U.S. Department of Commerce National Oceanic and Atmospheric Administration National Ocean Service			
	DESCRIPTIVE REPORT		
Type of Survey: Navigable Area			
Registry Number:	H13321		
	LOCALITY		
State(s):	State(s): Hawaii		
General Locality:	General Locality: Hawaiian Islands and Vicinity		
Sub-locality:	Sub-locality: Cape Kumukahi to Waipuku Point		
	2019		
	CHIEF OF PARTY Benjamin K. Evans, CAPT/NOAA		
LIBRARY & ARCHIVES			
Date:			

NATIO	U.S. DEPARTMENT OF COMMERCE NAL OCEANIC AND ATMOSPHERIC ADMINISTRATION	REGISTRY NUMBER:		
HYDROGR	APHIC TITLE SHEET	H13321		
INSTRUCTIONS: The Hydrographic Sheet should be accompanied by this form, filled in as completely as possible, when the sheet is forwarded to the Office.				
State(s):	Hawaii			
General Locality:	Hawaiian Islands and Vicinity			
Sub-Locality:	Cape Kumukahi to Waipuku Point			
Scale:	40000	40000		
Dates of Survey:	09/20/2019 to 09/22/2019			
Instructions Dated:	08/01/2019			
Project Number:	OPR-T383-RA-19			
Field Unit:	NOAA Ship Rainier			
Chief of Party:	Benjamin K. Evans, CAPT/NOAA			
Soundings by:	Multibeam Echo Sounder			
Imagery by:	Multibeam Echo Sounder Backscatter			
Verification by:	Pacific Hydrographic Branch	Pacific Hydrographic Branch		
Soundings Acquired in:	meters at Mean Lower Low Water			

#### Remarks:

Any revisions to the Descriptive Report (DR) applied during office processing are shown in red italic text. The DR is maintained as a field unit product, therefore all information and recommendations within this report are considered preliminary unless otherwise noted. The final disposition of survey data is represented in the NOAA nautical chart products. All pertinent records for this survey are archived at the National Centers for Environmental Information (NCEI) and can be retrieved via https://www.ncei.noaa.gov/. Products created during office processing were generated in NAD83 UTM 5N, MLLW. All references to other horizontal or vertical datums in this report are applicable to the processed hydrographic data provided by the field unit.

## **Table of Contents**

A. Area Surveyed	1
A.1 Survey Limits	1
A.2 Survey Purpose	2
A.3 Survey Quality	2
A.4 Survey Coverage	
A.6 Survey Statistics	5
B. Data Acquisition and Processing	7
B.1 Equipment and Vessels	7
B.1.1 Vessels	7
B.1.2 Equipment	10
B.2 Quality Control	10
B.2.1 Crosslines	
B.2.2 Uncertainty	
B.2.3 Junctions	15
B.2.4 Sonar QC Checks	15
B.2.5 Equipment Effectiveness	16
B.2.6 Factors Affecting Soundings	16
B.2.7 Sound Speed Methods	
B.2.8 Coverage Equipment and Methods	
B.2.9 Detect Fliers	
B.3 Echo Sounding Corrections	18
B.3.1 Corrections to Echo Soundings	
B.3.2 Calibrations	
B.4 Backscatter	18
B.5 Data Processing	
B.5.1 Primary Data Processing Software	
B.5.2 Surfaces	
C. Vertical and Horizontal Control	21
C.1 Vertical Control	21
C.2 Horizontal Control	21
D. Results and Recommendations	
D.1 Chart Comparison	
D.1.1 Electronic Navigational Charts	22
D.1.2 Shoal and Hazardous Features	22
D.1.3 Charted Features	
D.1.4 Uncharted Features	
D.1.5 Channels	22
D.2 Additional Results	23
D.2.1 Aids to Navigation	23
D.2.2 Maritime Boundary Points	23
D.2.3 Bottom Samples	23
D.2.4 Overhead Features	
D.2.5 Submarine Features	23

D.2.6 Platforms	
D.2.7 Ferry Routes and Terminals	
D.2.8 Abnormal Seafloor or Environmental Conditions	23
D.2.9 Construction and Dredging	24
D.2.10 New Survey Recommendations	25
D.2.11 ENC Scale Recommendations	25
E. Approval Sheet	
F. Table of Acronyms	

## **List of Tables**

Table 1: Survey Limits	1
Table 2: Survey Coverage	3
Table 3: Hydrographic Survey Statistics	6
Table 4: Dates of Hydrography	7
Table 5: Vessels Used	7
Table 6: Major Systems Used	10
Table 7: Survey Specific Tide TPU Values	
Table 8: Survey Specific Sound Speed TPU Values	14
Table 9: Primary bathymetric data processing software	20
Table 10: Primary imagery data processing software	
Table 11: Submitted Surfaces	
Table 12: ERS method and SEP file	
Table 13: Largest Scale ENCs	22

