U.S. Department of Commerce National Oceanic and Atmospheric Administration National Ocean Service		
	DESCRIPTIVE REPORT	
Type of Survey:	Navigable Area	
Registry Number:	H13467	
	LOCALITY	
State(s):	Wisconsin	
General Locality:	Green Bay, WI	
Sub-locality:	Entrance to Fox River	
	2021	
CHIEF OF PARTY David Neff, C.H.		
LIBRARY & ARCHIVES		
Date:		

NATIO	U.S. DEPARTMENT OF COMMERCE NAL OCEANIC AND ATMOSPHERIC ADMINISTRATION	REGISTRY NUMBER:	
HYDROGRAPHIC TITLE SHEET H13467			
INSTRUCTIONS: The	Hydrographic Sheet should be accompanied by this form, filled in as completely as possib	ble, when the sheet is forwarded to the Office.	
State(s):	Wisconsin		
General Locality:	Green Bay, WI		
Sub-Locality:	Entrance to Fox River		
Scale:	10000		
Dates of Survey:	06/09/2021 to 08/17/2021		
Instructions Dated:	04/26/2021		
Project Number:	OPR-Y390-KR-21		
Field Unit:	eTrac		
Chief of Party:	David Neff, C.H.		
Soundings by:	Multibeam Echo Sounder		
Imagery by:	Multibeam Echo Sounder Backscatter		
Verification by:	Atlantic Hydrographic Branch	Atlantic Hydrographic Branch	
Soundings Acquired in:	meters at Low Water Datum IGLD-1985		

Remarks:

All times are UTC. The purpose of this survey is to update existing NOS nautical charts. H13467 covers approximately 27 square nautical miles in the entrance to Fox River, Wisconsin.

Any revisions to the Descriptive Report (DR) applied during office processing are shown in red italic text. The DR is maintained as a field unit product, therefore all information and recommendations within this report are considered preliminary unless otherwise noted. The final disposition of survey data is represented in the NOAA nautical chart products. All pertinent records for this survey are archived at the National Centers for Environmental Information (NCEI) and can be retrieved via https://www.ncei.noaa.gov/. Products created during office processing were generated in NAD83 UTM 16N, IGLD Low Water Datum. All references to other horizontal or vertical datums in this report are applicable to the processed hydrographic data provided by the field unit.

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# **Descriptive Report to Accompany Survey H13467**

Project: OPR-Y390-KR-21 Locality: Green Bay, WI Sublocality: Entrance to Fox River Scale: 1:10000 June 2021 - August 2021 **eTrac** 

Chief of Party: David Neff, C.H.

# A. Area Surveyed

eTrac Inc. conducted hydrographic survey operations in the entrance to Fox River, Wisconsin. H13467 covers approximately 27 square nautical miles of survey area. 1790.39 linear nautical miles were acquired during the survey.

Survey was conducted within these limits between June 09, 2020 (DN160) and August 17, 2020 (DN229).

# A.1 Survey Limits

Data were acquired within the following survey limits:

Northwest Limit	Southeast Limit
44° 45' 16.45" N	44° 32' 19.75" N
88° 1' 11.66" W	87° 46' 5.65" W

Table 1: Survey Limits

H13467

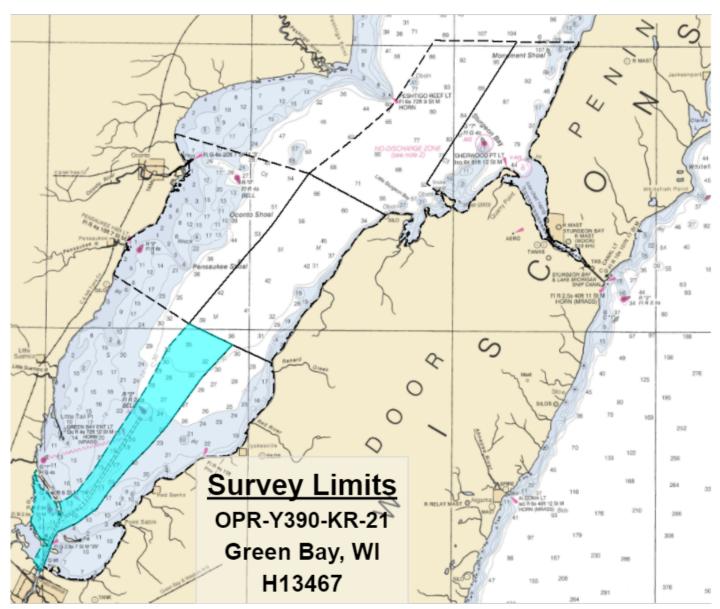


Figure 1: Survey Limits Overview (light blue area)

