U.S. Department of Commerce National Oceanic and Atmospheric Administration National Ocean Service			
Ι	DESCRIPTIVE REPORT		
Type of Survey:	Navigable Area		
Registry Number:	H13208		
	LOCALITY		
State(s):	California		
General Locality:	Channel Islands, CA		
Sub-locality:	Posa Anchorage to Fraser Point		
	2019		
CHIEF OF PARTY CAPT Marc Moser			
	LIBRARY & ARCHIVES		
Date:			

H13208

NATIO	U.S. DEPARTMENT OF COMMERCE NAL OCEANIC AND ATMOSPHERIC ADMINISTRATION	REGISTRY NUMBER:		
HYDROGRAPHIC TITLE SHEETH13208				
INSTRUCTIONS: The	Hydrographic Sheet should be accompanied by this form, filled in as completely as possib	ble, when the sheet is forwarded to the Office.		
State(s):	California			
General Locality:	Channel Islands, CA			
Sub-Locality:	Posa Anchorage to Fraser Point			
Scale:	20000			
Dates of Survey:	10/12/2019 to 10/14/2019	10/12/2019 to 10/14/2019		
Instructions Dated:	08/27/2019			
Project Number:	OPR-L397-FA-19			
Field Unit:	NOAA Ship Fairweather			
Chief of Party:	CAPT Marc Moser			
Soundings by:	Multibeam Echo Sounder			
Imagery by:	Multibeam Echo Sounder Backscatter			
Verification by:	Pacific Hydrographic Branch			
Soundings Acquired in:	meters at Mean Lower Low Water			

Remarks:

The purpose of this survey is to provide contemporary surveys to update National Ocean Service (NOS) nautical charts. All separates are filed with the hydrographic data. Any revisions to the Descriptive Report (DR) generated during office processing are shown in bold red italic text. The processing branch maintains the DR as a field unit product, therefore, all information and recommendations within the body of the DR are considered preliminary unless otherwise noted. The final disposition of surveyed features is represented in the OCS nautical chart update products. All pertinent records for this survey, including the DR, are archived at the National Centers for Environmental Information (NCEI) and can be retrieved via http:// www.ncei.noaa.gov/.

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Descriptive Report to Accompany Survey H13208

Project: OPR-L397-FA-19 Locality: Channel Islands, CA Sublocality: Posa Anchorage to Fraser Point Scale: 1:20000 October 2019 - October 2019 **NOAA Ship Fairweather** Chief of Party: CAPT Marc Moser

A. Area Surveyed

The survey area is located between Posa Anchorage and Fraser Point, CA

A.1 Survey Limits

Data were acquired within the following survey limits:

Northwest Limit	Southeast Limit		
34° 3' 33" N	33° 58' 49.72" N		
119° 58' 26.65" W	119° 52' 29.48" W		

Table 1: Survey Limits

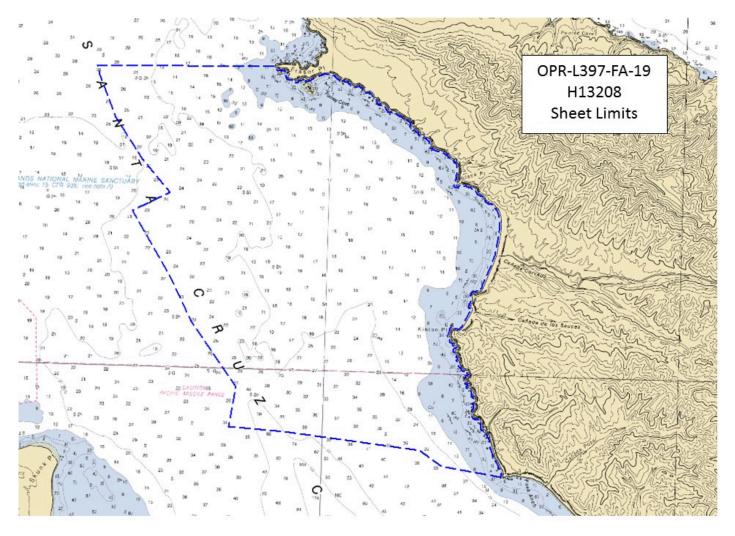


Figure 1: H13208 sheet limits (in blue) overlaid onto Chart 18728

Data were acquired to the survey limits in accordance with the requirements in the Project Instructions and the March 2019 NOS Hydrographic Surveys Specifications and Deliverables (HSSD) as shown in Figure 1. In all areas where the 3.5 meter depth contour or the sheet limits were not met, the Navigable Area Limit Line (NALL) was defined as the inshore limit of bathymetry due to kelp, the risks of maneuvering around anchored vessels, or in close proximity to the steep and rocky shoreline. An example of such an area is shown in Figure 2.

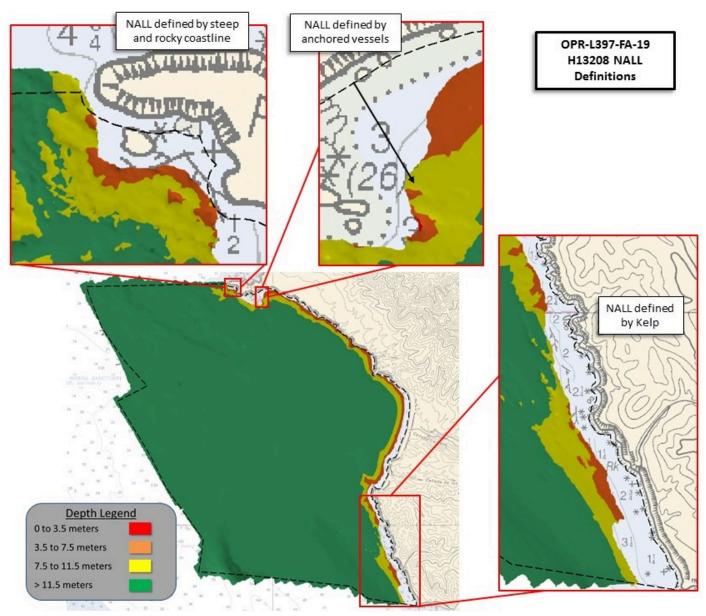


Figure 2: Areas where the NALL was defined by the presence of kelp or the risks of maneuvering around anchored vessels and the steep and rocky shoreline.

