H13247

U.S. Department of Commerce
National Oceanic and Atmospheric Administration
National Ocean Service

DESCRIPTIVE REPORT

Type of Survey:	Navigable Area
Registry Number:	H13247

LOCALITY

State(s):	Alaska
General Locality:	Kuskokwim Bay, AK
Sub-locality:	28 NM SW of Kwigillingok

2019

CHIEF OF PARTY
Andrew Orthmann

LIBRARY & ARCHIVES

Date:

U.S. DEPARTMENT OF COMMERCE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION	REGISTRY NUMBER:
HYDROGRAPHIC TITLE SHEET	**H13247**

INSTRUCTIONS: The Hydrographic Sheet should be accompanied by this form, filled in as completely as possible, when the sheet is forwarded to the Office.

State(s):	**Alaska**
General Locality:	**Kuskokwim Bay, AK**
Sub-Locality:	**28 NM SW of Kwigillingok**
Scale:	**40000**
Dates of Survey:	**07/01/2019 to 08/18/2019**
Instructions Dated:	**05/10/2019**
Project Number:	**OPR-R341-KR-19**
Field Unit:	**Terrasond**
Chief of Party:	**Andrew Orthmann**
Soundings by:	**Multibeam Echo Sounder**
Imagery by:	
Verification by:	**Pacific Hydrographic Branch**
Soundings Acquired in:	**meters at Mean Lower Low Water**

Remarks:

Any revisions to the Descriptive Report (DR) applied during office processing are shown in red italic text. The DR is maintained as a field unit product, therefore all information and recommendations within this report are considered preliminary unless otherwise noted. The final disposition of survey data is represented in the NOAA nautical chart products. All pertinent records for this survey are archived at the National Centers for Environmental Information (NCEI) and can be retrieved via https://www.ncei.noaa.gov/. Products created during office processing were generated in NAD83 UTM 3N, MLLW. All references to other horizontal or vertical datums in this report are applicable to the processed hydrographic data provided by the field unit.

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Descriptive Report to Accompany Survey H13247

Project: OPR-R341-KR-19

Locality: Kuskokwim Bay, AK

Sublocality: 28 NM SW of Kwigillingok

Scale: 1:40000

July 2019 - August 2019

Terrasond

Chief of Party: Andrew Orthmann

A. Area Surveyed

The project area is located in southwest Alaska in Kuskokwim Bay, SW of the entrance to the Kuskokwim River in a relatively remote area of the Arctic. Vessel traffic consists largely of barges servicing the communities that include Bethel up the Kuskokwim River to the NE, as well as vessels transiting between Kuskokwim Bay and Etolin Strait, to the west.

The area is normally not navigable during winter due to discontinuous sea ice in the bay and river ice flows from the Kuskokwim River. The area is highly exposed, with only limited protection from the north. The seafloor is relatively shallow (less than 20 meters) and gently sloping. Bottom samples returned primarily black sand.

Bathymetric data collection was carried out in July and August of 2019 under project OPR-R341-KR-19, with final processing and reporting carried out from September through December, 2019. Supporting tide data was acquired from June through October, 2019. Work was completed concurrently with other assigned areas within Kuskokwim Bay and near Nunivak Island, and done in accordance with the Hydrographic Survey Project Instructions (dated May 10th, 2019) and the NOS Hydrographic Surveys Specifications and Deliverables (HSSD), March 2019 edition.

A.1 Survey Limits

Data were acquired within the following survey limits:

Northwest Limit	Southeast Limit
59° 48' 29.99" N 164° 29' 7.52" W	59° 18' 6.08" N 163° 20' 6.79" W