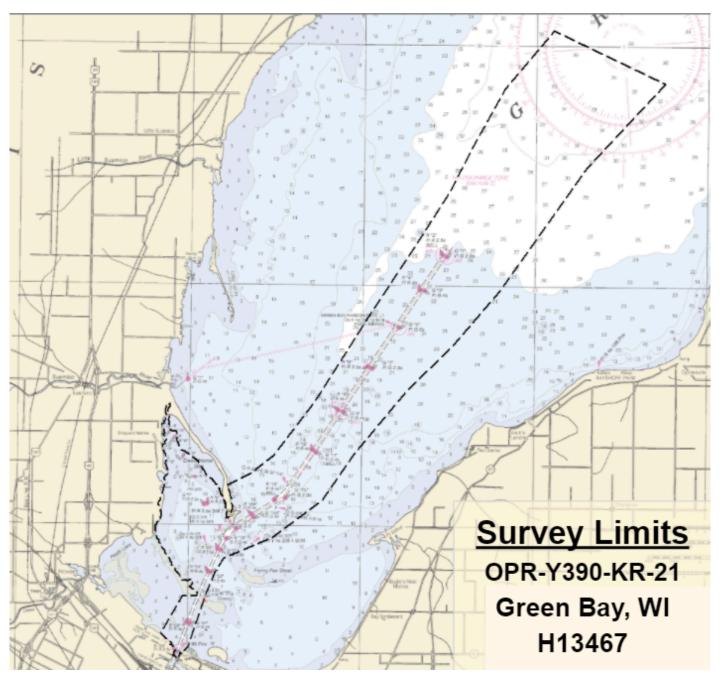


Figure 2: Survey Limits (black line)

All data were acquired in accordance with the requirements in the Project Instructions and specifications set forth in the Hydrographic Survey Specifications and Deliverables 2021 Edition (HSSD 2021).

# A.2 Survey Purpose

The purpose of this survey is to update existing National Ocean Service (NOS) nautical charts.

## A.3 Survey Quality

The entire survey is adequate to supersede previous data.

Survey H13467 is accurate to International Hydrographic Organization (IHO) Order 1a as required per the HSSD 2021.

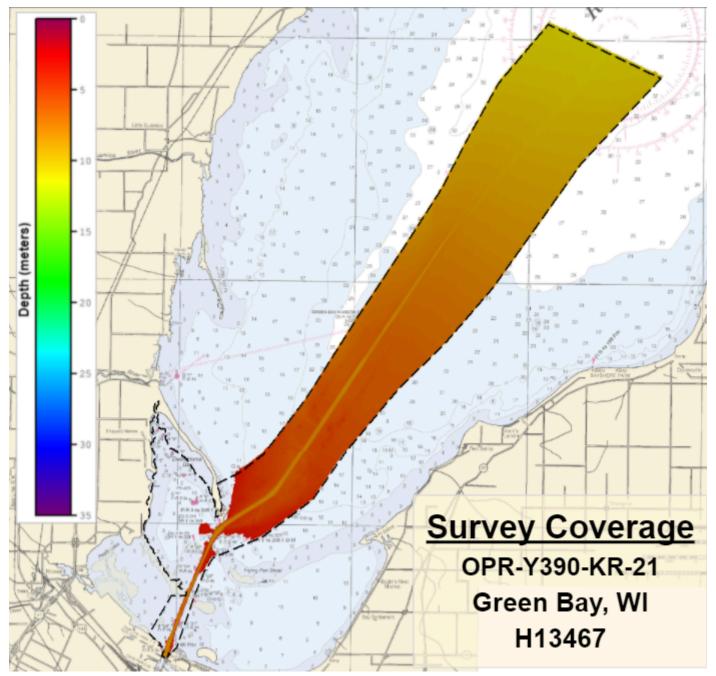
# A.4 Survey Coverage

The following table lists the coverage requirements for this survey as assigned in the project instructions:

Water Depth	Coverage Required	
All water in survey area	Complete 8370 LNM. Transit mileage, system calibration mileage and data which do not meet HSSD specifications shall not count towards the completion of the LNM requirement. Notify the COR/Project Manager upon nearing completion of LNM requirement. The final survey area shall be squared off and ensure the full investigation of any features within the surveyed extent.	
Sheets 1, 4, 6, and 7	Complete Coverage (Refer to HSSD Section 5.2.2.3)	

Table 2: Survey Coverage

Survey coverage was in accordance with the requirements listed above and in the HSSD. Note: Survey coverage did not extend to the entire assigned survey boundary as the Navigable Area Limit Line (NALL) was reached.