A.2 Survey Purpose

This year the Channel Islands National Marine Sanctuary work will focus on the remaining survey area around Santa Cruz Island, the largest of the Channel Islands (about 97 sq. mi.), located about 30 miles offshore of the California mainland city of Santa Barbara. The waters surrounding CINMS are highly productive and are home to recreational and commercial fishing efforts, and regularly host kayakers, surfers, sightseers, whale watchers, researchers, and Channel Islands National Park concessionaires, who all access the sanctuary via boats. Correspondingly, the abundance of sea life and aquatic habitats drives a thriving industry of recreational and commercial fishing state brings varied vessel traffic through the waters of

CINMS. The commercial fishing vessel traffic alone is responsible for the highest commercial landings value (approximately \$450 million; 2005-2015) across all of California's ports. Additionally, major mainland port traffic transiting to and from Los Angeles and Long Beach, California routes large cargo and tanker vessels close to CINMS boundaries. Much of the existing nautical chart data dates back to 1930s lead line or single beam echo sounder surveys, and the areas not surveyed to modern standards are predominantly located in the shallow waters (<40m) where vessel traffic is highest. This poses a serious risk to life, property, and the delicate ecosystem with 64 groundings since 2000. Increasing traffic is increasing the risk, with seven of those groundings in 2015 alone. Modern survey efforts, such as a 2015 survey by NOAA Ship Bell M. Shimada, have found previously undetected pinnacles within the sanctuary. This survey will continue modern mapping efforts to identify any similar threats that may exist in these waters. The CINMS hydrographic survey will be as unique as the region itself. In addition to providing data for crucial nautical chart updates, this survey will also generate backscatter data, which will be used in habitat mapping and substrate analysis. Both multibeam echo sounder and backscatter data will not only serve to enhance marine navigational safety, but will also be used by sanctuary managers, planners, and researchers, aiding them in the conservation of this most precious resource. Survey data from this project is intended to supersede all prior survey data in the common area.

A.3 Survey Quality

The entire survey is adequate to supersede previous data.

Data acquired in H13208 meet multibeam echo sounder (MBES) coverage requirements for complete coverage, as required by the HSSD. This includes crosslines (see Section B.2.1), NOAA allowable uncertainty (see Section B.2.09), and density requirements (see Section B.2.10).

A.4 Survey Coverage

The following table lists the coverage requirements for this survey as assigned in the project instructions:

Water Depth	Coverage Required	
All waters in survey area	Complete Coverage	

Table 2: Survey Coverage

The entirety of H13208 was acquired with Complete Coverage, meeting the requirements listed above and in the HSSD. See Figure 3 for an overview of coverage.

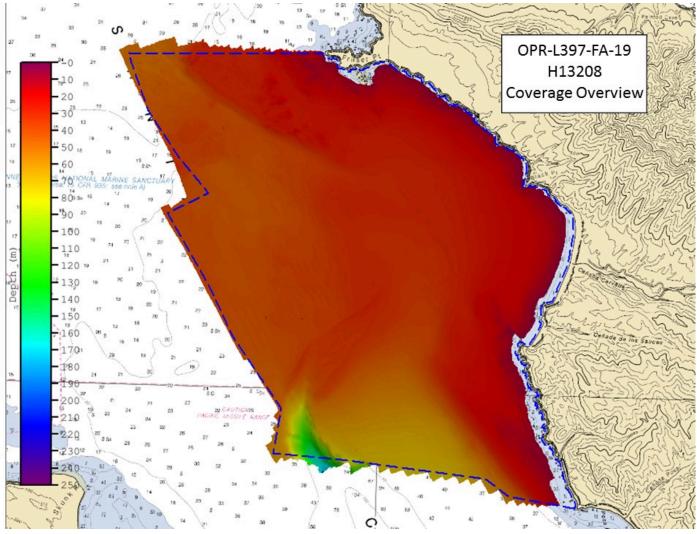


Figure 3: H13208 survey coverage overlaid onto Chart 18728

A.6 Survey Statistics

The following table lists the mainscheme and crossline acquisition mileage for this survey:

	HULL ID	2807	2806	2805	2808	Total
	SBES Mainscheme	0	0	0	0	0
	MBES Mainscheme	116.72	62.26	61.44	110.12	350.54
	Lidar Mainscheme	0	0	0	0	0
LNM	SSS Mainscheme	0	0	0	0	0
LINIVI	SBES/SSS Mainscheme	0	0	0	0	0
	MBES/SSS Mainscheme	0	0	0	0	0
	SBES/MBES Crosslines	5.50	0.81	0	9.26	15.57
	Lidar Crosslines	0	0	0	0	0
Numb Bottor	er of n Samples					0
	er Maritime ary Points igated					0
Numb	er of DPs					0
	er of Items igated by Ops					0
Total S	SNM					15.09

 Table 3: Hydrographic Survey Statistics

The following table lists the specific dates of data acquisition for this survey:

Survey Dates	Day of the Year
10/12/2019	285
10/13/2019	286

Survey Dates	Day of the Year		
10/14/2019	287		

Table 4: Dates of Hydrography

B. Data Acquisition and Processing

B.1 Equipment and Vessels

Refer to the OPR-L397-FA-19 Data Acquisition and Processing Report (DAPR) for a complete description of data acquisition and processing systems, survey vessels, quality control procedures and data processing methods. Additional information to supplement sounding and survey data, and any deviations from the DAPR are discussed in the following sections.

B.1.1 Vessels

The following vessels were used for data acquisition during this survey:

Hull ID	2805	2808	2806	2807
LOA	8.6 meters	8.6 meters	8.6 meters	8.6 meters
Draft	1.1 meters	1.1 meters	1.1 meters	1.1 meters

Table 5: Vessels Used

B.1.2 Equipment

The following major systems were used for data acquisition during this survey:

Manufacturer	Model	Туре
Kongsberg Maritime	EM 2040	MBES
Sea-Bird Scientific	SBE 19plus V2	Conductivity, Temperature, and Depth Sensor
Applanix	POS MV 320 v5	Positioning and Attitude System
Teledyne RESON	SVP 71	Sound Speed System

Table 6: Major Systems Used

The equipment was installed on the survey platform as follows: Each launch utilizes the Kongsberg EM 2040 MBES, a POS MV v5 system for position and attitude, SVP 71 surface sound speed sensors, and SBE 19plus V2 for conductivity, temperature, and depth (CTD) casts.

B.2 Quality Control

B.2.1 Crosslines

Multibeam/single beam echo sounder/side scan sonar crosslines acquired for this survey totaled 4.44% of mainscheme acquisition.

Crosslines were collected, processed and compared in accordance with Section 5.2.4.2 of the HSSD. To evaluate crosslines, a surface generated via data strictly from mainscheme lines and a surface generated via data strictly from crosslines were created. From these two surfaces, a difference surface (mainscheme - crosslines = difference surface) was generated (Figure 4), and is submitted in the Separates II Digital Data folder. Statistics show the mean difference between depths derived from mainscheme data and crossline data was 0.02 meters (with mainscheme being shoaler) and 95% of nodes falling within +/- 0.26 meters (Figure 5). For the respective depths, the difference surface was compared to the allowable NOAA uncertainty standards. In total, 99.93% of the depth differences between H13208 mainscheme and crossline data were within allowable NOAA uncertainties.