Table 1: Survey Limits

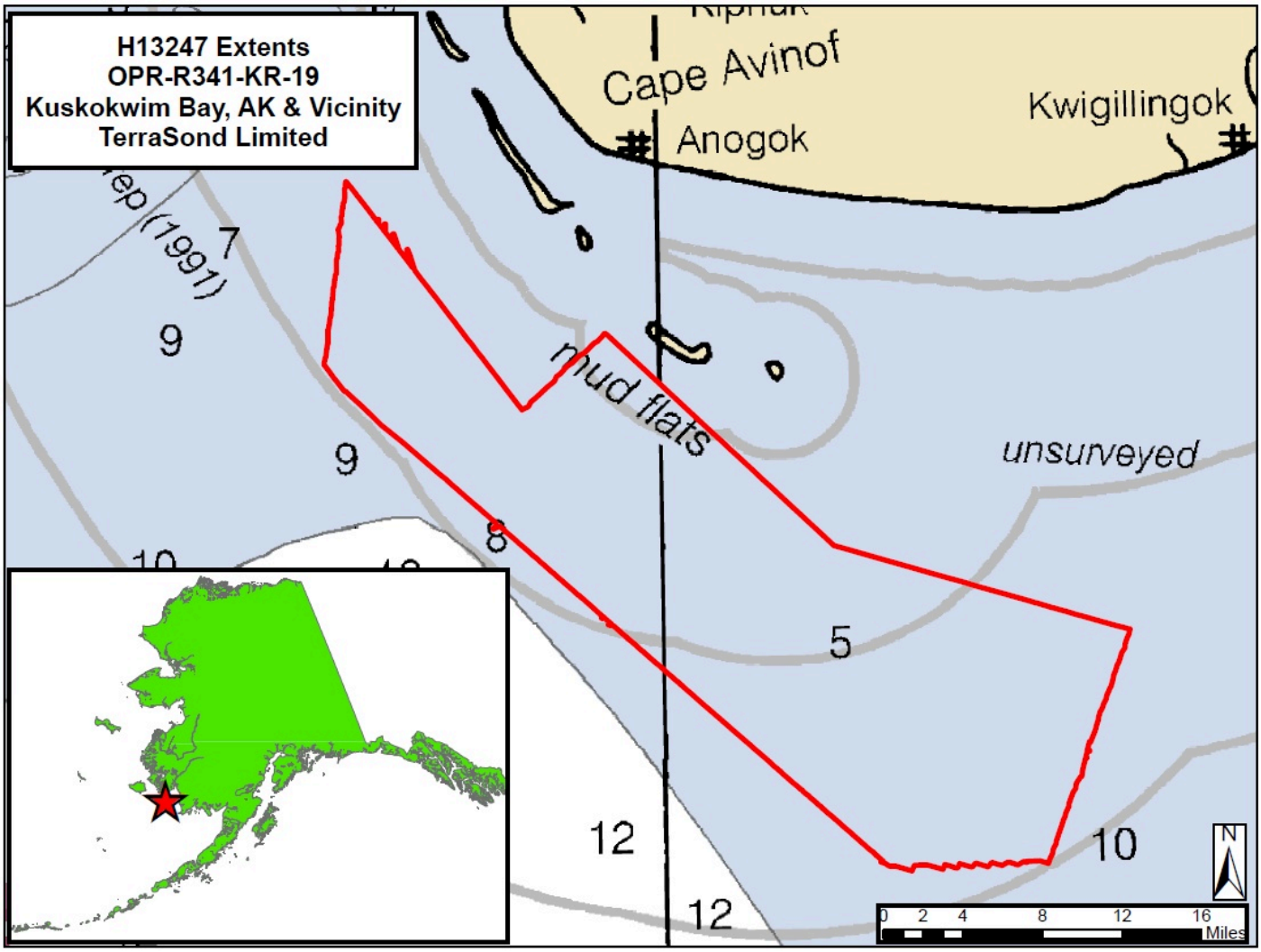

Figure 1: Image showing survey extents.

Per consultation with HSD OPS, area from the unassigned adjacent survey area "HXXXXX" was added to this survey. Surveying to all extents of the HXXXXX area was not required. Refer to the Survey Coverage section of this report for more discussion.

Data was successfully acquired to all originally assigned limits of H13247.

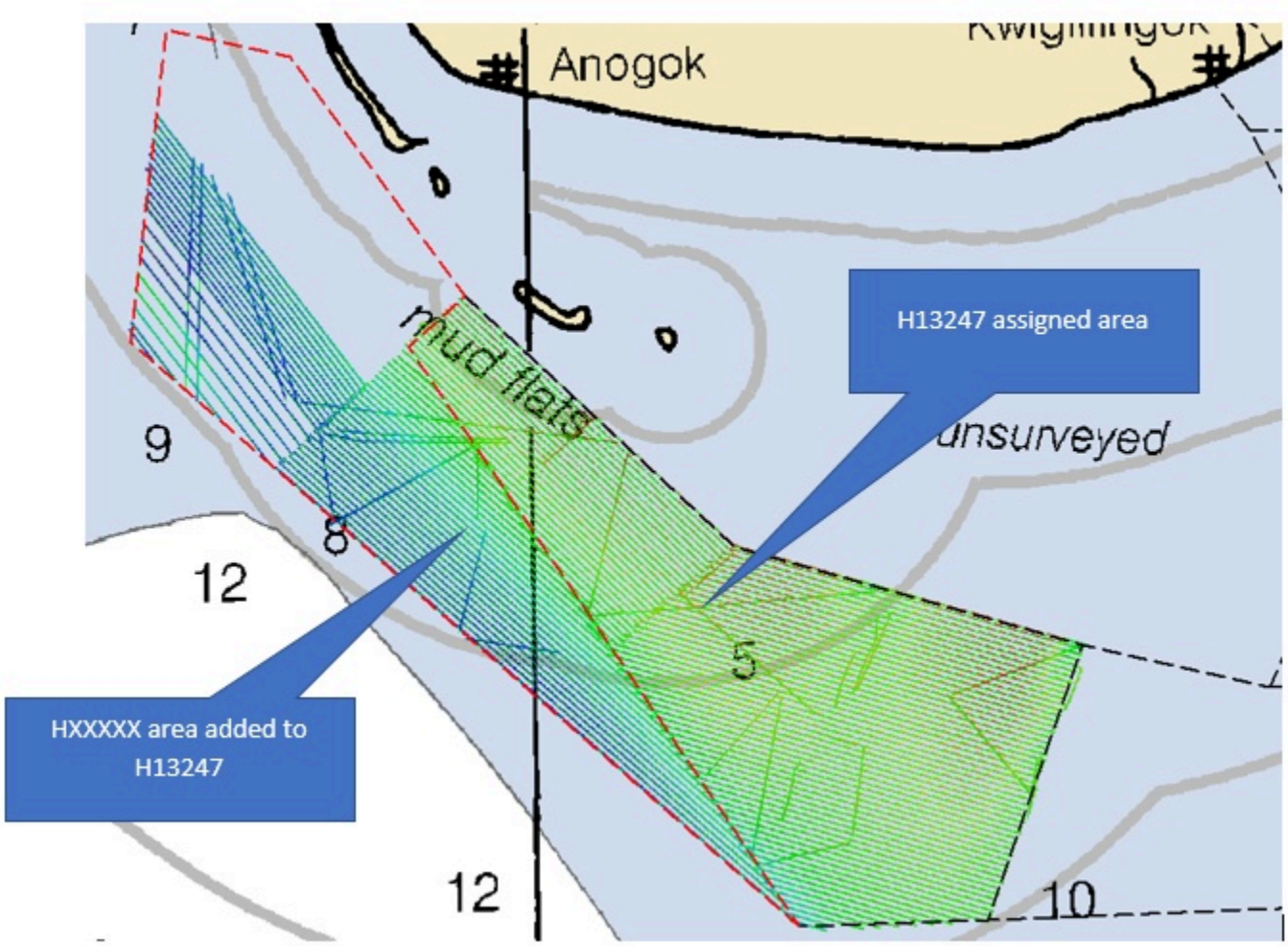

Figure 2: Original survey limits of H13247 (right side of image) were achieved. Area from the unassigned sheet HXXXXX (red dashed polygon, left side of image) was partially surveyed and added to H13247.

A.2 Survey Purpose

The overall project OPR-R341-KR-19 is intended to provide contemporary surveys to update National Ocean Service (NOS) nautical charting products in the U.S. Arctic to support commerce in the region. Automatic Identification Systems (AIS) traffic patterns feeding the Hydrographic Health model, along with direct user feedback helped to define the survey area in Kuskokwim Bay, Southwest Alaska. This area is largely unsurveyed and contains mud flats, uncharted shoals, and poorly modeled tides, forcing vessel traffic between the Kuskokwim River and northern communities to take an extended southerly route to stay in safe water. Surveying these areas within Kuskokwim Bay will allow for shorter routes, increasing the safety and efficiency of vessel traffic. This work will also directly support the maritime services available to the native communities of Kwigillingok and Kongiganak.