# List of Figures

Figure 1: H13321 assigned survey area (Chart 19320)	2
Figure 2: Pydro derived plot showing HSSD density compliance of H13321 finalized complete coverage	
variable-resolution MBES data	3
Figure 3: H13321 MBES coverage and assigned survey limits (Chart 19320)	4
Figure 4: Example of Navigable Area Limit Line (NALL) determination; the dashed line indicates assigned	d
sheet limits. Safety and time constraints prevented full coverage of the NALL	5
Figure 5: NOAA Ship RAINIER	8
Figure 6: Example of NOAA ship RAINIER survey launch	9
Figure 7: H13321 crossline surface overlaid on mainscheme tracklines	.11
Figure 8: Pydro derived plot showing node difference statistics of H13321 mainscheme to crossline	
data	12
Figure 9: Pydro derived plot showing absolute percentage pass value of H13321 mainscheme to crossline	
data	13
Figure 10: Pydro derived plot showing TVU compliance of H13321 complete coverage finalized variable	
resolution MBES data	15
Figure 11: H13321 sound speed cast locations	17

Figure	12: Overview of H13321 multibeam acoustic backscatter coverage (assigned sheet limits shown in	
green).		19
Figure	13: Example of abnormal seafloor in survey area H13321	24
$\mathcal{O}$		

## **Descriptive Report to Accompany Survey H13321**

Project: OPR-T383-RA-19 Locality: Hawaiian Islands and Vicinity Sublocality: Cape Kumukahi to Waipuku Point Scale: 1:40000 September 2019 - September 2019

## NOAA Ship Rainier

Chief of Party: Benjamin K. Evans, CAPT/NOAA

## A. Area Surveyed

The survey area is referred to as H13321, "Cape Kumukahi to Waipuku Point" (sheet 11) within the Project Instructions. The area encompasses approximately 57 square nautical miles off the eastern side of the "Big Island" of Hawaii.

## A.1 Survey Limits

Data were acquired within the following survey limits:

Northwest Limit	Southeast Limit
19° 33' 26" N	19° 19' 12" N
154° 56' 49" W	152° 42' 48" W

Table 1: Survey Limits

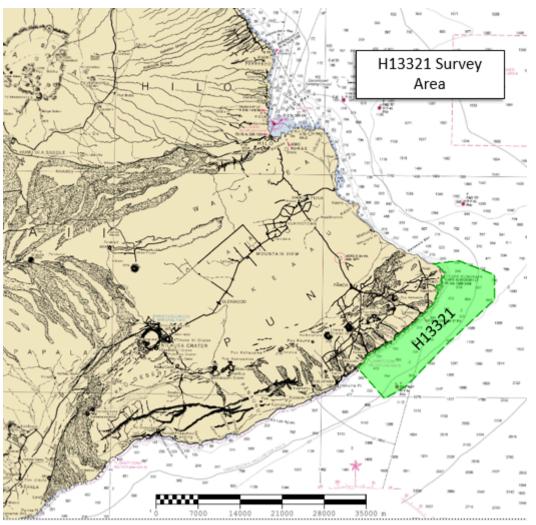


Figure 1: H13321 assigned survey area (Chart 19320).

Survey limits were acquired in accordance with the requirements in the Project Instructions and the HSSD.

## A.2 Survey Purpose

The 2018 eruption of Kilauea deposited lava into the ocean, significantly changing the coastline and seafloor on the eastern side of the big island. Due to the volcanic eruption altering the seafloor, new bathymetric data are required to update nautical charts for safe navigation. Survey data from this project are intended to supersede all prior survey data in the common area.

## A.3 Survey Quality

The entire survey is adequate to supersede previous data.

Pydro QC Tools was used to analyze H13321 multibeam echosounder (MBES) data density. The submitted H13321 variable-resolution (VR) surface met HSSD density requirements as shown in the histogram below.

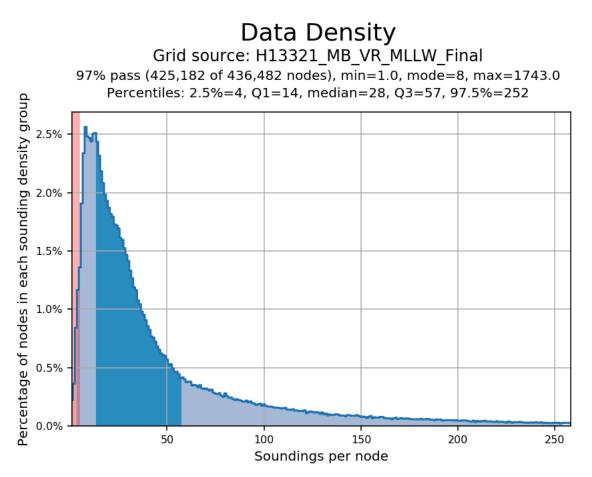


Figure 2: Pydro derived plot showing HSSD density compliance of H13321 finalized complete coverage variable-resolution MBES data.

## A.4 Survey Coverage

The following table lists the coverage requirements for this survey as assigned in the project instructions:

Water Depth	Coverage Required
All waters within survey area	Complete Coverage (Refer to HSSD Section 5.2.2.3)

#### Table 2: Survey Coverage

Multibeam echosounder (MBES) coverage was acquired to the Navigable Area Limit Line (NALL) in most places. The Project Instructions defined the NALL for this survey as 10-meter water depth. The survey vessels were operated as close to the new lava flow created shoreline as navigationally possible. Areas

NOAA Ship Rainier

where survey coverage did not reach 10-meters depths nor the assigned sheet limits were due to reaching the extent of safe navigation.