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Figure 3: Survey Coverage

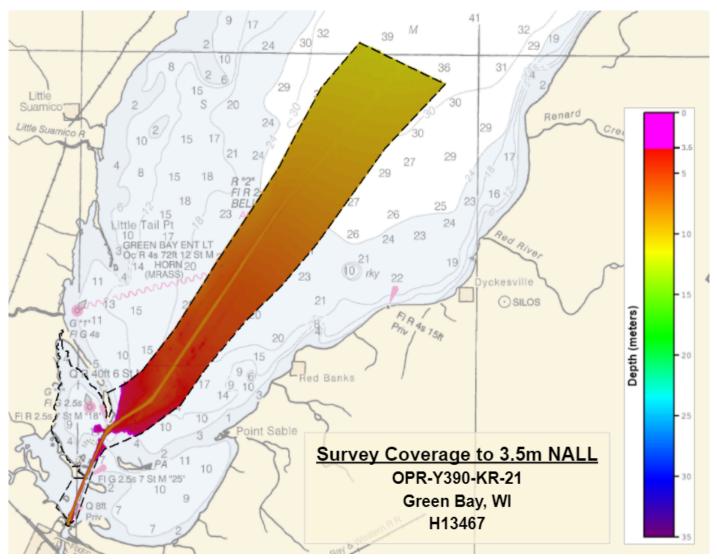


Figure 4: Survey Coverage with 3.5m NALL displayed

# A.6 Survey Statistics

The following table lists the mainscheme and crossline acquisition mileage for this survey:

	HULL ID	R/V Endeavor	R/V Rapid	R/V Voxel	Total
	SBES Mainscheme	0	0	0	0
	MBES Mainscheme	804.63	881.19	28.71	1714.5
	Lidar Mainscheme	0	0	0	0
LNM	SSS Mainscheme	0	0	0	0
	SBES/SSS Mainscheme	0	0	0	0
	MBES/SSS Mainscheme	0	0	0	0
	SBES/MBES Crosslines	2.08	0	73.79	75.86
	Lidar Crosslines	0	0	0	0
Numb Botton	er of n Samples				11
	er Maritime ary Points igated				0
Numb	er of DPs				0
	er of Items igated by Ops				0
Total S	SNM				0

Table 3: Hydrographic Survey Statistics

The following table lists the specific dates of data acquisition for this survey:

Survey Dates	Day of the Year
06/09/2021	160

Survey Dates	Day of the Year
06/10/2021	161
06/11/2021	162
06/12/2021	163
06/13/2021	164
06/14/2021	165
06/15/2021	166
06/16/2021	167
06/17/2021	168
06/18/2021	169
06/19/2021	170
06/20/2021	171
06/22/2021	173
06/23/2021	174
06/25/2021	176
06/26/2021	177
06/27/2021	178
06/28/2021	179
06/29/2021	180
07/02/2021	183
07/03/2021	184
07/04/2021	185
08/04/2021	216
08/05/2021	217
08/06/2021	218
08/17/2021	229

Table 4: Dates of Hydrography

# **B.** Data Acquisition and Processing

# **B.1** Equipment and Vessels

Refer to the Data Acquisition and Processing Report (DAPR) for a complete description of data acquisition and processing systems, survey vessels, quality control procedures and data processing methods. Additional information to supplement sounding and survey data, and any deviations from the DAPR are discussed in the following sections.

#### **B.1.1 Vessels**

The following vessels were used for data acquisition during this survey:

Hull ID	R/V Endeavor	R/V Rapid	R/V Voxel	
LOA	13.4 meters	8.5 meters	14.0 meters	
Draft	0.8 meters	0.6 meters	0.6 meters	

Table 5: Vessels Used

The R/V Endeavor is a 13.4 meter aluminum catamaran equipped with an over-the-side Pitman Arm with secondary tie point.

The R/V Rapid is a 8.5 meter aluminum monohull equipped with both a Universal Sonar Mount (USM) starboard and port multibeam pole mount.

The R/V Voxel is a 14.0 meter aluminum catamaran equipped with an electro hydraulic actuated moonpool accessed adjustable aluminum and stainless steel custom mount.

#### **B.1.2** Equipment

Manufacturer	Model	Туре
R2Sonic	2024	MBES
R2Sonic	I2NS	Positioning and Attitude System
Applanix	POS MV 320 v5	Positioning and Attitude System
AML Oceanographic	SmartX	Sound Speed System
AML Oceanographic	BaseX2	Sound Speed System
AML Oceanographic	MicroX SV	Sound Speed System
AML Oceanographic	MVP-X	Sound Speed System

The following major systems were used for data acquisition during this survey:

#### Table 6: Major Systems Used

Note: R/V Endeavor utilized a dual head R2Sonic 2024 multibeam echosounder system, an AML Micro.X for the surface sound speed system, an AML/eTrac MVP-X for the sound speed system, an AML Base.X2 as a spare for the sound speed system, and a POS MV 320 V5 for the positioning and attitude system.

R/V Rapid utilized a dual head R2Sonic 2024 multibeam echosounder system, an AML Micro.X for the surface sound speed system, an AML Base.X2 for the sound speed system, and a R2Sonic I2NS for the positioning and attitude system.

R/V Voxel utilized a single head R2Sonic 2024 multibeam echosounder system, an AML Micro.X for the surface sound speed system, an AML Smart.X for the sound speed system, and a POS MV 320 V5 for the positioning and attitude system.