Furthermore, this project will provide support for other NOAA Hydrographic surveys and regional tidal products by installing temporary water level measuring stations in the vicinities of Cape Newenham and Nushagak Peninsula located in Bristol Bay.

Survey data within the survey limits is intended to supersede all prior survey data within the project limits.

A.3 Survey Quality

The entire survey is adequate to supersede previous data.

A.4 Survey Coverage

The following table lists the coverage requirements for this survey as assigned in the project instructions:

Water Depth	Coverage Required
All waters in survey area within Sheet 2	Set Line Spacing MBES at 400 m (Refer to HSSD Section 5.2.2.4 Option A)
All waters in survey area	Complete 5301 LNM. Transit mileage, system calibration mileage and data which do not meet HSSD specifications shall not count towards the completion of the LNM requirement. Notify the COR/Project Manager upon nearing completion of LNM requirement. The final survey area shall be squared off and ensure the full investigation of any features within the surveyed extent.

Table 2: Survey Coverage

Coverage requirements were met.

5,761 linear nautical miles (LNM) was acquired project-wide, which exceeded the required minimum of 5,301 LNM. The overage of 460 LNM (about 8.7% of required LNM) was collected to compensate for any inefficiencies incidental to the execution of line collection such as excess crossline LNM, data acquired on turns in order to scout depths between lines in shallow water, or lines ran closer together than required.

Survey of "HXXXXX" and Incorporation into H13247:

This survey is divided into two parts for coverage tracking purposes. The eastern part is the originally assigned H13247, and the western part is the unassigned "HXXXXX" area from the project instructions. The eastern part was surveyed in full, achieving all extents and the required line spacing of 400 m. Refer to the image of the two parts previously in this report.

MBES data collection in the western part, HXXXXX, commenced when it became obvious that survey of the seven sheets assigned under the project would not require all 5,301 LNM assigned in the project instructions. The eastern part of HXXXXX was surveyed first in order to be coterminous with the original H13247 extents before proceeding into the western portion. Most lines in the HXXXXX area were also acquired at 400 m spacing per the project instructions requirement for "Sheet 8". However, after consultation with NOAA OPS, the final sets of lines (located in the SW portion of the survey area) were spaced at 800 m to cover more area with the remaining LNM.

To simplify reporting and data management, all data collected in "HXXXXX" was incorporated into H13247 instead of being assigned as a new H#.

Refer to Appendix II for correspondence regarding the area.

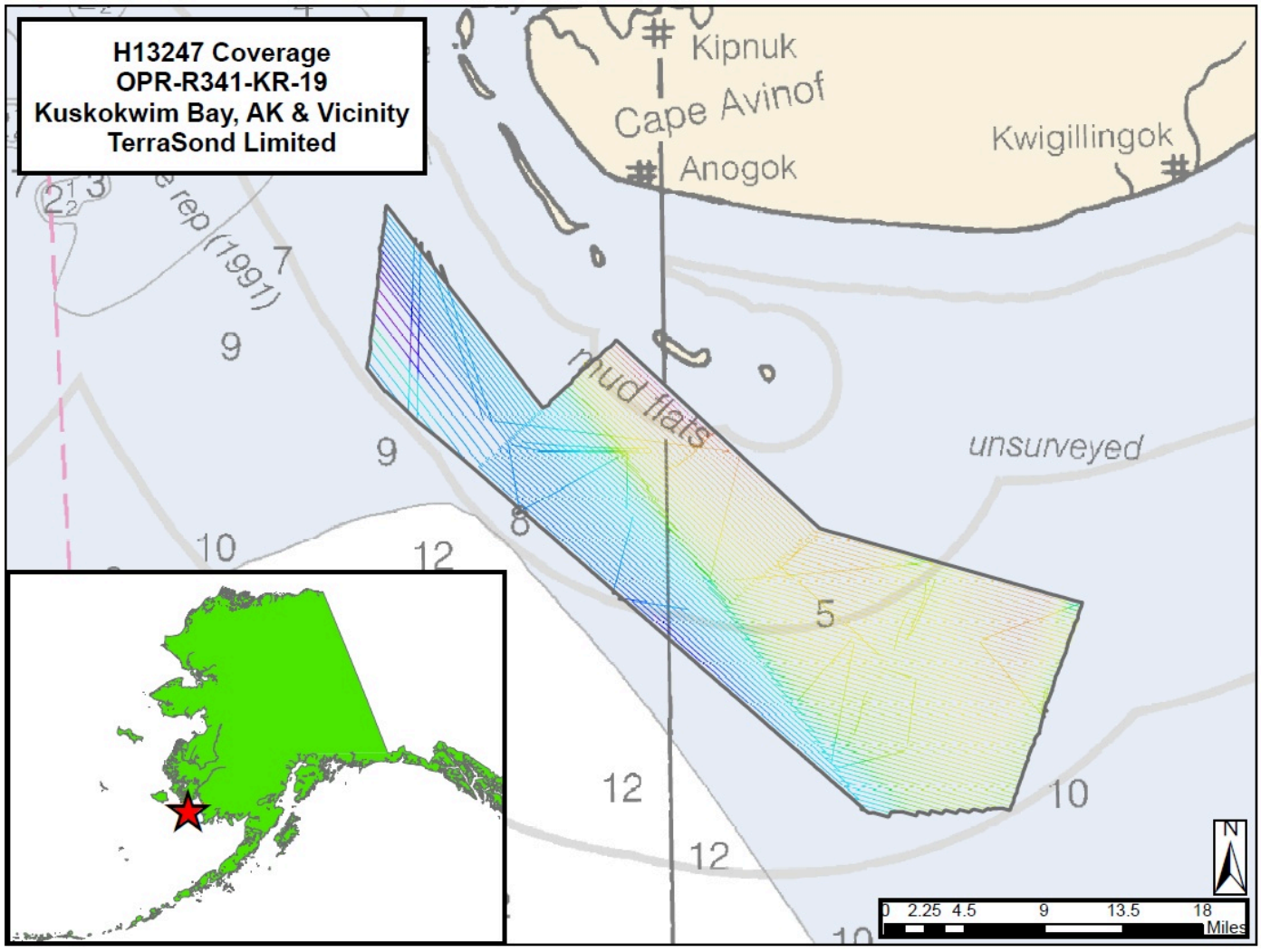

Figure 3: Image showing survey coverage.

