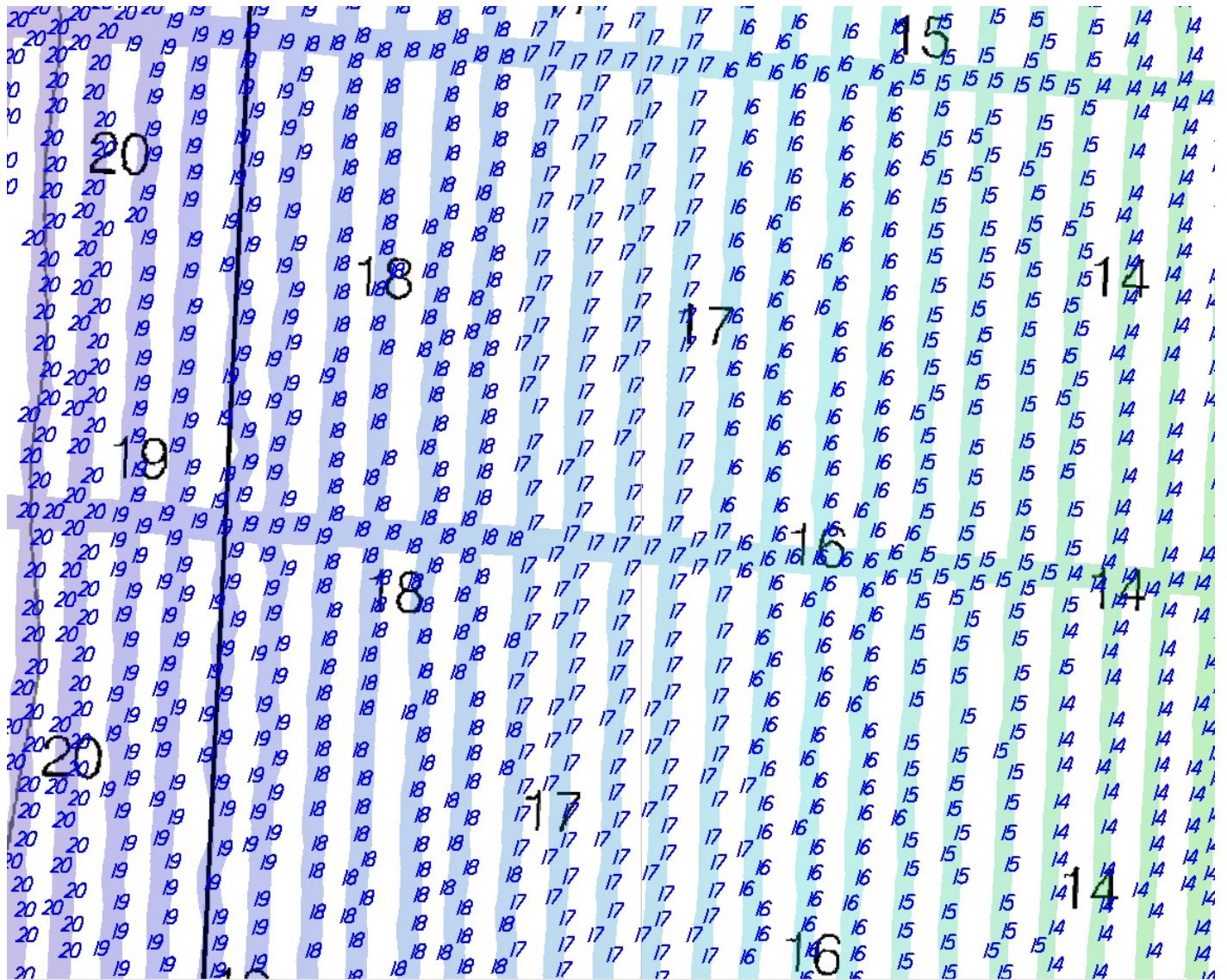


Figure 4: Example of the excellent agreement between this survey and chart 16190. Soundings from this survey (blue) agree with soundings on the chart (black) to 1 fathom or better.

**D.1.2 Electronic Navigational Charts**

The following are the largest scale ENC's, which cover the survey area:

ENC	Scale	Edition	Update Application Date	Issue Date	Preliminary?
US4AK8DM	1:100000	3	04/22/2015	04/22/2015	NO

Table 15: Largest Scale ENC's

## US4AK8DM

The same differences observed for the RNC apply to the ENC.