## **B.2 Quality Control**

#### **B.2.1** Crosslines

A beam-to-beam statistical analysis was performed using the Cross Check tool in Qimera. 1 meter Combined Uncertainty and Bathymetric Estimator (CUBE) weighted dynamic surfaces were created incorporating only the mainscheme lines and excluded crosslines. The Cross Check tool was used to perform the beam-by-beam comparison of the crossline data to the mainscheme surface. Comparisons showed excellent agreement, well above 95% of the allowable TVU.

Below is a histogram of the crossline comparison statistics showing IHO Order 1a compliance per beam.

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Note: A 1m sheetwide surface was unable to be created due to technical issues within Qimera, therefore the surface was divided into multiple parts. These surfaces were created for QC only and are not submitted as a surface deliverable.

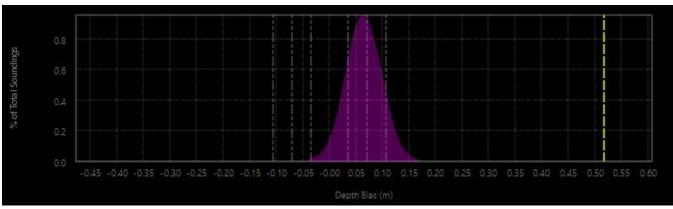


Figure 5: H13467 Crossline Comparison (Surface 1 of 5)

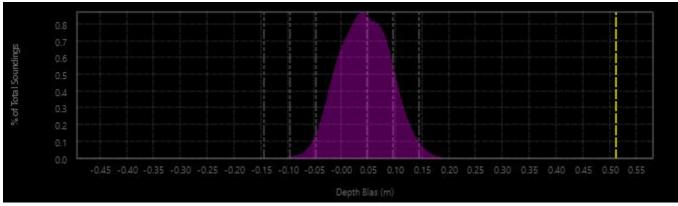


Figure 6: H13467 Crossline Comparison (Surface 2 of 5)

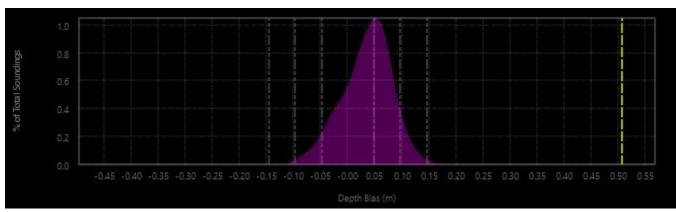


Figure 7: H13467 Crossline Comparison (Surface 3 of 5)

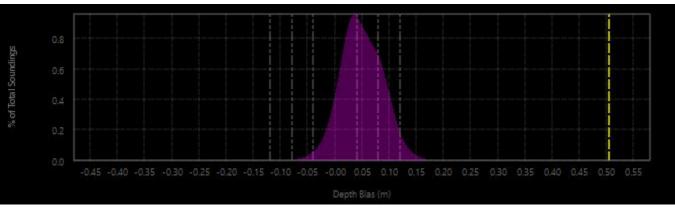


Figure 8: H13467 Crossline Comparison (Surface 4 of 5)

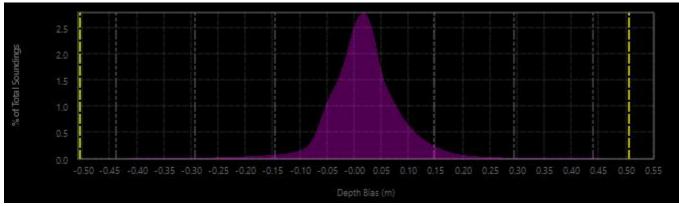


Figure 9: H13467 Crossline Comparison (Surface 5 of 5)

### **B.2.2 Uncertainty**

The following survey specific parameters were used for this survey:

Method	Measured	Zoning
ERS via ERTDM	0.045 meters	N/A

Table 7: Survey Specific Tide TPU Values.

Hull ID	Measured - CTD	Measured - MVP	Measured - XBT	Surface
R/V Endeavor	0.05 meters/second	N/A	N/A	0.2 meters/second
R/V Rapid	0.05 meters/second	N/A	N/A	0.2 meters/second
R/V Voxel	0.05 meters/second	N/A	N/A	0.2 meters/second

Table 8: Survey Specific Sound Speed TPU Values.

Standard deviation and uncertainty layers of the Dynamic Surface were utilized during data processing to search for features, water column noise, and systematic errors.

IHO Order 1a uncertainty specification was met by 99.5+% to 100% of the nodes.

The uncertainty of each finalized Bathymetric Attributed Grid (BAG) was generated through the NOAA QC Tools and an image of the results is located below.

For H13467 the following percentages represent the results of the TPU calculation:

Complete Coverage MBES (Finalized 1m (1 of 5) CUBE weighted Dynamic Surface in NOAA QC Tools) = 99.5+% of nodes are within the allowable TVU.

Complete Coverage MBES (Finalized 1m (2 of 5) CUBE weighted Dynamic Surface in NOAA QC Tools) = 100% of nodes are within the allowable TVU.