A.6 Survey Statistics

The following table lists the mainscheme and crossline acquisition mileage for this survey:

	HULL ID	*ASV-CW5*	*Qualifier 105*	*Total*
LNM	**SBES Mainscheme**	0	0	0
	MBES Mainscheme	693.3	994.1	1687.4
	Lidar Mainscheme	0	0	0
	SSS Mainscheme	0	0	0
	SBES/SSS Mainscheme	0	0	0
	MBES/SSS Mainscheme	0	0	0
	SBES/MBES Crosslines	34.7	105.3	140
	Lidar Crosslines	0	0	0
Number of Bottom Samples				4
Number Maritime Boundary Points Investigated				0
Number of DPs				0
Number of Items Investigated by Dive Ops				0
Total SNM				354.5

Table 3: Hydrographic Survey Statistics

The following table lists the specific dates of data acquisition for this survey:

Survey Dates	Day of the Year
07/01/2019	182
07/04/2019	185
07/07/2019	188
07/16/2019	197
07/17/2019	198
07/18/2019	199
07/19/2019	200
07/20/2019	201
07/21/2019	202
07/22/2019	203
07/23/2019	204
07/24/2019	205
07/25/2019	206
07/26/2019	207
07/27/2019	208
07/28/2019	209
08/17/2019	229
08/18/2019	230

Table 4: Dates of Hydrography

B. Data Acquisition and Processing

B.1 Equipment and Vessels

Refer to the Data Acquisition and Processing Report (DAPR) for a complete description of data acquisition and processing systems, survey vessels, quality control procedures and data processing methods. Additional information to supplement sounding and survey data, and any deviations from the DAPR are discussed in the following sections.

B.1.1 Vessels

The following vessels were used for data acquisition during this survey:

Hull ID	*ASV-CW5*	*Qualifier 105*
LOA	5.5 meters	32 meters
Draft	0.5 meters	1.8 meters

Table 5: Vessels Used

Figure 4: ASV-CW5 (foreground), and Q105 (background).

The Qualifier 105 (Q105) is a 32 m aluminum-hull vessel owned and operated by Support Vessels of Alaska. The Q105 acquired multibeam data and provided housing and facilities for on-site data processing. The vessel was also used to collect bottom samples, deploy/recover BMPG tide gauges, conduct sound speed casts, and deploy/recover the ASV-CW5 vessel.

The ASV-CW5 (C-Worker 5) is a 5.5 m aluminum-hull Autonomous Surface Vessel (ASV) owned and operated by L3-Harris ASV. The ASV was operated in an unmanned but monitored mode, collecting multibeam data in close proximity to the Q105.

B.1.2 Equipment

The following major systems were used for data acquisition during this survey:

Manufacturer	Model	Type
Teledyne RESON	SeaBat 7125 SV	MBES
Teledyne RESON	SeaBat 7101	MBES
Applanix	POS MV 320 v5	Positioning and Attitude System
Teledyne Oceanscience	rapidCAST	Sound Speed System
Valeport	rapidPro SVT	Sound Speed System

Table 6: Major Systems Used

Both survey vessels were outfit for MBES data collection with similar survey equipment. The ASV-CW5 was equipped with a Reson SeaBat 7125 MBES while the Q105 used a Reson SeaBat 7101 MBES. Both vessels used Applanix POSMV 320 V5 (Wavemaster II) units for attitude and position measurements. Sound speed profiles were collected using a Valeport rapidPro SVT sensor (deployed using a Teledyne Oceanscience RapidCast system) from the Q105 only.

B.2 Quality Control

B.2.1 Crosslines

Effort was made to ensure crosslines had good temporal and geographic distribution, were angled to enable nadir-to-nadir comparisons, and that the required minimum percent of mainscheme LNM was achieved.

Crosslines were conducted with both vessels to ensure there was ample overlap for inter-vessel comparisons, with each vessel crossing the other's mainscheme lines. Since the two vessels worked in close proximity and normally ran parallel lines, crosslines were often collected in sets whenever both vessels were in simultaneous operation. Crosslines were also occasionally collected while transiting across the survey area to reach a different survey priority such as bottom sample locations or infills, leading to crosslines that were diagonal to the direction of mainscheme lines.

The crossline analysis was conducted using CARIS HIPS “Line QC Report” process. Each crossline (with all associated file segments) was selected and run separately through the process, which calculated the depth difference between each accepted crossline sounding and a "QC" BASE (CUBE-type) surface’s depth layer created from the mainscheme data. The QC surface was created with the same parameters and resolution used for the final surface, with the important distinction that the QC surface did not include crosslines so as to not bias the results. Differences in depth were grouped by beam number and statistics were computed, including the percentage of soundings with differences from the QC surface falling within IHO Order 1a.

When at least 95% of the sounding differences exceed IHO Order 1a, the crossline was considered to “pass,” but when less than 95% of the soundings compare within IHO Order 1, the crossline was considered to “fail.” A 5% (or less) failure rate was considered acceptable since this approach compares soundings to a surface (instead of a surface to a surface), allowing for the possibility that noisy crossline soundings that don't adversely affect the final surface could be counted as a QC failure in this process.

Lines selected as crosslines and their percentage (%) of soundings passing IHO Order 1a, sorted from highest passing to lowest, are listed below.