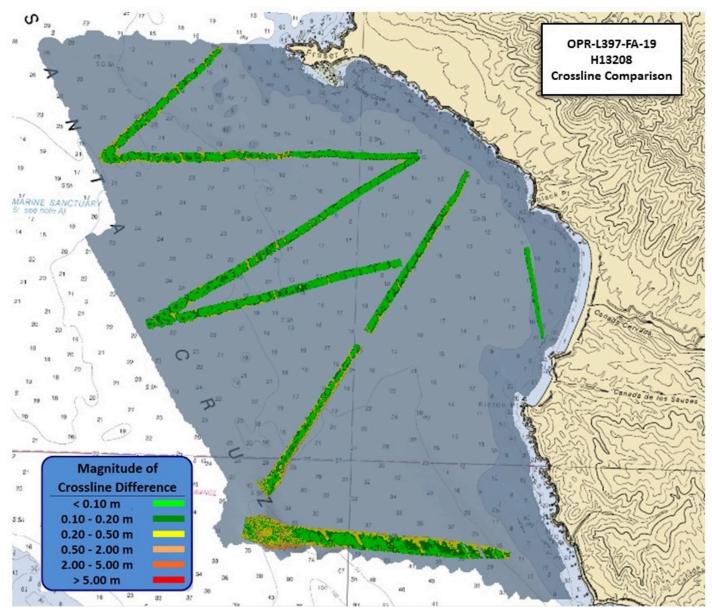


Figure 4: Overview of H13208 crosslines

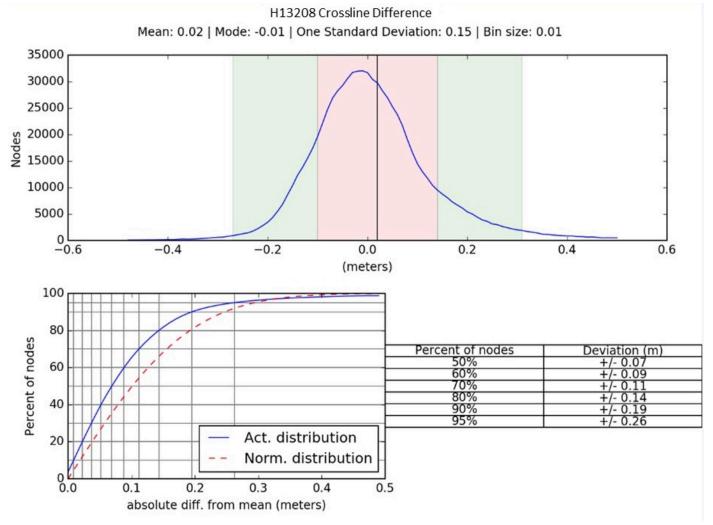


Figure 5: H13208 Crossline and maincheme difference statistics

B.2.2 Uncertainty

The following survey specific parameters were used for this survey:

Method	Measured	Zoning
ERS via VDATUM		7.8 centimeters

Table 7: Survey Specific Tide TPU Values.

Hull ID	Measured - CTD	Measured - MVP	Surface
280X	2 meters/second	N/A	0.5 meters/second

Table 8: Survey Specific Sound Speed TPU Values.

In addition to the usual a priori estimates of uncertainty via device models for vessel motion and VDATUM, real-time and post-processed uncertainty sources were also incorporated into the depth estimates of survey H13208. Real-time uncertainties were provided via EM 2040 MBES data and Applanix Delayed Heave RMS. Following post-processing of the real-time vessel motion, recomputed uncertainties of vessel roll, pitch, gyro and navigation were applied in CARIS HIPS and SIPS via a Smoothed Best Estimate of Trajectory (SBET) RMS file generated in Applanix POSPac.

B.2.3 Junctions

H13208 junctions with 2 adjacent surveys from this project, H13209, H13325 and 1 survey from prior projects, H13205 as shown in Figure 6. Data overlap between H13208 and each adjacent survey was achieved. These areas of overlap between surveys were reviewed in CARIS HIPS and SIPS by surface differencing (at equal resolutions) to assess surface agreement. The multibeam data were also examined in CARIS Subset Editor for consistency and agreement. The junctions with H13208 are generally within the NOAA allowable uncertainty in their areas of overlap. For all junctions with H13208, a negative difference indicates H13208 was shoaler and a positive difference indicates H13208 was deeper.

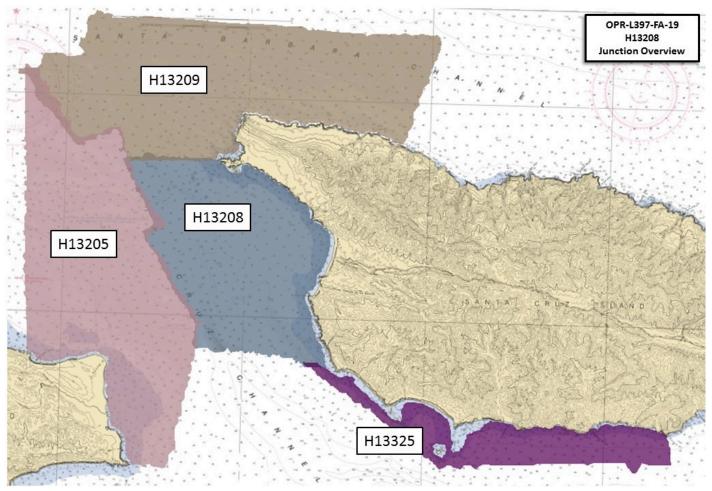


Figure 6: Overview of H13208 junction surveys

The following junctions were made with this survey:

Registry Number	Scale	Year	Field Unit	Relative Location
H13209	1:20000	2019	NOAA Ship FAIRWEATHER	N
H13325	1:20000	2019	NOAA Ship FAIRWEATHER	SE
H13205	1:20000	2018	NOAA Ship RAINIER	W

Table 9: Junctioning Surveys

<u>H13209</u>

Surface differencing in CARIS HIPS and SIPS was used to assess junction agreement between the surface from H13208 and the surface from H13209 (Figure 7). The statistical analysis of the difference surface

shows a mean of 0.05 meters with 95% of the nodes having a maximum deviation of +/-0.34 meters, as seen in Figure 8. It was found that 99.85% of nodes are within NOAA allowable uncertainty.

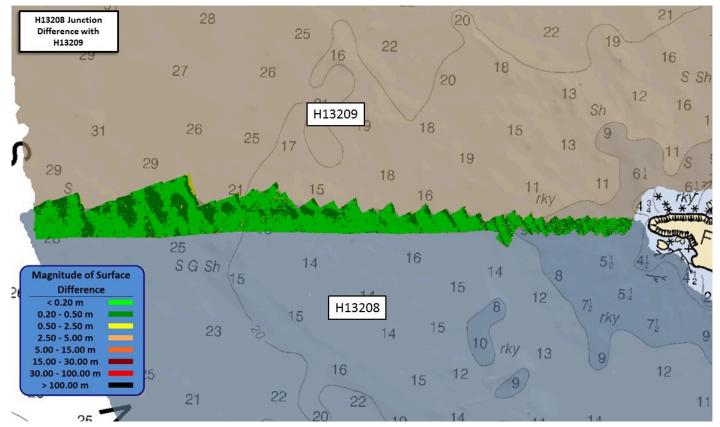


Figure 7: Difference surface between H13208 (gray) and junctioning survey H13209 (brown)