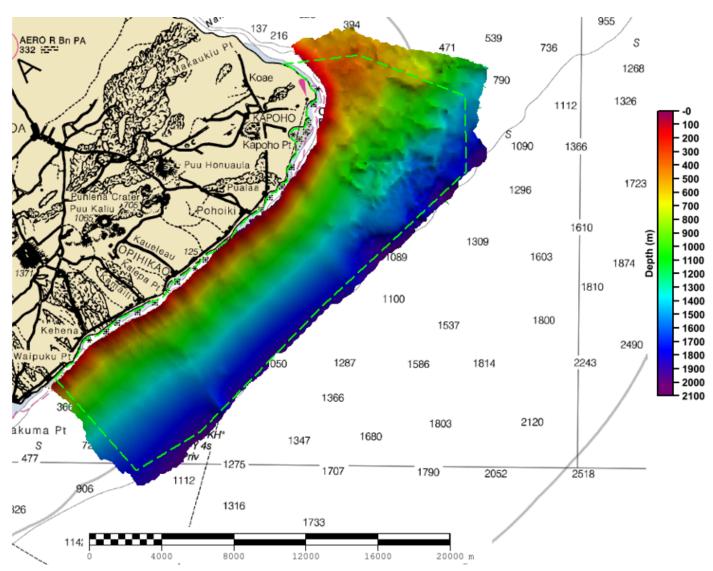
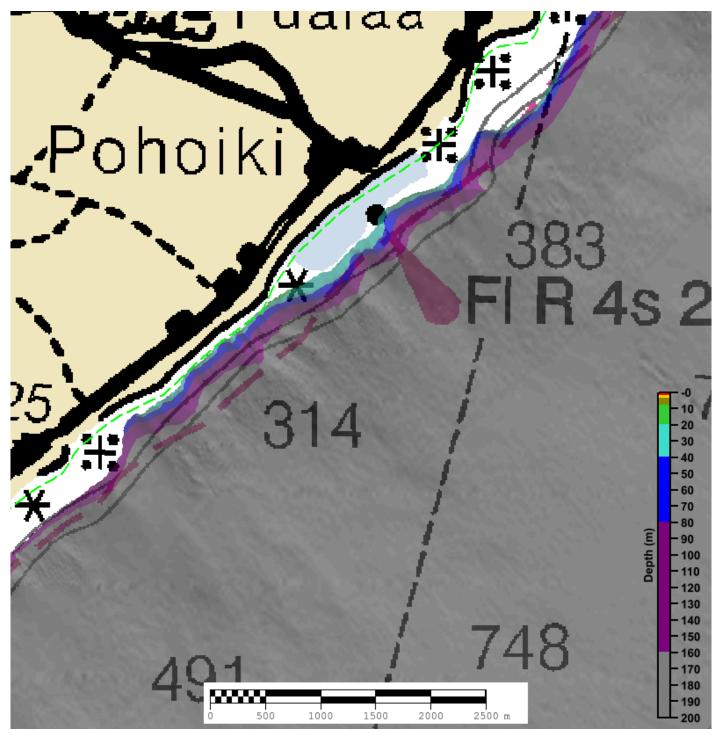


Figure 3: H13321 MBES coverage and assigned survey limits (Chart 19320).



*Figure 4: Example of Navigable Area Limit Line (NALL) determination; the dashed line indicates assigned sheet limits. Safety and time constraints prevented full coverage of the NALL.* 

## **A.6 Survey Statistics**

The following table lists the mainscheme and crossline acquisition mileage for this survey:

	HULL ID	S221	2804	Total
	SBES Mainscheme	0	0	0
	MBES Mainscheme	223.94	9.87	233.81
	Lidar Mainscheme	0	0	0
LNM	SSS Mainscheme	0	0	0
	SBES/SSS Mainscheme	0	0	0
	MBES/SSS Mainscheme	0	0	0
	SBES/MBES Crosslines	40.25	0	40.25
	Lidar Crosslines	0	0	0
Numb Botton	er of n Samples			0
	er Maritime ary Points igated			0
Number of DPs				0
1	er of Items igated by Dps			0
Total S	SNM			65.74

Table 3: Hydrographic Survey Statistics

The following table lists the specific dates of data acquisition for this survey:

Survey Dates	Day of the Year
09/20/2019	263
09/22/2019	265

Table 4: Dates of Hydrography

## **B.** Data Acquisition and Processing

## **B.1** Equipment and Vessels

Refer to the Data Acquisition and Processing Report (DAPR) for a complete description of data acquisition and processing systems, survey vessels, quality control procedures and data processing methods. Additional information to supplement sounding and survey data, and any deviations from the DAPR are discussed in the following sections.

### **B.1.1 Vessels**

The following vessels were used for data acquisition during this survey:

Hull ID	S221	2804
LOA	70.4 meters	8.8 meters
Draft	5.7 meters	1.1 meters

Table 5: Vessels Used



Figure 5: NOAA Ship RAINIER.



Figure 6: Example of NOAA ship RAINIER survey launch.