0261-Q105-202-B5XL00000 -- 100.0% pass
0287-Q105-203-B2EW10400 -- 100.0% pass
0355-Q105-208-B_XL -- 100.0% pass
0552-Q105-229-BXL-01 -- 100.0% pass
0553-Q105-229-BXL-02 -- 100.0% pass
0554-Q105-229-BXL-03 -- 100.0% pass
0555-Q105-229-BXL-04 -- 100.0% pass
0557-Q105-229-BXL-06 -- 100.0% pass
0558-Q105-229-BXL-05 -- 100.0% pass
0560-Q105-229-BXL-07 -- 100.0% pass
0561-Q105-229-BXL-08 -- 100.0% pass
0562-Q105-229-BXL-09 -- 100.0% pass
0567-Q105-229-B8_XL2 -- 100.0% pass
0568-Q105-230-B8_XL3 -- 100.0% pass
0569-Q105-230-BXL-15 -- 100.0% pass
0570-Q105-230-BXL-15 -- 100.0% pass
0571-Q105-230-BXL-16 -- 100.0% pass
0572-Q105-230-BXL-17 -- 100.0% pass
0573-Q105-230-BXL-17 -- 100.0% pass
0575-Q105-230-BXL-18 -- 100.0% pass
0576-Q105-230-BXL-19 -- 100.0% pass
0565-ASV-CW5-202-B1EW07600 -- 100.0% pass
0636-ASV-CW5-205-B6EW10400 -- 100.0% pass
0663-ASV-CW5-208-B_XL -- 100.0% pass
0665-ASV-CW5-209-B3_XL -- 100.0% pass
1525-ASV-CW5-229-B8_XL1 -- 100.0% pass
1526-ASV-CW5-230-B8_XL4 -- 100.0% pass

Results: Agreement between the mainscheme surface and crossline soundings is excellent. For each crossline, at least 95% of the crossline soundings compare to the mainscheme surface within IHO Order 1a. None were considered to fail QC.

Refer to Separate II: Digital Data for the detailed Crossline QC reports.

B.2.2 Uncertainty

The following survey specific parameters were used for this survey:

Method	Measured	Zoning
ERS via ERTDM	0.13 meters	0 meters

Table 7: Survey Specific Tide TPU Values.

Hull ID	Measured - CTD	Measured - MVP	Surface
Q105	0.5 meters/second	N/A	.025 meters/second
ASV	0.5 meters/second	N/A	.025 meters/second

Table 8: Survey Specific Sound Speed TPU Values.

0.13 was provided and used as the uncertainty of the NOAA-provided ERTDM model. Refer to Appendix I for correspondence.

The uncertainty layer of the final surface was examined in CARIS HIPS. Uncertainty falls in the range of 0.261 to 0.439 m. Most grid cells are on the lower end of the uncertainty range, approximately 0.270 m. 100% of grid cells have uncertainty within allowable TVU for the depth.

B.2.3 Junctions

NOAA's "Gridded Surface Comparison V19.4" utility was used to complete the junction comparisons. The utility differences the surfaces from the junctioning surveys and generates statistics, including the percentage of grid cells that compare to within allowable TVU for the depth. 4 m-resolution CUBE surfaces were used for all comparisons.

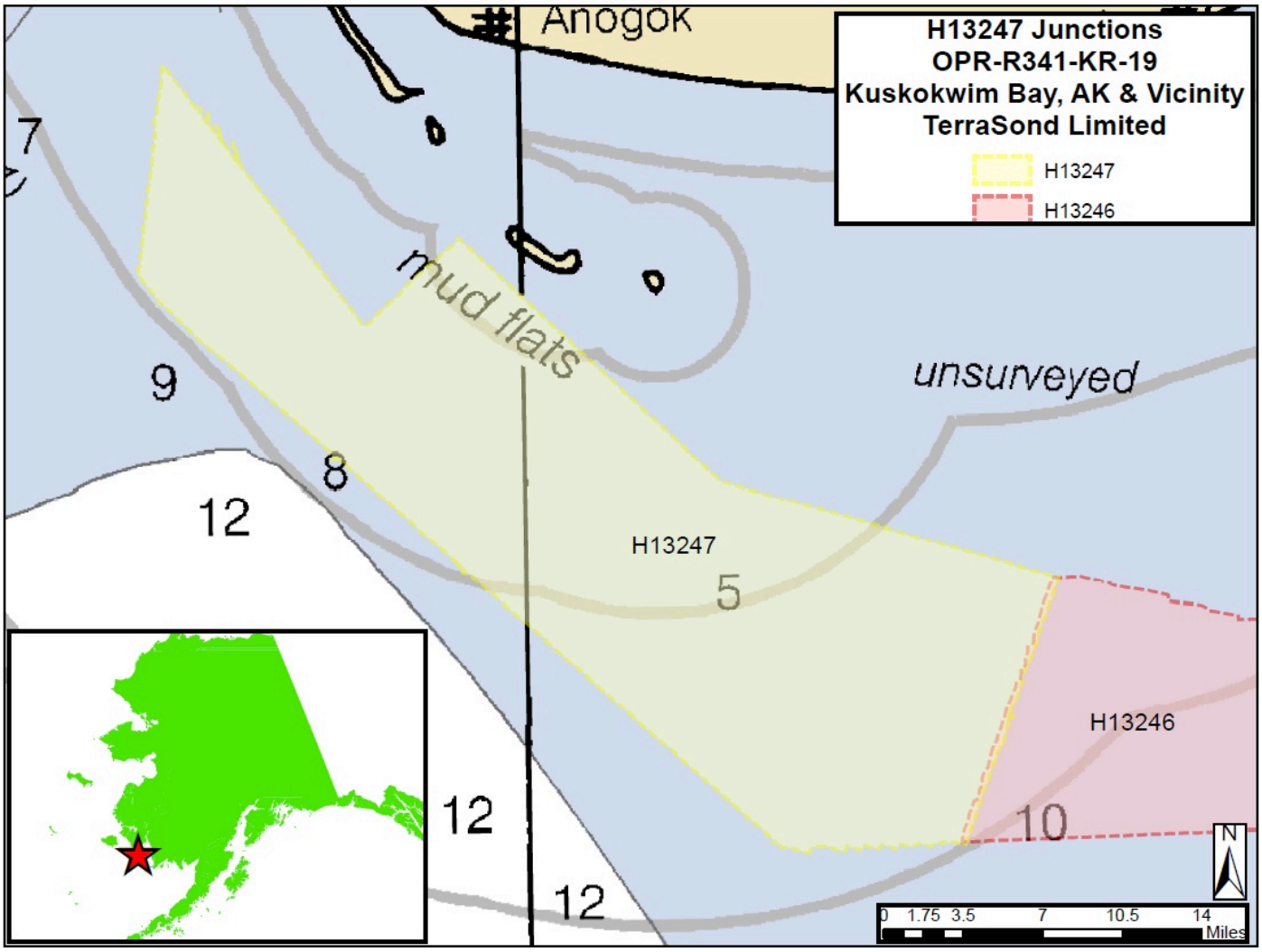

Figure 5: Image showing survey junctions.