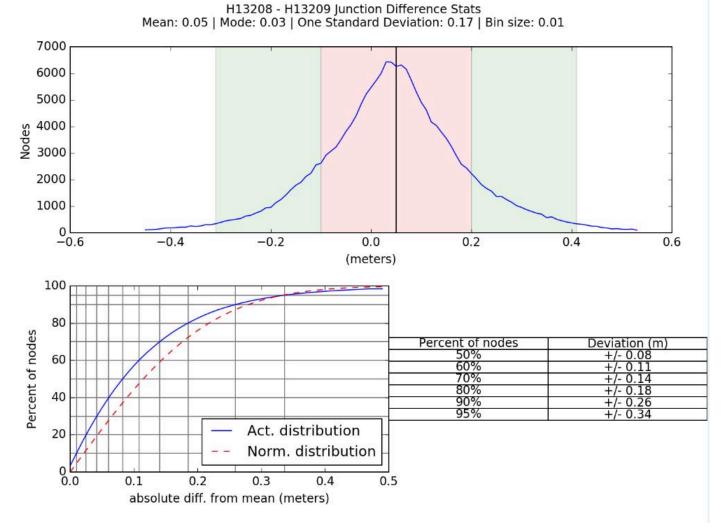


Figure 8: Difference surface statistics between H13208 and H13209 (VR surface)

<u>H13325</u>

Surface differencing in CARIS HIPS and SIPS was used to assess junction agreement between the surface from H13208 and the surface from H13325 (Figure 9). The statistical analysis of the difference surface shows a mean of 0.04 meters with 95% of the nodes having a maximum deviation of +/- 0.17 meters, as seen in Figure 10. It was found that 99.99% of nodes are within NOAA allowable uncertainty.

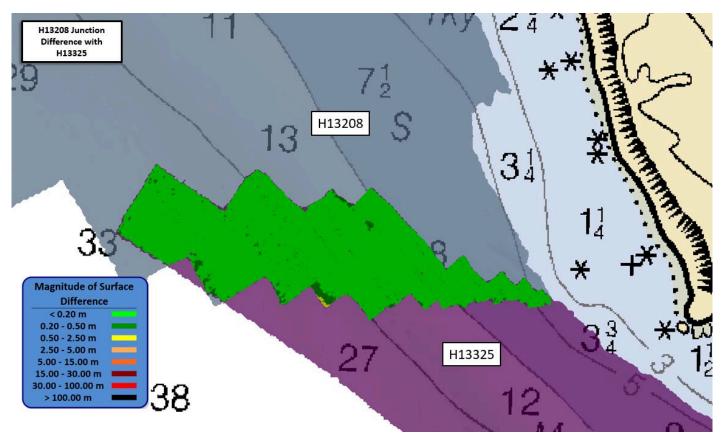


Figure 9: Difference surface between H13208 (gray) and junctioning survey H13325 (purple)

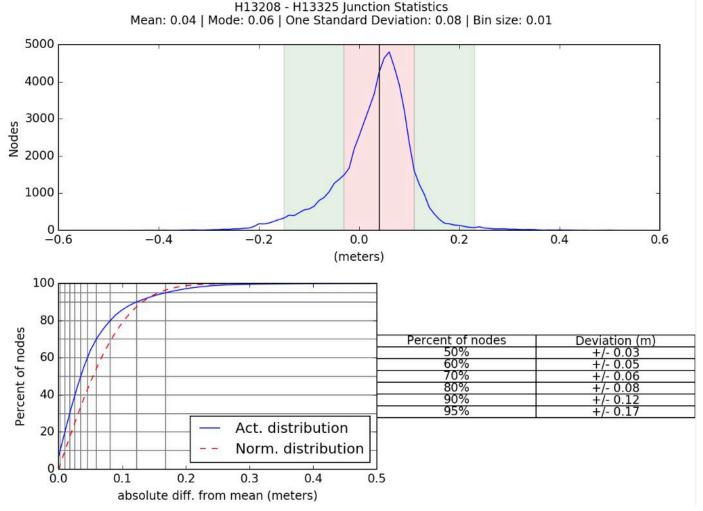


Figure 10: Difference surface statistics between H13208 and H13325 (VR surface)

<u>H13205</u>

Surface differencing in CARIS HIPS and SIPS was used to assess junction agreement between the surface from H13208 and the surface from H13205 (Figure 11). The statistical analysis of the difference surface shows a mean of 0.11 meters with 95% of the nodes having a maximum deviation of +/- 0.32 meters, as seen in Figure 12. It was found that 99.97% of nodes are within NOAA allowable uncertainty.

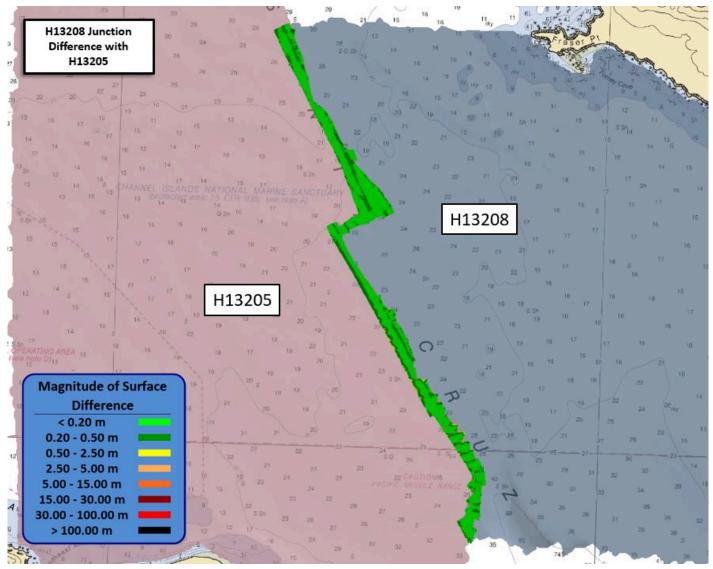
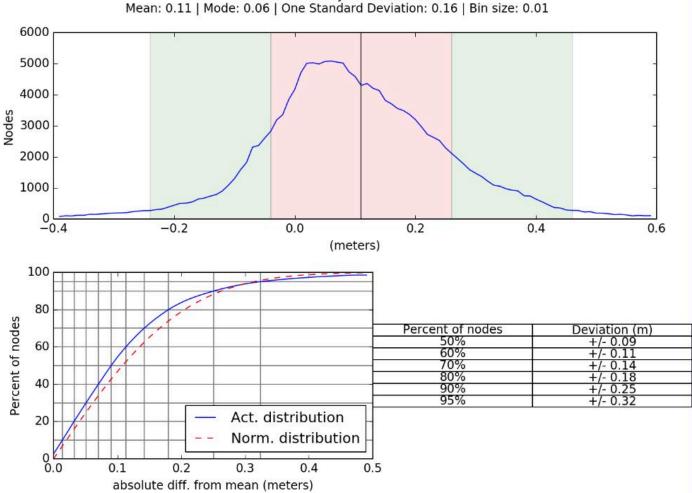


Figure 11: Difference surface between H13208 (gray) and junctioning survey H13205 (pink)



H13208 - H13205 Junction Statistics

Figure 12: Difference surface statistics between H13208 and H13205 (VR surface)

B.2.4 Sonar QC Checks

Sonar system quality control checks were conducted as detailed in the quality control section of the DAPR.