Complete Coverage MBES (Finalized 1m (3 of 5) CUBE weighted Dynamic Surface in NOAA QC Tools) = 100% of nodes are within the allowable TVU.

Complete Coverage MBES (Finalized 1m (4 of 5) CUBE weighted Dynamic Surface in NOAA QC Tools) = 99.5+% of nodes are within the allowable TVU.

Complete Coverage MBES (Finalized 1m (5 of 5) CUBE weighted Dynamic Surface in NOAA QC Tools) = 99.5+% of nodes are within the allowable TVU.

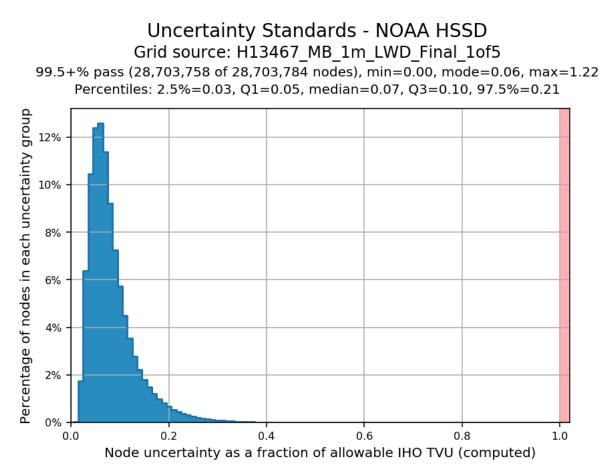


Figure 10: H13467 Finalized 1m Complete Coverage MBES TVU Statistics (1 of 5)

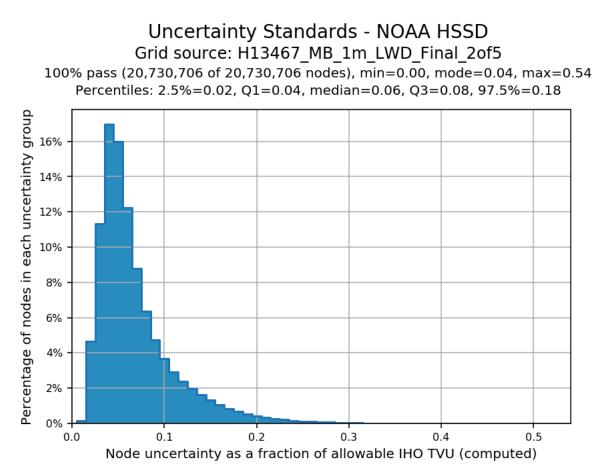


Figure 11: H13467 Finalized 1m Complete Coverage MBES TVU Statistics (2 of 5)

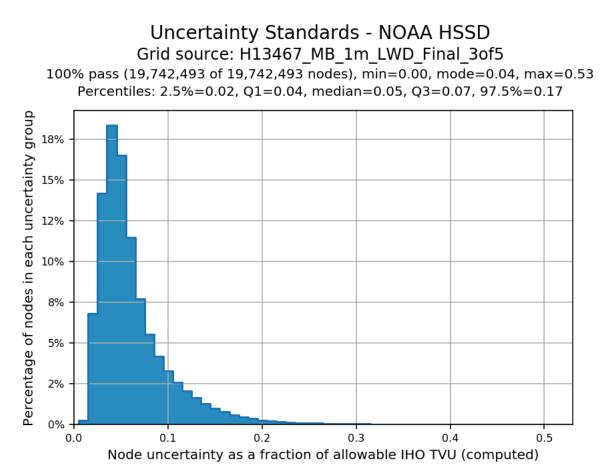


Figure 12: H13467 Finalized 1m Complete Coverage MBES TVU Statistics (3 of 5)

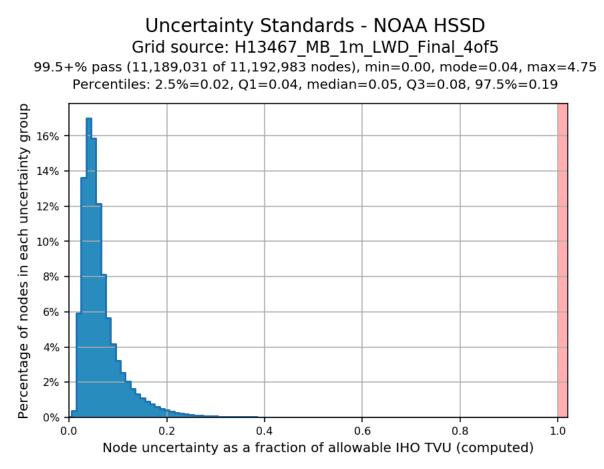


Figure 13: H13467 Finalized 1m Complete Coverage MBES TVU Statistics (4 of 5)