All H13321 data were acquired by NOAA Ship RAINIER and survey launch 2804 (RA-6). These vessels acquired depth soundings, backscatter imagery and sound speed profiles. Water column data were logged by RAINIER concurrently with multibeam as .WCD files on days 263 and 265. Limited shoreline verification was conducted from NOAA Ship RAINIER and launch 2804 (RA-6).

## **B.1.2 Equipment**

Manufacturer	Model	Туре
Applanix	POS MV 320 v5	Positioning and Attitude System
Kongsberg Maritime	EM 710	MBES
Kongsberg Maritime	EM 2040	MBES
AML Oceanographic	Micro-CTD	Conductivity, Temperature, and Depth Sensor
Sea-Bird Scientific	SBE 19plus	Conductivity, Temperature, and Depth Sensor
ODIM Brooke Ocean	MVP200	Sound Speed System
Teledyne RESON	SVP 70	Sound Speed System

The following major systems were used for data acquisition during this survey:

#### Table 6: Major Systems Used

Refer to the Data Acquisition and Processing Report (DAPR) for a comprehensive description of data acquisition and processing systems, survey vessels, quality control and processing methods. Additional information to supplement soundings and other survey data and any deviations from the DAPR are discussed in this report.

## **B.2 Quality Control**

### **B.2.1** Crosslines

NOAA Ship RAINIER acquired 40.25 nautical miles of multibeam crosslines. H13321 crossline data is adequate for verifying and evaluating the internal consistency of survey data. The Compare Grids function in Pydro Explorer analyzed finalized VR surfaces of H13321 crossline-only and mainscheme-only data. In the different surface, 99.5% of nodes met IHO allowable Total Vertical Uncertainty (TVU) standards. Figures 7-9 provide additional results.

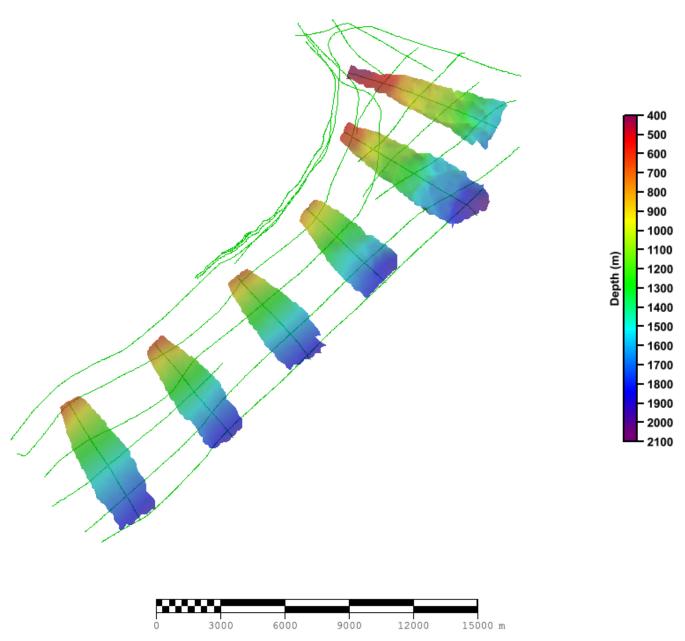
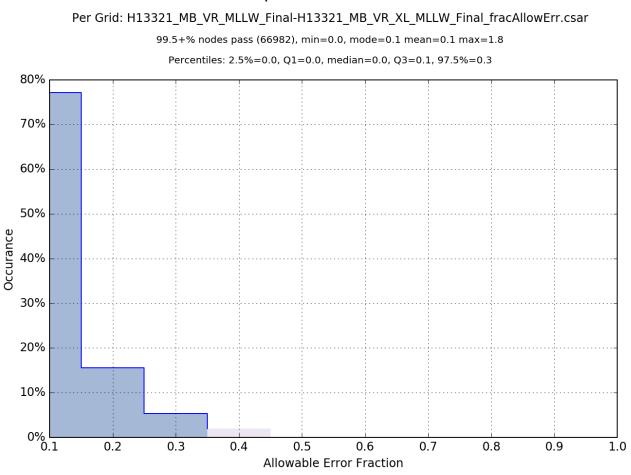


Figure 7: H13321 crossline surface overlaid on mainscheme tracklines.



## **Comparison Distribution**

Figure 8: Pydro derived plot showing node difference statistics of H13321 mainscheme to crossline data.

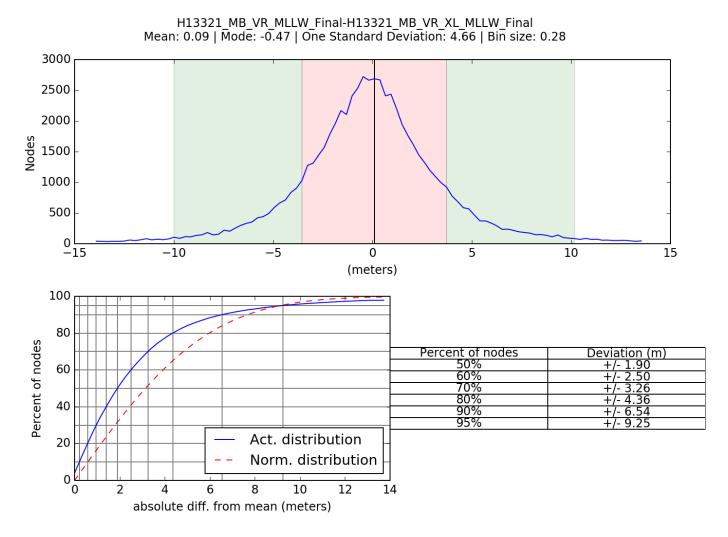


Figure 9: Pydro derived plot showing absolute percentage pass value of H13321 mainscheme to crossline data.