B.2.5 Equipment Effectiveness

There were no conditions or deficiencies that affected equipment operational effectiveness.

B.2.6 Factors Affecting Soundings

Sound Speed Issues

In certain areas, particularly the central and southern offshore portions of the survey area, sound speed issues were apparent, visible primarily as "smiles" (see Figure 13). Given the location of the issues, the most probable cause is subsurface mixing that was not modeled on the surface. Surfaces were not significantly impacted and the data still meet NOAA allowable uncertainty parameters from HSSD Section 5.1.3. As such, the data remain sufficient to supersede previous data.

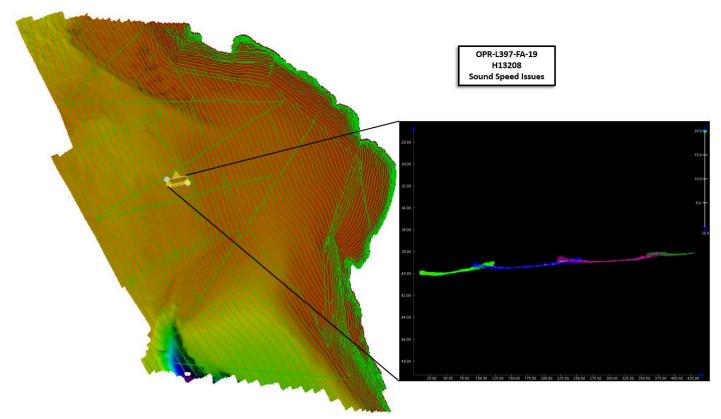


Figure 13: Example of sound speed issues visible in the data exaggerated 20x

B.2.7 Sound Speed Methods

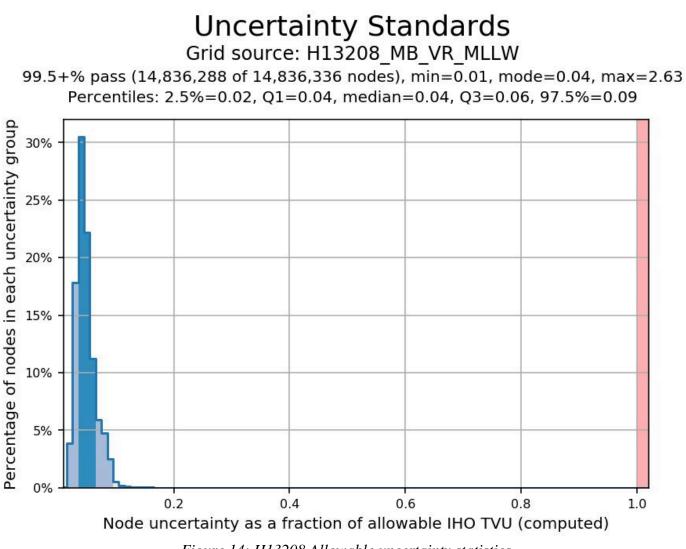
Sound Speed Cast Frequency: Casts were conducted at a minimum of one every four hours during launch acquisition. Casts were conducted more frequently in areas where the influx of freshwater had an effect on the speed of sound in the water column and when there was a change in surface sound speed greater than two meters per second.

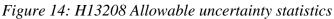
B.2.8 Coverage Equipment and Methods

All equipment and survey methods were used as detailed in the DAPR.

B.2.9 NOAA Allowable Uncertainty

The surface was analyzed using the HydrOffice QC Tools Grid QA feature to determine compliance with specifications. Overall, 99.99% of nodes within the surface meet NOAA Allowable Uncertainty specifications for H13208 (Figure 14).





B.2.10 Density

The surface was analyzed using the HydrOffice QC Tools Grid QA feature to determine compliance with specifications. Density requirements for H13208 were achieved with at least 99.89% of surface nodes containing five or more soundings as required by HSSD Section 5.2.2.3 (Figure 15).

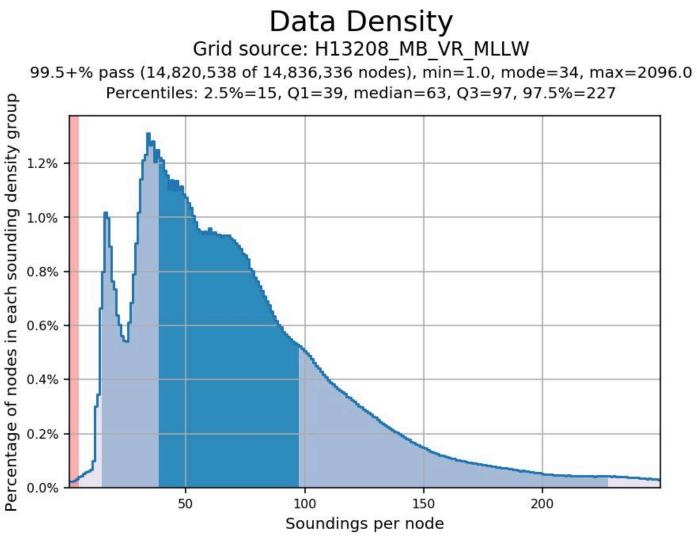


Figure 15: H13208 Data density statistics

B.3 Echo Sounding Corrections

B.3.1 Corrections to Echo Soundings

All data reduction procedures conform to those detailed in the DAPR.

B.3.2 Calibrations

All sounding systems were calibrated as detailed in the DAPR.

B.4 Backscatter

Raw backscatter data were stored in the .all file for Kongsberg systems. All backscatter were processed to GSF files and a floating point mosaic was created by the field unit via Fledermaus FMGT 7.8.10. See Figure 16 for a greyscale representation of the complete mosaic. A relative backscatter calibration was performed by HSTB via a patch test in order to bring the survey systems on each of the launches into alignment. See Figure 17 for a table of the calibration values entered into the Processing Settings within FMGT. Approximate inter-calibration corrections for offsets between sonar systems were applied to the mosaic.