The following junctions were made with this survey:

Registry Number	Scale	Year	Field Unit	Relative Location
H13246	1:40000	2019	Terrasond, Ltd.	E

Table 9: Junctioning Surveys

H13246

Agreement between the two surveys is excellent. The mean difference is 0.01 m with a standard deviation of 0.06 m. 100% of overlapping grid cells compare within the allowable TVU for the depth.

B.2.4 Sonar QC Checks

Sonar system quality control checks were conducted as detailed in the quality control section of the DAPR.

B.2.5 Equipment Effectiveness

POSMV Dropouts (ASV-CW5)

Approximately every 24 hours during survey operations the POSMV on the ASV-CW5 would drop offline. This was observed as sudden output of obviously erroneous data by the POSMV such as excessive vessel speeds, incorrect headings, and erroneous motion, followed by an automatic reinitialization of the POSMV. The issue would often repeat 1-2 additional times over a 5-10 minute period before resuming normal operations for an additional 24 hours. No definite cause was determined.

When this occurred the ASV-CW5 would break offline, note the issue in the acquisition log, circle back and proceed with rerunning the affected section of line. The affected section of line was subsequently rejected in processing. Since affected data was rejected and reran there is no adverse affect on final deliverables.

B.2.6 Factors Affecting Soundings

There were no other factors that affected corrections to soundings.

B.2.7 Sound Speed Methods

Sound Speed Cast Frequency: 2 hours

Sound speed profiles or "casts" were acquired aboard the Q105 while underway with a Teledyne Oceanscience RapidCAST system, which utilized a Valeport rapidPro SVT sound speed profiler.

Surface sound speed at the sonar head was monitored continuously and a new cast was collected when the surface speed varied from the previous profile's speed at the same depth by greater than 2 m/s, leading to a cast interval of approximately 2 hours.

Casts were taken as deep as possible. On survey lines with significant differences in depth, the deeper portion of the line was favored to ensure that changes across the full water column were measured.

The cast data was used to correct the sounding data for both vessels, using the "nearest in distance within time" (set to 4 hours) within CARIS HIPS.

B.2.8 Coverage Equipment and Methods

All equipment and survey methods were used as detailed in the DAPR.

B.2.9 GPS Vertical Busts

Vertical busts attributable to GPS positioning error between crosslines or overlapping mainscheme are apparent periodically in the data set. These are normally less than 0.15 m, with extreme cases showing up to 0.30 m of vertical separation. However, all crosslines--including those exhibiting or crossing areas exhibiting vertical busts--pass within IHO Order 1a, and final surfaces are within allowable TVU for the depth.

B.3 Echo Sounding Corrections

B.3.1 Corrections to Echo Soundings

Deviations from the Corrections to Echo Soundings section of the DAPR are itemized below. Note that in all cases final data is within specifications.

Delayed Heave Exceptions

The following lines could not have Delayed Heave loaded. This was usually due to a software crash or other issue causing logging to the associated POS file to cease early. Real-time heave was used instead during all processing phases including SVP correction, Compute GPS Tide, and Merge on these lines.

0029-ASV-CW5-182-B6EW07200_-_0002
0029-ASV-CW5-182-B6EW07200_-_0003
0030-ASV-CW5-182-B6EW07200_-_0001
0031-ASV-CW5-182-B6EW07200_-_0001
0038-ASV-CW5-182-B4EW09200_-_0004

0080-ASV-CW5-188-B6EW12800_-_0001
0081-ASV-CW5-188-B6EW12800_-_0001
0643-ASV-CW5-205-B7EW00800_-_0011
0590-ASV-CW5-204-B5EW01200_-_0004

GPS Height Smoothing

The following lines were loaded with GPS heights that had been smoothed to remove spikes and/or shortterm drifts using a 6-minute moving average. The smoothed GPS height data was loaded using CARIS' Generic Data Parser utility from text files at a rate of 1 Hz, which are included with the survey deliverables. Since the smoothing process removed heave data from the GPS record, the "Apply Dynamic Heave" option was set to "None" during computation of GPS Tide for these lines. More details are available in the DAPR.

0511-ASV-CW5-197-B6EW08800_-_0001
0511-ASV-CW5-197-B6EW08800_-_0002
0511-ASV-CW5-197-B6EW08800_-_0003
0511-ASV-CW5-198-B6EW08800_-_0004

Applanix Smart Base (ASB)

The following POS file was processed using Applanix Smart Base (ASB) instead of the project default PP-RTX to improve vertical matchup on a few lines, also listed below.

POS File:

2019-228-2348-ASV

Lines:

1516-ASV-CW5-229-B6EW12400_-_0002
1516-ASV-CW5-229-B6EW12400_-_0003
1517-ASV-CW5-229-B6EW12800_-_0001
1518-ASV-CW5-229-B6EW12400_-_0001

B.3.2 Calibrations

All sounding systems were calibrated as detailed in the DAPR.

B.4 Backscatter

All equipment and survey methods were used as detailed in the DAPR.

B.5 Data Processing

B.5.1 Primary Data Processing Software

The following Feature Object Catalog was used: NOAA Extended Attribute Files V2019.3.

NOAA Extended Attributes were used for the Final Feature File (FFF) submitted with the survey deliverables.

B.5.2 Surfaces

The following surfaces and/or BAGs were submitted to the Processing Branch:

Surface Name	Surface Type	Resolution	Depth Range	Surface Parameter	Purpose
H13247_MB_4m_MLLW_Final	CARIS Raster Surface (CUBE)	4 meters	0 meters - 80 meters	NOAA_4m	MBES Set Line Spacing
H13247_MBAB_1m_ASV_400kHz_1of2	MB Backscatter Mosaic	1 meters	0 meters - 80 meters	N/A	MBES Set Line Spacing
H13247_MBAB_1m_ASV_400kHz_2of2	MB Backscatter Mosaic	1 meters	0 meters - 80 meters	N/A	MBES Set Line Spacing
H13247_MBAB_1m_Q105_240kHz_1of2	MB Backscatter Mosaic	1 meters	0 meters - 80 meters	N/A	MBES Set Line Spacing
H13247_MBAB_1m_Q105_240kHz_2of2	MB Backscatter Mosaic	1 meters	0 meters - 80 meters	N/A	MBES Set Line Spacing

Table 10: Submitted Surfaces

The final depth information for this survey was submitted as a CARIS BASE surface (CSAR format) which best represented the seafloor at the time of the 2019 survey. The surface was created from fully processed data with all final corrections applied.