### **D.1.3 AWOIS Items**

There were no assigned AWOIS items for this survey.

### **D.1.4 Maritime Boundary Points**

No maritime boundary points were assigned for this survey.

### **D.1.5 Charted Features**

There are no charted features labeled PA, ED, PD, or Rep. within the survey extents.

### **D.1.6 Uncharted Features**

No uncharted features were found during this survey.

### **D.1.7 Dangers to Navigation**

No DTONs were found during this survey.

### **D.1.8 Shoal and Hazardous Features**

Prince of Wales Shoal, over which this survey was conducted, could be potentially hazardous to vessels of significant draft. However, soundings from this survey compare well to the charted soundings on chart 16190. Therefore, the chart already adequately depicts potential dangers.

### **D.1.9 Channels**

No channels exist in the survey area.

### **D.1.10 Bottom Samples**

Bottom samples were collected for this survey. Most returned brown silt, with some clay and fine sand.

Samples were not retained. Bottom characteristics are encoded as SBDARE objects in the FFF, with photos of each sample in the accompanying "multimedia" directory, included with the survey deliverables.

## **D.2 Additional Results**

### **D.2.1 Shoreline**

This survey did not intersect shoreline, and shoreline investigation was not assigned.

### **D.2.2 Prior Surveys**

Comparison with prior surveys was not required.

### **D.2.3 Aids to Navigation**

No ATONs were observed in the survey area, and none were assigned for investigation.

### **D.2.4 Overhead Features**

No overhead features existed within the survey area.

### **D.2.5 Submarine Features**

None to note.

### **D.2.6 Ferry Routes and Terminals**

Ferry routes and terminals do not exist within the survey area.

### **D.2.7 Platforms**

Platforms do not exist within the survey area.

### **D.2.8 Significant Features**

All significant features and conditions encountered have been described previously.

**D.2.9 Construction and Dredging**

No construction or dredging was occurring within the survey extents, nor are there any known future plans for construction or dredging in the survey area.

**D.2.10 New Survey Recommendation**

No new surveys are recommended in this area.

**D.2.11 Inset Recommendation**

No new chart insets are recommended in this area.


## E. Approval Sheet

Field operations contributing to the completion of survey H12752 were conducted under my direct supervision with frequent personal checks of progress, integrity, and adequacy.

This report, digital data, and all other accompanying records are approved. All records are respectfully submitted and forwarded for final review.

The survey data was collected in accordance with the Statement of Work and meets or exceeds the requirements set in the 2014 NOS Hydrographic Surveys and Specifications Deliverables (HSSD) document. This data is adequate to supersede charted data in common areas. This survey is complete and no additional work is required with the exception of any deficiencies, if any, noted in the Descriptive Report.

Report Name	Report Date Sent
Coast Pilot Review (CPB9_E33_C09_20151016_1817_Recommendations)	2015-10-20
OPR S313-KR-15 Tide Station Removal Report (9469515 Outside Lopp Lagoon)	2015-09-28

Approver Name	Approver Title	Approval Date	Signature
Andrew Orthmann, C.H.	TerraSond Charting Program Manager	11/20/2015	 <small>Digitally signed by Andrew Orthmann            DN: cn=Andrew Orthmann, o=Terrasond Limited, ou=US            Date: 2015.11.20 13:12:03            #127            Reason: I am approving this document            Location: Palmer, AK</small>

## F. Table of Acronyms

<b>Acronym</b>	<b>Definition</b>
<b>AHB</b>	Atlantic Hydrographic Branch
<b>AST</b>	Assistant Survey Technician
<b>ATON</b>	Aid to Navigation
<b>AWOIS</b>	Automated Wreck and Obstruction Information System
<b>BAG</b>	Bathymetric Attributed Grid
<b>BASE</b>	Bathymetry Associated with Statistical Error
<b>CO</b>	Commanding Officer
<b>CO-OPS</b>	Center for Operational Products and Services
<b>CORS</b>	Continually Operating Reference Station
<b>CTD</b>	Conductivity Temperature Depth
<b>CEF</b>	Chart Evaluation File
<b>CSF</b>	Composite Source File
<b>CST</b>	Chief Survey Technician
<b>CUBE</b>	Combined Uncertainty and Bathymetry Estimator
<b>DAPR</b>	Data Acquisition and Processing Report
<b>DGPS</b>	Differential Global Positioning System
<b>DP</b>	Detached Position
<b>DR</b>	Descriptive Report
<b>DTON</b>	Danger to Navigation
<b>ENC</b>	Electronic Navigational Chart
<b>ERS</b>	Ellipsoidal Referenced Survey
<b>ERZT</b>	Ellipsoidally Referenced Zoned Tides
<b>FFF</b>	Final Feature File
<b>FOO</b>	Field Operations Officer
<b>FPM</b>	Field Procedures Manual
<b>GAMS</b>	GPS Azimuth Measurement Subsystem
<b>GC</b>	Geographic Cell
<b>GPS</b>	Global Positioning System
<b>HIPS</b>	Hydrographic Information Processing System
<b>HSD</b>	Hydrographic Surveys Division
<b>HSSD</b>	Hydrographic Survey Specifications and Deliverables