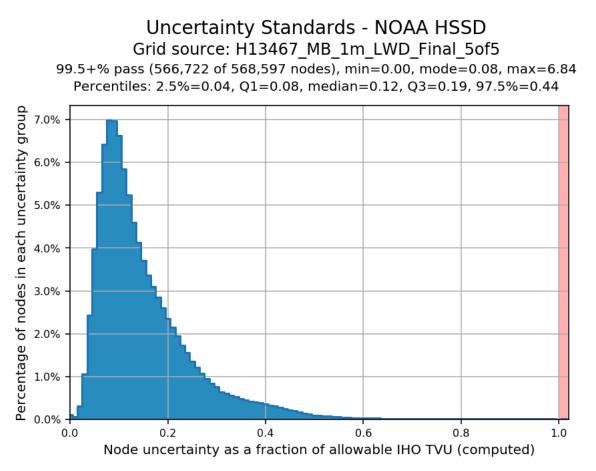


Figure 14: H13467 Finalized 1m Complete Coverage MBES TVU Statistics (5 of 5)

Survey specific sound speed TPU values reported in Table 8 are inconsistent with those applied to the processed sounding data. Both measured and surface sound speed uncertainty vary from 0.03 to 0.05 m/ sec.

The Qimera-exported BAG uncertainty values originate solely from the standard deviation of the soundings that contributed to each CUBE hypothesis, scaled to the 95% confidence interval, and do not use total propagated vertical uncertainty estimates in this calculation.

#### **B.2.3 Junctions**

Depth differences between junctioning surveys were evaluated using the JunctionTrac program, developed in-house by eTrac Inc. For each junction, each CUBE weighted dynamic surface's nodes were exported to an ASCII CSV file where the fields were (Easting, Northing, Depth) for each node. A 1 meter difference surface between the junctioning datasets was also created and exported to an ASCII CSV file where the fields were (Easting, Northing, Depth) for each node. A 1 meter difference surface between the junctioning datasets was also created and exported to an ASCII CSV file where the fields were (Easting, Northing, Diff) for each node. The three ASCII CSV files were then loaded into the

JunctionTrac program and junction statistics were computed. A file was also created in this process to locate any nodes from the difference surface that exceed the allowable TVU, which was imported into Qimera and any identified points from JunctionTrac were analyzed. Note: the difference surfaces were created for comparison efforts only and are not submitted as surface deliverables.

The following junctions were made with this survey:
---

Registry Number	Scale	Year	Field Unit	Relative Location
H13468	1:10000	2021	eTrac	W
H13469	1:10000	2021	eTrac	Е
H13470	1:20000	2021	eTrac	NE

Table 9: Junctioning Surveys

#### <u>H13468</u>

The junction comparison was performed using all overlapping data between H13467 and H13468. Below is a histogram of junction comparison statistics showing the difference between the junctioning surfaces and allowable TVU as well as difference statistics. 100% of nodes were within allowable TVU.

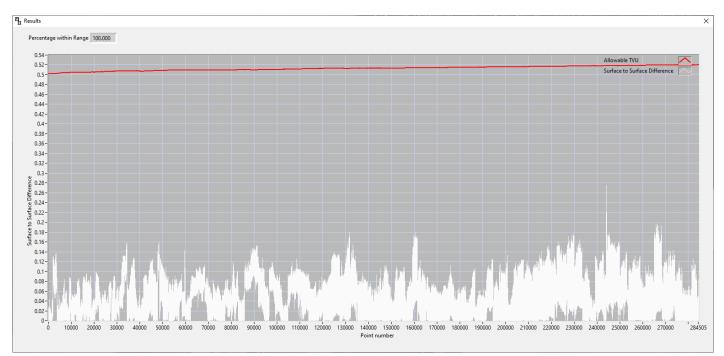


Figure 15: H13467 - H13468 Junction Comparison

Criteria	Number of Nodes	Resulting %	
DIFF < 10cm	272106	95.64%	
10cm < DIFF < 20cm	12388	4.35%	
20cm < DIFF < 30cm	12	0.00%	
DIFF > 30cm	0	0.00%	
Total	284506	100.00%	

Figure 16: H13467 - H13468 Difference Statistics

#### <u>H13469</u>

The junction comparison was performed using all overlapping data between H13467 and H13469. Below is a histogram of junction comparison statistics showing the difference between the junctioning surfaces and allowable TVU as well as difference statistics. 99.9955% of nodes were within allowable TVU.

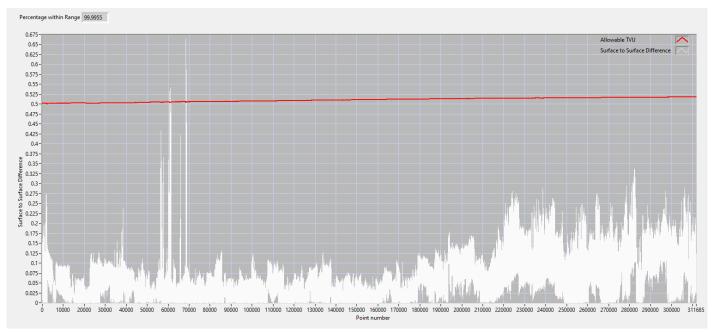


Figure 17: H13467 - H13469 Junction Comparison

Criteria	Number of Nodes	Resulting %	
DIFF < 10cm	265190	85.08%	
10cm < DIFF < 20cm	45296	14.53%	
20cm < DIFF < 30cm	1127	0.36%	
DIFF > 30cm	73	0.02%	
Total	311686	100.00%	

Figure 18: H13467 - H13469 Difference Statistics

#### <u>H13470</u>

The junction comparison was performed using all overlapping data between H13467 and H13470. Below is a histogram of junction comparison statistics showing the difference between the junctioning surfaces and allowable TVU as well as difference statistics. 100% of nodes were within allowable TVU.