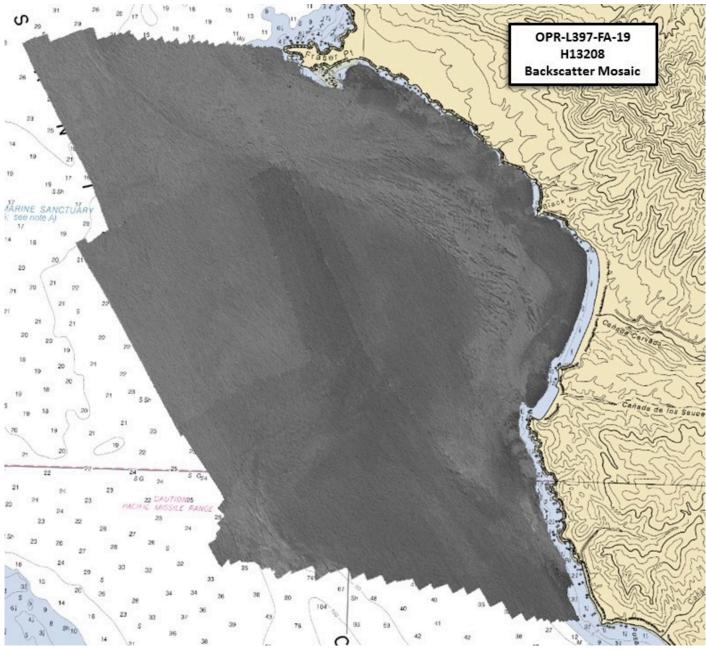


Figure 16: Backscatter mosaic for H13208

	200					300			400		
	Shor t CW	Med CW	Long CW	FM (Both)	Shor t CW	Med CW	Long CW	FM (Both)	Short CW	Med CW	Long CW
2805	-1.1	-1.4	-1.8	2.7	-0.7	-0.9	-1.0	-1.4	3	3.9	4.8
2806	1.8	1.8	1.8	2.4	-0.1	-0.3	-0.4	-0.8	3.6	4.65	5.7
2807	-0.3	-0.15	0	0	0	-0.2	-0.3	-0.7	3.3	4.2	5.1
2808	0	0.6	1.2	1.6	-0.3	-0.5	-0.6	-1.0	1.8	2.7	3.6

B.5 Data Processing

B.5.1 Primary Data Processing Software

The following software program was the primary program used for bathymetric data processing:

Manufacturer	Name	Version
CARIS	HIPS and SIPS	11.1.3

Table 10: Primary bathymetric data processing software

The following software program was the primary program used for imagery data processing:

Manufacturer	Name	Version
QPS	Fledermaus	7.8.10

Table 11: Primary imagery data processing software

The following Feature Object Catalog was used: NOAA Profile Version 2019.

B.5.2 Surfaces

The following surfaces and/or BAGs were submitted to the Processing Branch:

Surface Name	Surface Type	Resolution	Depth Range	Surface Parameter	Purpose
H13208_MB_VR_MLLW_final	CARIS VR Surface (CUBE)	Variable Resolution	0.543 meters - 173.218 meters	NOAA_VR	Complete MBES
H13208_MB_VR_MLLW	CARIS VR Surface (CUBE)	Variable Resolution	0.543 meters - 173.218 meters	NOAA_VR	Complete MBES

Table 12: Submitted Surfaces

The NOAA CUBE parameters defined in the HSSD were used for the creation of all CUBE surfaces for H13208. The surfaces have been reviewed where noisy data, or "fliers" are incorporated into the gridded solutions causing the surface to be shoaler or deeper than the true sea floor. Where these spurious soundings cause the gridded surface to vary from the reliably measured seabed by greater than the maximum allowable Total Vertical Uncertainty at that depth, the noisy data have been rejected by the hydrographer and the surface recomputed.

Flier Finder, part of the QC Tools package within HydrOffice, was used to assist the search for spurious soundings following gross cleaning. Flier Finder was run iteratively until all remaining flagged fliers were deemed to be valid aspects of the surface.

B.5.3 Data Logs

Data acquisition and processing notes are included in the acquisition and processing logs, and additional processing such as final separation model reduction and sound speed application are noted in the H13208 Data Log spreadsheet. All data logs are submitted digitally in the Separates I folder.

C. Vertical and Horizontal Control

Per Section 5.1.2.3 of the 2014 Field Procedures Manual, no Horizontal and Vertical Control Report has been generated for H13208.

C.1 Vertical Control

The vertical datum for this project is Mean Lower Low Water.

ERS Datum Transformation

The following ellipsoid-to-chart vertical datum transformation was used:

Method	Ellipsoid to Chart Datum Separation File
ERS via VDATUM	OPR-L397-FA-19_100mNAD83-MLLW_geoid12a.csar

Table 13: ERS method and SEP file

ERS methods were used as the final means of reducing H13208 to MLLW for submission.

C.2 Horizontal Control

The horizontal datum for this project is North American Datum of 1983 (NAD 83).

The projection used for this project is Universal Transverse Mercator (UTM) Zone 11.

The following PPK methods were used for horizontal control:

• RTX

Vessel kinematic data were post-processed using Applanix POSPac processing software and RTX positioning methods described in the DAPR. Smoothed Best Estimate of Trajectory (SBET) and associated error (RMS) data were applied to all MBES data in CARIS HIPS and SIPS.

WAAS

During real-time acquisition, all platforms received correctors from the Wide Area Augmentation System (WAAS) for increased accuracies similar to USCG DGPS stations. WAAS and SBETs were the sole methods of positioning for H13208 as no DGPS stations were available for real-time horizontal control.

D. Results and Recommendations

D.1 Chart Comparison

A comparison was performed between survey H13208 and ENC US5CA66M using CARIS HIPS and SIPS. Sounding and contour layers were overlaid on the ENC to assess differences between the surveyed soundings and charted depths. The ENC was compared to the surface by extracting all soundings from the chart and creating an interpolated TIN surface which could be differenced with the surface from H13208 as shown in Figure 18. Statistical analysis of the difference surface is shown in Figure 19.

All data from H13208 should supersede charted data. In general, surveyed soundings agree with the majority of charted depths. A full discussion follows below.

D.1.1 Electronic Navigational Charts

The following are the largest scale ENCs, which cover the survey area:

ENC	Scale	Edition	Update Application Date	Issue Date	Preliminary?
US5CA66M	1:40000	6	05/24/2019	10/04/2019	NO

Table 14: Largest Scale ENCs

US5CA66M

Soundings from H13208 are in general agreement with charted depths on ENC US5CA66M with the exception of the southwest corner of the survey area where differences range to 15 fathoms as seen in Figure 20.

Contours from H13208 are in general agreement with charted contours on ENC US5CA66M as shown in Figure 21. The hydrographer recommends that the 20 fathom contour line be updated to represent the most recent survey.