<b>Acronym</b>	<b>Definition</b>
<b>HSTP</b>	Hydrographic Systems Technology Programs
<b>HSX</b>	Hypack Hysweep File Format
<b>HTD</b>	Hydrographic Surveys Technical Directive
<b>HVCR</b>	Horizontal and Vertical Control Report
<b>HVF</b>	HIPS Vessel File
<b>IHO</b>	International Hydrographic Organization
<b>IMU</b>	Inertial Motion Unit
<b>ITRF</b>	International Terrestrial Reference Frame
<b>LNM</b>	Local Notice to Mariners
<b>LNM</b>	Linear Nautical Miles
<b>MCD</b>	Marine Chart Division
<b>MHW</b>	Mean High Water
<b>MLLW</b>	Mean Lower Low Water
<b>NAD 83</b>	North American Datum of 1983
<b>NAIP</b>	National Agriculture and Imagery Program
<b>NALL</b>	Navigable Area Limit Line
<b>NM</b>	Notice to Mariners
<b>NMEA</b>	National Marine Electronics Association
<b>NOAA</b>	National Oceanic and Atmospheric Administration
<b>NOS</b>	National Ocean Service
<b>NRT</b>	Navigation Response Team
<b>NSD</b>	Navigation Services Division
<b>OCS</b>	Office of Coast Survey
<b>OMAO</b>	Office of Marine and Aviation Operations (NOAA)
<b>OPS</b>	Operations Branch
<b>MBES</b>	Multibeam Echosounder
<b>NWLON</b>	National Water Level Observation Network
<b>PDBS</b>	Phase Differencing Bathymetric Sonar
<b>PHB</b>	Pacific Hydrographic Branch
<b>POS/MV</b>	Position and Orientation System for Marine Vessels
<b>PPK</b>	Post Processed Kinematic
<b>PPP</b>	Precise Point Positioning
<b>PPS</b>	Pulse per second



<b>Acronym</b>	<b>Definition</b>
<b>PRF</b>	Project Reference File
<b>PS</b>	Physical Scientist
<b>PST</b>	Physical Science Technician
<b>RNC</b>	Raster Navigational Chart
<b>RTK</b>	Real Time Kinematic
<b>SBES</b>	Singlebeam Echosounder
<b>SBET</b>	Smooth Best Estimate and Trajectory
<b>SNM</b>	Square Nautical Miles
<b>SSS</b>	Side Scan Sonar
<b>ST</b>	Survey Technician
<b>SVP</b>	Sound Velocity Profiler
<b>TCARI</b>	Tidal Constituent And Residual Interpolation
<b>TPE</b>	Total Propagated Error
<b>TPU</b>	Topside Processing Unit
<b>USACE</b>	United States Army Corps of Engineers
<b>USCG</b>	United States Coast Guard
<b>UTM</b>	Universal Transverse Mercator
<b>XO</b>	Executive Officer
<b>ZDA</b>	Global Positioning System timing message
<b>ZDF</b>	Zone Definition File

APPROVAL PAGE

**H12753**

Data meet or exceed current specifications as certified by the OCS survey acceptance review process. Descriptive Report and survey data except where noted are adequate to supersede prior surveys and nautical charts in the common area.

The following products will be sent to NGDC for archive

- H12753\_DR.pdf
- Collection of depth varied resolution BAGS
- Processed survey data and records
- H12753\_GeoImage.pdf

The survey evaluation and verification has been conducted according current OCS Specifications.

Approved: \_\_\_\_\_

**Peter Holmberg**

**Cartographic Team Lead, Pacific Hydrographic Branch**

The survey has been approved for dissemination and usage of updating NOAA's suite of nautical charts.

Approved: \_\_\_\_\_

**Kurt Brown**

**Physical Scientist, Pacific Hydrographic Branch**