The surface was created using NOAA CUBE parameters and resolutions by depth range in conformance with the 2019 HSSD. The surface was finalized, and designated soundings were applied where applicable. Horizontal projection was selected as UTM Zone 3 North, NAD83.

A non-finalized versions of the CSAR surface is also included which does not have a depth cutoff applied. This does not have the "_Final" designation in the filename.

An S-57 (.000) Final Feature File (FFF) was submitted with the survey deliverables as well. The FFF contains data not readily represented by the final surface, including bottom samples and shoreline verification results (if any). Each object is encoded with mandatory S-57 attributes and NOAA Extended Attributes (V2019.3).

Georeferenced multibeam backscatter mosaics (Geotif format in NAD83 UTM Zone 3N, 1 m resolution) were also produced and are provided with the survey deliverables. Separate mosiacs were produced for each vessel. Note that backscatter processing and mosaic generation was not a requirement and the mosaics are provided as-is. The mosaics may have flaws or holidays which could be addressed through further processing. However, they are of sufficient quality to show the relative changes in seafloor type across the survey area.

C. Vertical and Horizontal Control

Additional information discussing the vertical or horizontal control for this survey can be found in the accompanying HVCR.

C.1 Vertical Control

The vertical datum for this project is Mean Lower Low Water.

ERS Datum Transformation

The following ellipsoid-to-chart vertical datum transformation was used:

Method	Ellipsoid to Chart Datum Separation File
ERS via ERTDM	R341KR2019_ERTDM_NAD83-MLLW

Table 11: ERS method and SEP file

All soundings were reduced to MLLW using the ERTDM NAD83 to MLLW separation model grid file provided by NOAA using ERS methodology.

Discrete tide zones were generated using project gauge data but were used for comparison purposes only.

A comparison between the provided ERTDM model and a ERZT model created using the tide zones was undertaken. There is generally good agreement between the models, with project-wide agreement averaging 0.033 m with a standard deviation of 0.271 m.

See the HVCR for additional information.

C.2 Horizontal Control

The horizontal datum for this project is North American Datum of 1983 (NAD 83).

The projection used for this project is Universal Transverse Mercator (UTM) Zone 3.

The following PPK methods were used for horizontal control:

- Smart Base
- RTX

The Trimble PP-RTX subscription-based correction service within POSPac was used for final positioning. Results were good overall, with RMS error usually at 0.10 m or better vertically. Applanix Smart Base (ASB) was used on a handful of lines to improve vertical agreement. These were itemized earlier in this report. Refer to the DAPR for additional detail.

RTK

The survey vessels were configured to receive RTK-level correctors via Hemisphere AtlasLink SBAS (L-band) receivers. This was utilized throughout the survey on the ASV-CW5 but only briefly at the start of operations on the Q105. However, all real-time correctors were superseded in processing with PPK correctors from Applanix POSPac. Refer to the DAPR for additional detail.

WAAS

The FAA Wide Area Augmentation System (WAAS) was used for real-time positioning on the Q105 for the majority of the survey. These positions were superseded in processing with PPK correctors from Applanix POSPac, as described in the DAPR.

D. Results and Recommendations

D.1 Chart Comparison

The chart comparison was performed by examining the best-scale Electronic Navigational Charts (ENCs) that intersect the survey area. The latest edition(s) available at the time of report compilation were used.

The chart comparison was accomplished by overlaying the finalized BASE surface(s) with shoal-biased soundings and the final feature file (FFF) on the charts in CARIS HIPS. The general agreement between charted soundings and survey soundings was then examined and a more detailed comparison was undertaken for any shoals or other dangerous features. In areas where a large scale chart overlapped with a small scale chart, only the larger scale chart was examined.

When comparing to survey data, chart scale was taken into account so that 1 mm at chart scale was considered to be the valid radius for charted soundings and features.

Results are shown in the following sections. It is recommended that in all cases of disagreement this survey should supersede charted data.

USCG Notice to Mariners (NM) and USCG Local Notice to Mariners (LNM) for District 17 from week 26/2019 through 34/2019 were checked and no items were found that affected the survey area.

Note that ENC metadata and non-specific geographic area objects on the ENCs that overlap the survey area were not investigated.

D.1.1 Electronic Navigational Charts

The following are the largest scale ENCs, which cover the survey area:

ENC	Scale	Edition	Update Application Date	Issue Date
US2AK95M	1:1534076	9	08/20/2018	10/16/2019

Table 12: Largest Scale ENCs

D.1.2 Shoal and Hazardous Features

No shoals or potentially hazardous features exist for this survey.

No DTONs were submitted for this survey.

D.1.3 Charted Features

No charted features exist for this survey.

D.1.4 Uncharted Features

No uncharted features exist for this survey.

D.1.5 Channels

No channels exist for this survey. There are no designated anchorages, precautionary areas, safety fairways, traffic separation schemes, pilot boarding areas, or channel and range lines within the survey limits.

D.2 Additional Results

D.2.1 Aids to Navigation

No Aids to navigation (ATONs) exist for this survey.

D.2.2 Maritime Boundary Points

No Maritime Boundary Points were assigned for this survey.

D.2.3 Bottom Samples

Four bottom samples were assigned via the PRF. Samples were obtained at all locations and returned primarily black sand.

Refer to the FFF submitted with the survey deliverables for results.

D.2.4 Overhead Features

No overhead features exist for this survey.

D.2.5 Submarine Features

No submarine features exist for this survey.

D.2.6 Platforms

No platforms exist for this survey.

D.2.7 Ferry Routes and Terminals

No ferry routes or terminals exist for this survey.

D.2.8 Abnormal Seafloor or Environmental Conditions

No abnormal seafloor and/or environmental conditions exist for this survey.

D.2.9 Construction and Dredging

No present or planned construction or dredging exist within the survey limits.