### **B.2.2 Uncertainty**

The following survey specific parameters were used for this survey:

Method	Measured	Zoning
ERS via ERTDM	ERS via ERTDM 0 meters	

Table 7: Survey Specific Tide TPU Values.

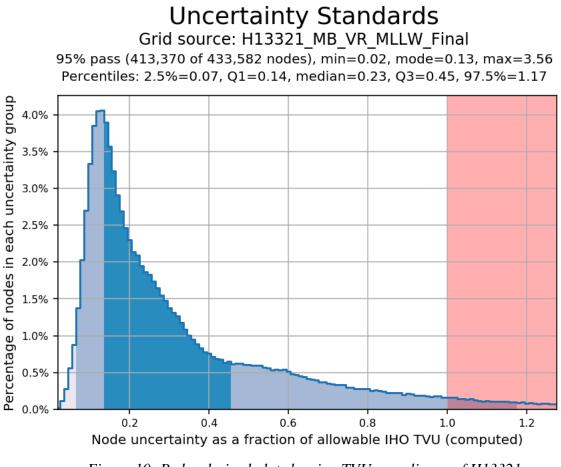
Hull ID	Measured - CTD	Measured - MVP	Measured - XBT	Surface
S221	N/A meters/second	1 meters/second	N/A meters/second	0.05 meters/second
2804	3 meters/second	N/A meters/second	N/A meters/second	0.05 meters/second

Table 8: Survey Specific Sound Speed TPU Values.

We derived Total Propagated Uncertainty (TPU) values for H13321 based on a combination of equipment specifications and capabilities, and vessel characteristics. The tidal uncertainty used for this survey was provided in the project instructions for the NOAA Ellipsoidal Referenced Tidal Datum Model (ERTDM).

In addition, we incorporated real-time and post-processed uncertainty sources into the depth estimates of this survey. The real-time uncertainties for position, navigation, attitude, and vessel motion data were applied during acquisition and initially in post-processing. Then, we used POSPac MMS software to generate SBET and RMS files with attitude, GPS height, and position uncertainties, which supersede real-time POS MV data when applied in CARIS HIPS.

Uncertainty values of the submitted finalized grid were calculated in CARIS using "Greater of the Two" of uncertainty and standard deviation (scaled to 95%). Grid QA v5 within Pydro QC Tools was used to analyze H13321 TVU compliance. H13321 met HSSD requirements in over 99.5 percent of grid nodes, which is shown in the histogram plot below."



*Figure 10: Pydro derived plot showing TVU compliance of H13321 complete coverage finalized variable resolution MBES data.* 

### **B.2.3 Junctions**

There are no contemporary surveys that junction with this survey.

## **B.2.4 Sonar QC Checks**

Sonar system quality control checks were conducted as detailed in the quality control section of the DAPR.

### **B.2.5 Equipment Effectiveness**

There were no conditions or deficiencies that affected equipment operational effectiveness.

### **B.2.6 Factors Affecting Soundings**

There were no other factors that affected corrections to soundings.

#### **B.2.7 Sound Speed Methods**

Sound Speed Cast Frequency: A total of 18 sound speed profiles were acquired for this survey at discrete locations within the survey area at least once every four hours. S221 sound speed profiles were acquired using ODIM Brooke Ocean MVP200. Launch sound speed profiles were acquired using Sea-Bird Scientific SBE 19 plus profilers. All casts were concatenated into a master file and applied using the "Nearest in distance within time (4 hours)" profile selection method within CARIS.

Three casts were extended in the concatenated master file by selecting sections of a nearby cast that had been extended in Sound Speed Manager and adding the data to supplement sound speed profiles in deeper water.

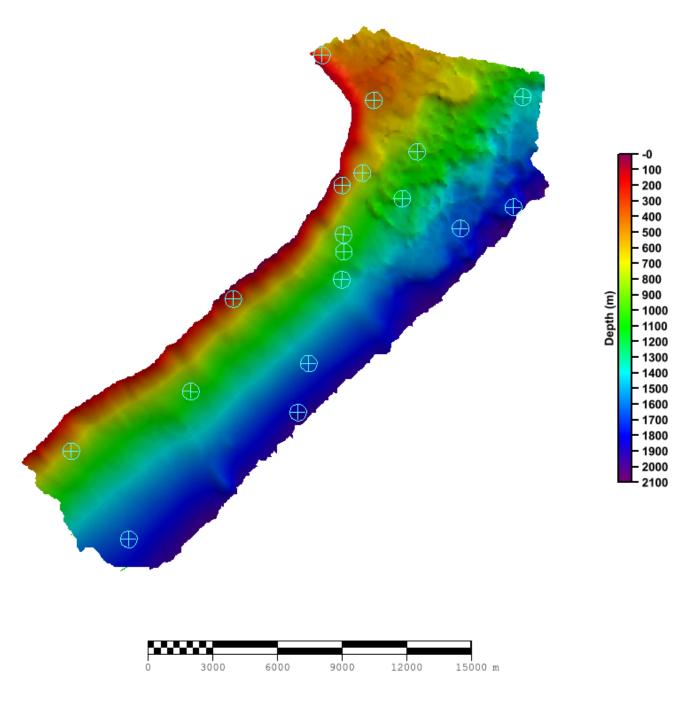


Figure 11: H13321 sound speed cast locations.