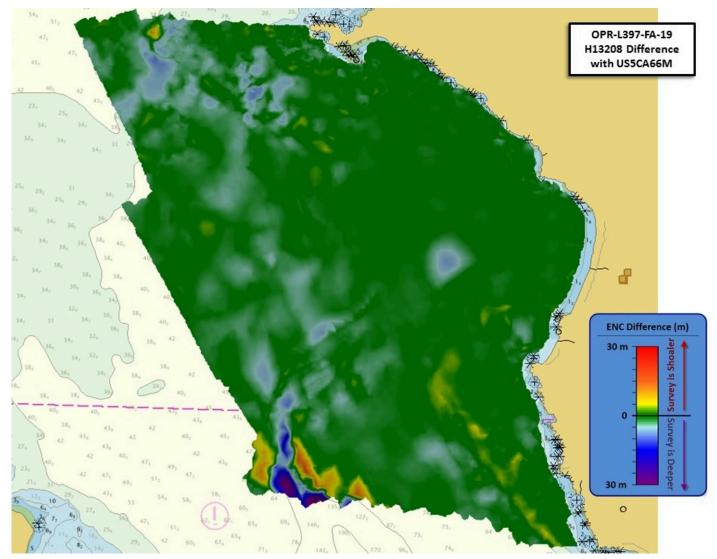
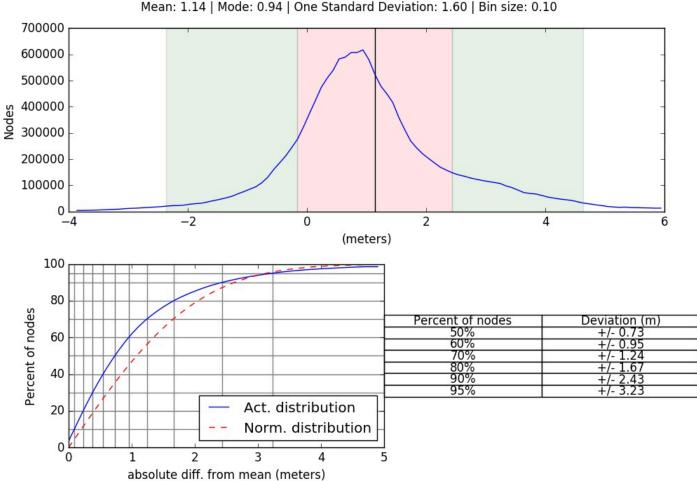
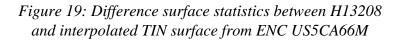


Figure 18: Difference surface between H13208 and interpolated TIN surface from ENC US5CA66M



H13208 - US5CA66M Difference Statistics Mean: 1.14 | Mode: 0.94 | One Standard Deviation: 1.60 | Bin size: 0.10



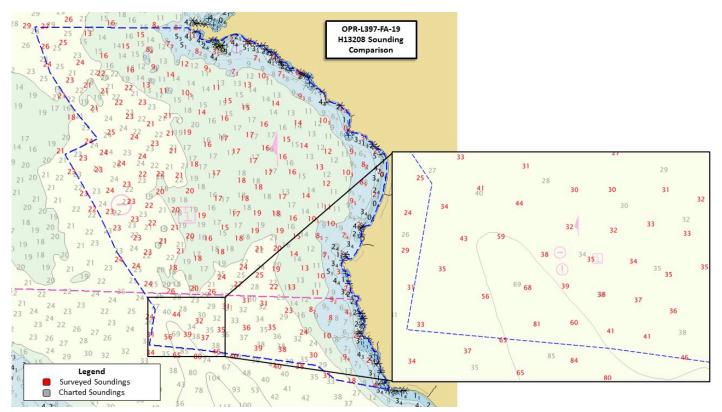


Figure 20: Overview of H13208 soundings (fathoms) overlaid onto ENC US5CA66M

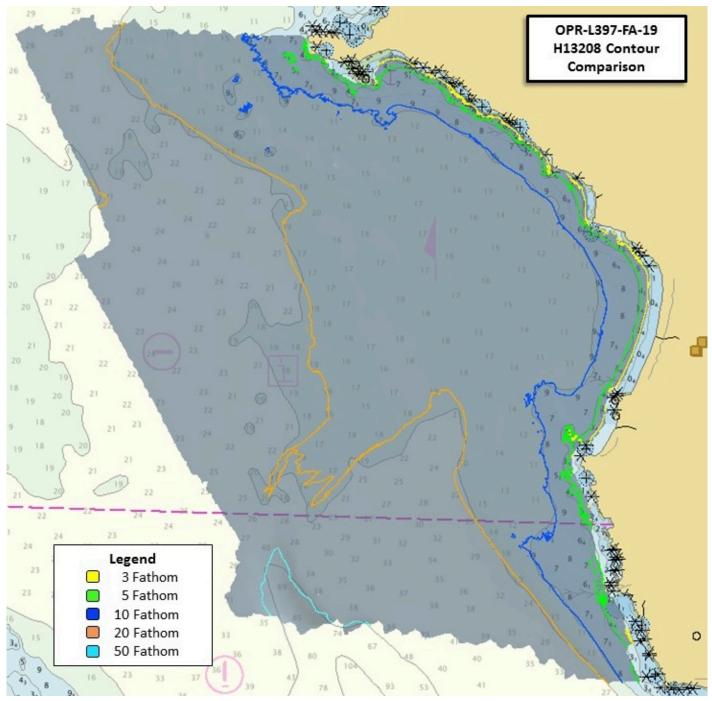


Figure 21: Overview of H13208 contours overlaid onto ENC US5CA66M

D.1.2 Maritime Boundary Points

No Maritime Boundary Points were assigned for this survey.

D.1.3 Charted Features

No charted features exist for this survey.

D.1.4 Uncharted Features

Survey H13208 has 12 new features that are addressed in the H13208 Final Feature File. Of these features, there is 1 new Obstruction, 3 new Land Areas, 3 Land Elevations, 4 new Seabed Areas, and 1 new Kelp feature.

D.1.5 Shoal and Hazardous Features

No shoals or potentially hazardous features exist for this survey.

D.1.6 Channels

No channels exist for this survey. There are no designated anchorages, precautionary areas, safety fairways, traffic separation schemes, pilot boarding areas, or channel and range lines within the survey limits.

D.1.7 Bottom Samples

No bottom samples were required for this survey.

D.2 Additional Results

D.2.1 Shoreline

Fairweather personnel conducted limited shoreline verification and reconnaissance, utilizing traditional shoreline methods, at times near predicted negative or low tides within the survey limits. Inaccessible features inshore of the NALL were attributed in the Final Feature File with the description of "Not Addressed" and remarks of "Retain as charted, not investigated due to being inshore of NALL" as per HSSD Section 7.3.1. Annotations, information, and diagrams collected on DP forms and boat sheets during field operations were scanned and included in the Separates I Detached Positions folder. Shoreline verification procedures for H13208 conform to those detailed in the DAPR.

D.2.2 Aids to Navigation

No Aids to navigation (ATONs) exist for this survey.

D.2.3 Overhead Features

No overhead features exist for this survey.

D.2.4 Submarine Features

No submarine features exist for this survey.

D.2.5 Platforms

No platforms exist for this survey.

D.2.6 Ferry Routes and Terminals

No ferry routes or terminals exist for this survey.

D.2.7 Abnormal Seafloor and/or Environmental Conditions

No abnormal seafloor and/or environmental conditions exist for this survey.

D.2.8 Construction and Dredging

No present or planned construction or dredging exist within the survey limits.

D.2.9 New Survey Recommendation

No new surveys or further investigations are recommended for this area.

D.2.10 Inset Recommendation

No new insets are recommended for this area.

E. Approval Sheet

As Chief of Party, field operations for this hydrographic survey were conducted under my direct supervision, with frequent personal checks of progress and adequacy. I have reviewed the attached survey data and reports.

All field sheets, this Descriptive Report, and all accompanying records and data are approved. All records are forwarded for final review and processing to the Processing Branch.