D.2.10 New Survey Recommendations

No new surveys or further investigations are recommended for this area.

D.2.11 ENC Scale Recommendations

No new insets are recommended for this area.

E. Approval Sheet

Field operations and data processing contributing to the completion of this survey were conducted under my direct supervision with frequent personal checks of progress, integrity, and adequacy.

This report, digital data, and all other accompanying records are approved. All records are hereby respectfully submitted for final review and acceptance.

The survey data meets or exceeds the requirements set forth in the 2019 NOS Hydrographic Surveys Specifications and Deliverables document as well as the Hydrographic Survey Project Instructions and Statement of Work. This data is adequate to supersede charted data in their common areas. This survey is complete and no additional work is required with the exception of deficiencies (if any) noted in this Descriptive Report.

Report Name	Report Date Sent
Survey Outlines	2019-09-10
MMO Training Logsheet and Observation Logs	2019-09-12
NCEI Sound Speed Data Submission	2019-09-12
Coast Pilot Report	2019-09-13
Tides and Water Levels Package - 9465419 Levelock	2019-11-15
Tides and Water Levels Package - 9465993 Ishkowik	2019-11-15
Tides and Water Levels Package - 9463502 Port Moller	2019-11-16
Tides and Water Levels Package - 9465203 Naknek	2019-11-18
Tides and Water Levels Package - 9465137 Cape Pierce	2019-11-19
Tides and Water Levels Package - 9465265 Kulukak Point	2019-11-20
Tides and Water Levels Package - AAAAAAA Cape Mendenhall	2019-11-23
Tides and Water Levels Package - BBBBBBB SW Kuskokwim Bay	2019-11-23
Tides and Water Levels Package - CCCCCCC Cape Corwin	2019-11-27

Approver Name	Approver Title	Approval Date	Signature
Andrew Orthmann, C.H.	TerraSond Charting Program Manager	12/14/2019	Andrew Orthmann Digitally signed by Andrew Orthmann Date: 2019.12.14 18:25:31 -09'00'

F. Table of Acronyms

Acronym	Definition
AHB	Atlantic Hydrographic Branch
AST	Assistant Survey Technician
ATON	Aid to Navigation
AWOIS	Automated Wreck and Obstruction Information System
BAG	Bathymetric Attributed Grid
BASE	Bathymetry Associated with Statistical Error
CO	Commanding Officer
CO-OPS	Center for Operational Products and Services
CORS	Continuously Operating Reference Station
CTD	Conductivity Temperature Depth
CEF	Chart Evaluation File
CSF	Composite Source File
CST	Chief Survey Technician
CUBE	Combined Uncertainty and Bathymetry Estimator
DAPR	Data Acquisition and Processing Report
DGPS	Differential Global Positioning System
DP	Detached Position
DR	Descriptive Report
DTON	Danger to Navigation
ENC	Electronic Navigational Chart
ERS	Ellipsoidal Referenced Survey
ERTDM	Ellipsoidally Referenced Tidal Datum Model
ERZT	Ellipsoidally Referenced Zoned Tides
FFF	Final Feature File
FOO	Field Operations Officer
FPM	Field Procedures Manual
GAMS	GPS Azimuth Measurement Subsystem
GC	Geographic Cell
GPS	Global Positioning System
HIPS	Hydrographic Information Processing System
HSD	Hydrographic Surveys Division

Acronym	Definition
HSSD	Hydrographic Survey Specifications and Deliverables
HSTB	Hydrographic Systems Technology Branch
HSX	Hypack Hysweep File Format
HTD	Hydrographic Surveys Technical Directive
HVCR	Horizontal and Vertical Control Report
HVF	HIPS Vessel File
IHO	International Hydrographic Organization
IMU	Inertial Motion Unit
ITRF	International Terrestrial Reference Frame
LNM	Linear Nautical Miles
MBAB	Multibeam Echosounder Acoustic Backscatter
MCD	Marine Chart Division
MHW	Mean High Water
MLLW	Mean Lower Low Water
NAD 83	North American Datum of 1983
NALL	Navigable Area Limit Line
NTM	Notice to Mariners
NMEA	National Marine Electronics Association
NOAA	National Oceanic and Atmospheric Administration
NOS	National Ocean Service
NRT	Navigation Response Team
NSD	Navigation Services Division
OCS	Office of Coast Survey
OMAO	Office of Marine and Aviation Operations (NOAA)
OPS	Operations Branch
MBES	Multibeam Echosounder
NWLON	National Water Level Observation Network
PDBS	Phase Differencing Bathymetric Sonar
PHB	Pacific Hydrographic Branch
POS/MV	Position and Orientation System for Marine Vessels
PPK	Post Processed Kinematic
PPP	Precise Point Positioning
PPS	Pulse per second

Acronym	Definition
PRF	Project Reference File
PS	Physical Scientist
RNC	Raster Navigational Chart
RTK	Real Time Kinematic
RTX	Real Time Extended
SBES	Singlebeam Echosounder
SBET	Smooth Best Estimate and Trajectory
SNM	Square Nautical Miles
SSS	Side Scan Sonar
SSSAB	Side Scan Sonar Acoustic Backscatter
ST	Survey Technician
SVP	Sound Velocity Profiler
TCARI	Tidal Constituent And Residual Interpolation
TPU	Total Propagated Uncertainty
USACE	United States Army Corps of Engineers
USCG	United States Coast Guard
UTM	Universal Transverse Mercator
XO	Executive Officer
ZDF	Zone Definition File

APPROVAL PAGE

H13247

Data meet or exceed current specifications as certified by the OCS survey acceptance review process. Descriptive Report and survey data except where noted are adequate to supersede prior surveys and nautical charts in the common area.

The following products will be sent to NCEI for archive

- Descriptive Report
- Collection of Bathymetric Attributed Grids (BAGs)
- Collection of backscatter mosaics
- Processed survey data and records
- Bottom Samples
- GeoPDF of survey product

The survey evaluation and verification has been conducted according current OCS Specifications, and the survey has been approved for dissemination and usage of updating NOAA's suite of nautical charts.

Digitally signed by HOLMBERG.PETER.SCOTT.1365886101
Date: 2021.07.22 08:42:43 -07'00'

Approved:_____

Pete Holmberg
Products Team Lead, Pacific Hydrographic Branch