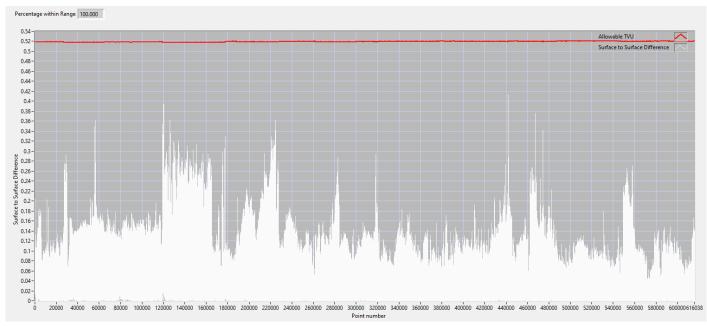


Figure 19: H13467 - H13470 Junction Comparison

Criteria	Number of Nodes	Resulting %	
DIFF < 10cm	577832	93.69%	
10cm < DIFF < 20cm	37410	6.07%	
20cm < DIFF < 30cm	1453	0.24%	
DIFF > 30cm	63	0.01%	
Total	616758	100.00%	

Figure 20: H13467 - H13470 Difference Statistics

#### **B.2.4 Sonar QC Checks**

Sonar system quality control checks were conducted as detailed in the quality control section of the DAPR.

#### **B.2.5 Equipment Effectiveness**

There were no conditions or deficiencies that affected equipment operational effectiveness.

#### **B.2.6 Factors Affecting Soundings**

There were no other factors that affected corrections to soundings.

#### **B.2.7 Sound Speed Methods**

Sound Speed Cast Frequency: SVP casts were generally taken every 2 hours. Occasionally casts would exceed a 2 hour frequency, however would never exceed a 4 hour frequency.

On R/V Endeavor, R/V Rapid, and R/V Voxel casts were applied in QPS Qinsy acquisition software at the time of the cast. Surface SVP measured at 1Hz was compared to surface speed from the current profile in real-time. If the surface velocity comparison was in excess of 2m/s at any time during survey operations, a new cast was taken.

Surface sound speeds were compared in real-time and profile to profile for each cast on the vessel. Additionally, the processor reviewed profiles in Qimera to remove spurious readings within a cast, compare day-to-day casts, and to check distribution over the surveyed area, in order to better understand trends for efficient acquisition planning.

#### **B.2.8** Coverage Equipment and Methods

All equipment and survey methods were used as detailed in the DAPR.

#### **B.2.9 Data Density Evaluation**

In order to determine if the density of the data met the specified 5 soundings per node, data density was evaluated using DensityTrac in the AmiTrac program, developed in-house by eTrac Inc. Each finalized CUBE weighted dynamic surface's nodes were exported to a BBH file. The BBH file was then loaded into the DensityTrac program and density statistics were computed.

For H13467 the following percentages represent the results of the density query:

Complete Coverage MBES (Finalized 1m (1 of 5) CUBE weighted Dynamic Surface) = 99.9804% of nodes are composed from at least 5 soundings.

Complete Coverage MBES (Finalized 1m (2 of 5) CUBE weighted Dynamic Surface) = 99.9872% of nodes are composed from at least 5 soundings.

Complete Coverage MBES (Finalized 1m (3 of 5) CUBE weighted Dynamic Surface) = 99.9862% of nodes are composed from at least 5 soundings.

Complete Coverage MBES (Finalized 1m (4 of 5) CUBE weighted Dynamic Surface) = 99.9724% of nodes are composed from at least 5 soundings.

Complete Coverage MBES (Finalized 1m (5 of 5) CUBE weighted Dynamic Surface) = 99.5597% of nodes are composed from at least 5 soundings.