The survey data meets or exceeds requirements as set forth in the NOS Hydrographic Surveys Specifications and Deliverables, Field Procedures Manual, Letter Instructions, and all HSD Technical Directives. These data are adequate to supersede charted data in their common areas. This survey is complete and no additional work is required with the exception of deficiencies noted in the Descriptive Report.

Approver Name	Approver Title	Approval Date	Signature
CAPT. Marc Moser	Chief of Party	02/20/2020	MOSER.MARC.S MOSER.MARC.STAN TANTON.11631 93902 -07'00'
Lt. Steve Moulton	Operations Officer	02/20/2020	MOULTON.STEPH BN.F.1282116835 -08'00' Digitally signed by MOULTON.STEPHEN.F.128211 6835 -08'00'
CHST Alissa Johnson	Chief Survey Technician	02/20/2020	JOHNSON.ALISSA JEAN.1537531165 Date: 2020.02.20 15:04:59 -08'00'
HAST Kevin Lally	Sheet Manager	02/20/2020	LALLY.KEVIN.FR Digitally signed by LALLY.KEVIN.FRANCIS.1570 ANCIS.15707344 734411 Date: 2020.03.11 13:30:14 -07'00'

F. Table of Acronyms

Acronym	Definition
AHB	Atlantic Hydrographic Branch
AST	Assistant Survey Technician
ATON	Aid to Navigation
AWOIS	Automated Wreck and Obstruction Information System
BAG	Bathymetric Attributed Grid
BASE	Bathymetry Associated with Statistical Error
СО	Commanding Officer
CO-OPS	Center for Operational Products and Services
CORS	Continuously Operating Reference Station
CTD	Conductivity Temperature Depth
CEF	Chart Evaluation File
CSF	Composite Source File
CST	Chief Survey Technician
CUBE	Combined Uncertainty and Bathymetry Estimator
DAPR	Data Acquisition and Processing Report
DGPS	Differential Global Positioning System
DP	Detached Position
DR	Descriptive Report
DTON	Danger to Navigation
ENC	Electronic Navigational Chart
ERS	Ellipsoidal Referenced Survey
ERTDM	Ellipsoidally Referenced Tidal Datum Model
ERZT	Ellipsoidally Referenced Zoned Tides
FFF	Final Feature File
FOO	Field Operations Officer
FPM	Field Procedures Manual
GAMS	GPS Azimuth Measurement Subsystem
GC	Geographic Cell
GPS	Global Positioning System
HIPS	Hydrographic Information Processing System
HSD	Hydrographic Surveys Division

Acronym	Definition	
HSSD	Hydrographic Survey Specifications and Deliverables	
HSTB	Hydrographic Systems Technology Branch	
HSX	Hypack Hysweep File Format	
HTD	Hydrographic Surveys Technical Directive	
HVCR	Horizontal and Vertical Control Report	
HVF	HIPS Vessel File	
ІНО	International Hydrographic Organization	
IMU	Inertial Motion Unit	
ITRF	International Terrestrial Reference Frame	
LNM	Linear Nautical Miles	
MBAB	Multibeam Echosounder Acoustic Backscatter	
MCD	Marine Chart Division	
MHW	Mean High Water	
MLLW	Mean Lower Low Water	
NAD 83	North American Datum of 1983	
NALL	Navigable Area Limit Line	
NTM	Notice to Mariners	
NMEA	National Marine Electronics Association	
NOAA	National Oceanic and Atmospheric Administration	
NOS	National Ocean Service	
NRT	Navigation Response Team	
NSD	Navigation Services Division	
OCS	Office of Coast Survey	
OMAO	Office of Marine and Aviation Operations (NOAA)	
OPS	Operations Branch	
MBES	Multibeam Echosounder	
NWLON	National Water Level Observation Network	
PDBS	Phase Differencing Bathymetric Sonar	
РНВ	Pacific Hydrographic Branch	
POS/MV	Position and Orientation System for Marine Vessels	
РРК	Post Processed Kinematic	
PPP	Precise Point Positioning	
PPS	Pulse per second	

Acronym	Definition	
PRF	Project Reference File	
PS	Physical Scientist	
RNC	Raster Navigational Chart	
RTK	Real Time Kinematic	
RTX	Real Time Extended	
SBES	Singlebeam Echosounder	
SBET	Smooth Best Estimate and Trajectory	
SNM	Square Nautical Miles	
SSS	Side Scan Sonar	
SSSAB	Side Scan Sonar Acoustic Backscatter	
ST	Survey Technician	
SVP	Sound Velocity Profiler	
TCARI	Tidal Constituent And Residual Interpolation	
ТРЕ	Total Propagated Error	
TPU	Topside Processing Unit	
USACE	United States Army Corps of Engineers	
USCG	United States Coast Guard	
UTM	Universal Transverse Mercator	
XO	Executive Officer	
ZDF	Zone Definition File	



UNITED STATES DEPARTMENT OF COMMERCE National Oceanic and Atmospheric Administration NATIONAL OCEAN SERVICE Office of Coast Survey Silver Spring, Maryland 20910-3282

July 30, 2019

MEMORANDUM FOR:	Captain Richard T. Brennan, NOAA Chief, Hydrographic Surveys Division
FROM:	Meredith Payne Project Manager OPR-L397-FA-19, Hydrographic Surveys Division
SUBJECT:	Early Data Release OPR-L397-FA-19

Hydrographic Surveys Division (HSD) requests a waiver for NOAA Ship *Fairweather* to release ship-processed data for the project OPR-L397-FA-19, Channel Islands to the Channel Islands National Marine Sanctuary (CINMS) stakeholders prior to passing RSA or SAR procedures at the processing branch.

Justification

OPR-L397-FA-19, Channel Islands was a project jointly funded by HSD and CINMS for the purpose of nautical chart updates and sanctuary management/habitat mapping. During planning stages for the project early data release to stakeholders was agreed to by HSD.

CINMS agrees to append the following Department of Commerce counsel-approved language to any products produced with these preliminary data:

These data are preliminary, and as such may contain position and depth errors and/or other quality issues. Products generated with these data are not to be used for measurements or navigation under any circumstances.

The user assumes the entire risk related to the use of these data or products generated with these data. The Office of Coast Survey is providing these data "as-is," and OCS disclaims any and all warranties, whether express or implied, including any implied warranties of merchantability or fitness for a particular purpose. In no event will OCS be liable to you or to any third party for any direct, indirect, incidental, consequential, special, or exemplary damages or lost profit resulting from any use or misuse of these data.

Decision

Waiver is:	Granted
	Denied



APPROVAL PAGE

H13208

Data meet or exceed current specifications as certified by the OCS survey acceptance review process. Descriptive Report and survey data except where noted are adequate to supersede prior surveys and nautical charts in the common area.

The following products will be sent to NCEI for archive

- Descriptive Report
- Collection of Bathymetric Attributed Grids (BAGs)
- Collection of backscatter mosaics
- Processed survey data and records
- GeoPDF of survey products

The survey evaluation and verification has been conducted according current OCS Specifications, and the survey has been approved for dissemination and usage of updating NOAA's suite of nautical charts.

Approved:

Commander Olivia Hauser, NOAA Chief, Pacific Hydrographic Branch