## **B.2.8** Coverage Equipment and Methods

All equipment and survey methods were used as detailed in the DAPR.

## **B.2.9 Detect Fliers**

Pydro QC Tools Flier Finder v8 was used to find fliers in the finalized variable resolution surface. Flier Finder settings: Checks included #2: Gaussian Curvature, #3: Adjacent Cells, #4: Edge Slivers, and #5: Isolated Nodes; Filters were defined as Distance  $\leq 1.0$  nodes and Delta Z  $\leq 0.01$  meters. "Features from S57 File" and "Designated (SR BAG only)" were not used. Flier height was not restricted. Obvious noise was rejected by the hydrographer in CARIS subset editor. After data cleaning, Flier Finder was run again and found 86 fliers in the surface. These fliers are a result of low data density at extreme depths and steep slopes in changing bathymetry.

## **B.3 Echo Sounding Corrections**

## **B.3.1** Corrections to Echo Soundings

All data reduction procedures conform to those detailed in the DAPR.

### **B.3.2** Calibrations

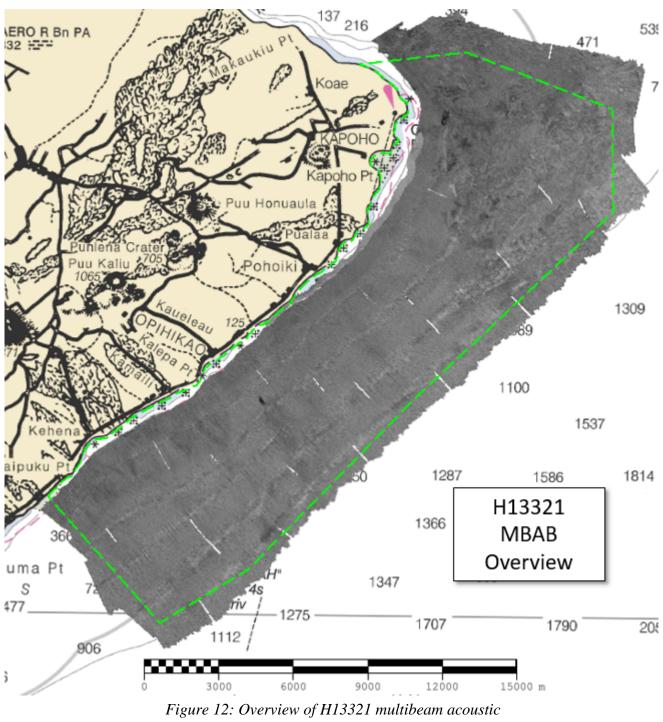
All sounding systems were calibrated as detailed in the DAPR.

## **B.4 Backscatter**

Raw backscatter data were acquired as .all files logged during MBES operations and processed by RAINIER personnel. Multiple gaps are present in the backscatter data are due to 20 minute automated line breaks during MBES acquisition. The .GSF files created during processing and one backscatter mosaic per vessel per frequency has been delivered with this report. Backscatter processing procedures are described in the DAPR. Line 0022\_20190921\_015329\_Rainier\_Deep\_263\_merged.gsf was not processed in a mosaic due to an internal error and does not impact the quality of the mosaic.

H13321

NOAA Ship Rainier



backscatter coverage (assigned sheet limits shown in green).

## **B.5 Data Processing**

## **B.5.1 Primary Data Processing Software**

The following software program was the primary program used for bathymetric data processing:

Manufacturer	Name	Version
CARIS	HIPS and SIPS	11.1.03

Table 9: Primary bathymetric data processing software

The following software program was the primary program used for imagery data processing:

Manufacturer	Ianufacturer Name Version	
QPS	Fledermaus Geocoder Toolkit (FMGT)	7.8.1

Table 10: Primary imagery data processing software

The following Feature Object Catalog was used: NOAA Profile Version 2019.

#### **B.5.2 Surfaces**

The following surfaces and/or BAGs were submitted to the Processing Branch:

Surface Name	Surface Type	Resolution	Depth Range	Surface Parameter	Purpose
H13321_MB_VR_MLLW	CARIS VR Surface (CUBE)	Variable Resolution	9.52 meters - 2084.51 meters	NOAA_VR	Complete MBES
H13321_MB_VR_MLLW_Final	CARIS VR Surface (CUBE)	Variable Resolution	9.52 meters - 2084.51 meters	NOAA_VR	Complete MBES

Table 11: Submitted Surfaces

Submitted Surfaces were generated using the NOAA recommended parameters for depth-based (Ranges) CARIS variable-resolution bathymetric grids as specified in 2019 HSSD.

Due to the extreme range of survey data, the surface did not meet resolution requirements for variable resolution surfaces in the shallower portions of this survey, per HSSD 5.2.2.3. Upon review it does not appear to impact the integrity or the feature detection ability of this survey and does not pose a danger to surface navigation.

## **C. Vertical and Horizontal Control**

Additional information discussing the vertical and horizontal control for this survey can be found in the accompanying 2019 DAPR.

## **C.1 Vertical Control**

The vertical datum for this project is Mean Lower Low Water.

#### ERS Datum Transformation

The following ellipsoid-to-chart vertical datum transformation was used:

Method	Ellipsoid to Chart Datum Separation File	
ERS via ERTDM	OPR-T383-	
	RA-19_ERTDM_NAD83(2011)_MLLW_Extended2.csar	

Table 12: ERS method and SEP file

## **C.2 Horizontal Control**

The horizontal datum for this project is North American Datum of 1983 (NAD 83).

The projection used for this project is Universal Transverse Mercator (UTM) Zone 5.

The following PPK methods were used for horizontal control:

• RTX

### WAAS

The Wide Area Augmentation System (WAAS) was used for real-time horizontal control during data acquisition. Post Processed-Real-Time Extended (PP-RTX) processing methods were used in Applanix POSPac MMS 8.3 software to produce SBETs for post-processed horizontal and vertical corrections.

## **D. Results and Recommendations**

## **D.1 Chart Comparison**

A comparison was made between H13321 survey data and Electronic Navigational Chart (ENC) US US3HA10M using a CUBE surface, selected soundings and contours created in CARIS.

### **D.1.1 Electronic Navigational Charts**

The following are the largest scale ENCs, which cover the survey area:

ENC	Scale	Edition	Update Application Date	Issue Date
US3HA10M	1:250000	17	07/20/2018	08/30/2019

#### Table 13: Largest Scale ENCs

#### **D.1.2 Shoal and Hazardous Features**

No shoals or potentially hazardous features exist for this survey.

### **D.1.3 Charted Features**

No charted features exist for this survey.

### **D.1.4 Uncharted Features**

No uncharted features exist for this survey.

### **D.1.5** Channels

No channels exist for this survey. There are no designated anchorages, precautionary areas, safety fairways, traffic separation schemes, pilot boarding areas, or channel and range lines within the survey limits.

## **D.2 Additional Results**

### **D.2.1** Aids to Navigation

Along the Puna Coast there is a privately maintained buoy; its position and status appear to be properly depicted on the chart. There is also a charted daymarker along the shoreline that was not observed. Further information regarding ATONs within the survey area is included in the H13321 Final Feature Files submitted with this report.

### **D.2.2 Maritime Boundary Points**

No Maritime Boundary Points were assigned for this survey.

### **D.2.3 Bottom Samples**

No bottom samples were required for this survey.

### **D.2.4 Overhead Features**

No overhead features exist for this survey.

### **D.2.5 Submarine Features**

No submarine features exist for this survey.

### **D.2.6 Platforms**

No platforms exist for this survey.

### **D.2.7 Ferry Routes and Terminals**

No ferry routes or terminals exist for this survey.

## **D.2.8** Abnormal Seafloor or Environmental Conditions

Nearly the entire seafloor within H13321 exhibits evidence of volcanic activity thus creating a dynamic seafloor with features of potential interest to researchers in the fields of marine geology, volcanology, benthic ecology and more.

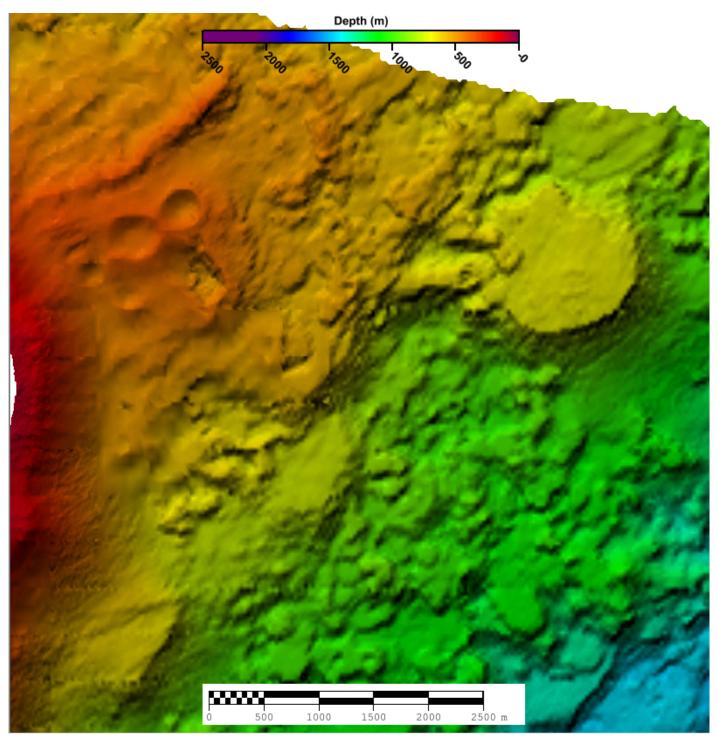


Figure 13: Example of abnormal seafloor in survey area H13321.

## **D.2.9** Construction and Dredging

No present or planned construction or dredging exist within the survey limits.

## **D.2.10 New Survey Recommendations**

No new surveys or further investigations are recommended for this area.

## **D.2.11 ENC Scale Recommendations**

No new insets are recommended for this area.

## E. Approval Sheet

As Chief of Party, field operations for this hydrographic survey were conducted under my direct supervision, with frequent personal checks of progress and adequacy. I have reviewed the attached survey data and reports.

All field sheets, this Descriptive Report, and all accompanying records and data are approved. All records are forwarded for final review and processing to the Processing Branch.

The survey data meets or exceeds requirements as set forth in the NOS Hydrographic Surveys Specifications and Deliverables, Field Procedures Manual, Letter Instructions, and all HSD Technical Directives. These data are adequate to supersede charted data in their common areas. This survey is complete and no additional work is required with the exception of deficiencies noted in the Descriptive Report.

Approver Name	Approver Title	Approval Date	Signature
Samuel F. Greenaway CDR/NOAA	Commanding Officer	02/24/2020	Digitally signed by GREENAWAY.SAMUEL.F.127 5635347 Date: 2020.02.24 12:12:11 -08'00'
Hadley A. Owen LT/NOAA	Field Operations Officer	02/24/2020	Digitally signed by OWEN.HADLEY.ANNE.141 0967070 Date: 2020.02.24 11:42:17 -08'00'
James B. Jacobson	Chief Survey Technician	02/24/2020	JACOBSONJAMES.BRYAN.12 69664017 Journal Journal Hove reviewed this document 2020.02.24 12:10:21 -08'00'
Christina L. Brooks	Assistant Survey Technician	02/24/2020	BROOKS.CHRISTINA.LOR RAINE.1553513177 2020.02.24 11:23:37 -08'00'

## F. Table of Acronyms

Acronym	Definition
AHB	Atlantic Hydrographic Branch
AST	Assistant Survey Technician
ATON	Aid to Navigation
AWOIS	Automated Wreck and Obstruction Information System
BAG	Bathymetric Attributed Grid
BASE	Bathymetry Associated with Statistical Error
СО	Commanding Officer
CO-OPS	Center for Operational Products and Services
CORS	Continuously Operating Reference Station
CTD	Conductivity Temperature Depth
CEF	Chart Evaluation File
CSF	Composite Source File
CST	Chief Survey Technician
CUBE	Combined Uncertainty and Bathymetry Estimator
DAPR	Data Acquisition and Processing Report
DGPS	Differential Global Positioning System
DP	Detached Position
DR	Descriptive Report
DTON	Danger to Navigation
ENC	Electronic Navigational Chart
ERS	Ellipsoidal Referenced Survey
ERTDM	Ellipsoidally Referenced Tidal Datum Model
ERZT	Ellipsoidally Referenced Zoned Tides
FFF	Final Feature File
FOO	Field Operations Officer
FPM	Field Procedures Manual
GAMS	GPS Azimuth Measurement Subsystem
GC	Geographic Cell
GPS	Global Positioning System
HIPS	Hydrographic Information Processing System
HSD	Hydrographic Surveys Division

Acronym	Definition
HSSD	Hydrographic Survey Specifications and Deliverables
HSTB	Hydrographic Systems Technology Branch
HSX	Hypack Hysweep File Format
HTD	Hydrographic Surveys Technical Directive
HVCR	Horizontal and Vertical Control Report
HVF	HIPS Vessel File
ІНО	International Hydrographic Organization
IMU	Inertial Motion Unit
ITRF	International Terrestrial Reference Frame
LNM	Linear Nautical Miles
MBAB	Multibeam Echosounder Acoustic Backscatter
MCD	Marine Chart Division
MHW	Mean High Water
MLLW	Mean Lower Low Water
NAD 83	North American Datum of 1983
NALL	Navigable Area Limit Line
NTM	Notice to Mariners
NMEA	National Marine Electronics Association
NOAA	National Oceanic and Atmospheric Administration
NOS	National Ocean Service
NRT	Navigation Response Team
NSD	Navigation Services Division
OCS	Office of Coast Survey
OMAO	Office of Marine and Aviation Operations (NOAA)
OPS	Operations Branch
MBES	Multibeam Echosounder
NWLON	National Water Level Observation Network
PDBS	Phase Differencing Bathymetric Sonar
РНВ	Pacific Hydrographic Branch
POS/MV	Position and Orientation System for Marine Vessels
РРК	Post Processed Kinematic
PPP	Precise Point Positioning
PPS	Pulse per second

Acronym	Definition
PRF	Project Reference File
PS	Physical Scientist
RNC	Raster Navigational Chart
RTK	Real Time Kinematic
RTX	Real Time Extended
SBES	Singlebeam Echosounder
SBET	Smooth Best Estimate and Trajectory
SNM	Square Nautical Miles
SSS	Side Scan Sonar
SSSAB	Side Scan Sonar Acoustic Backscatter
ST	Survey Technician
SVP	Sound Velocity Profiler
TCARI	Tidal Constituent And Residual Interpolation
TPU	Total Propagated Uncertainty
USACE	United States Army Corps of Engineers
USCG	United States Coast Guard
UTM	Universal Transverse Mercator
XO	Executive Officer
ZDF	Zone Definition File