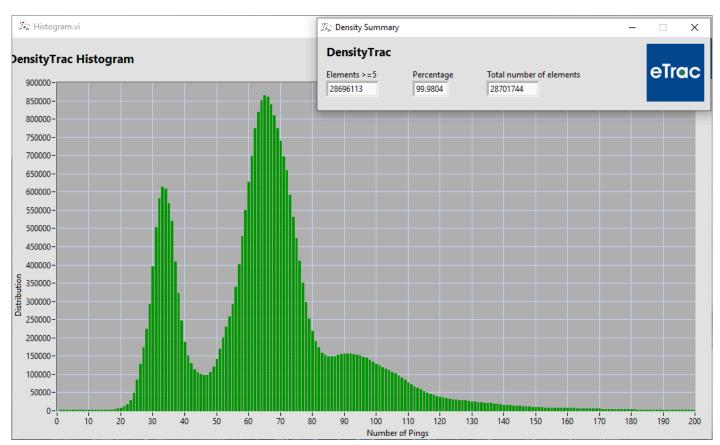


Figure 21: H13467 Finalized 1m Complete Coverage MBES Density Distribution (1 of 5)

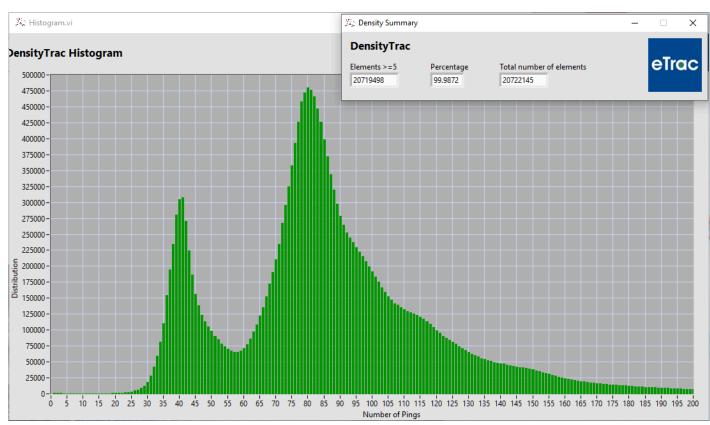


Figure 22: H13467 Finalized 1m Complete Coverage MBES Density Distribution (2 of 5)

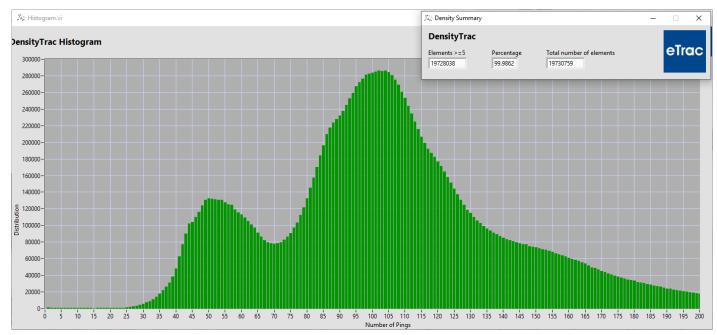


Figure 23: H13467 Finalized 1m Complete Coverage MBES Density Distribution (3 of 5)

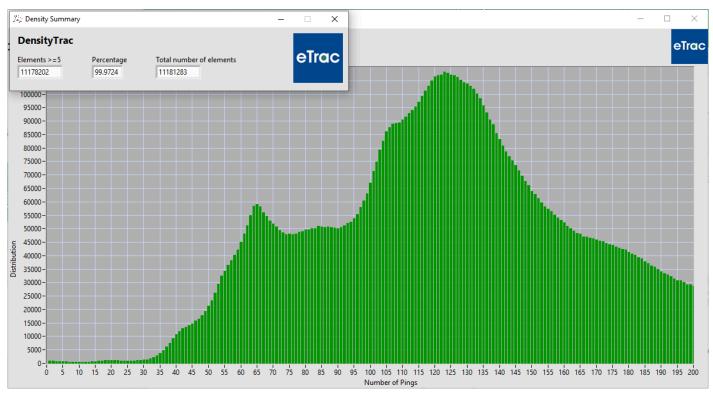


Figure 24: H13467 Finalized 1m Complete Coverage MBES Density Distribution (4 of 5)

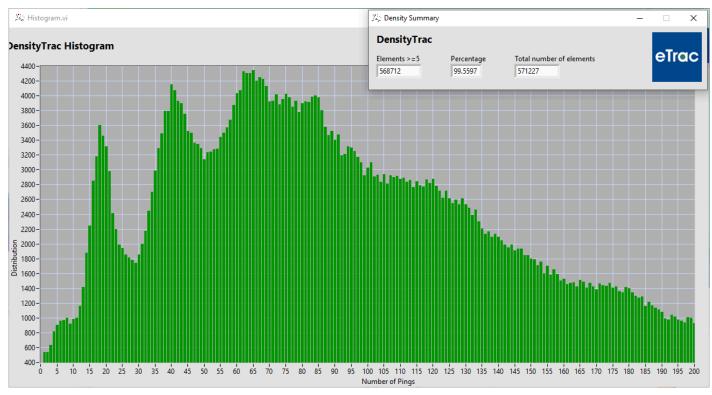


Figure 25: H13467 Finalized 1m Complete Coverage MBES Density Distribution (5 of 5)

# **B.3 Echo Sounding Corrections**

#### **B.3.1** Corrections to Echo Soundings

All data reduction procedures conform to those detailed in the DAPR.

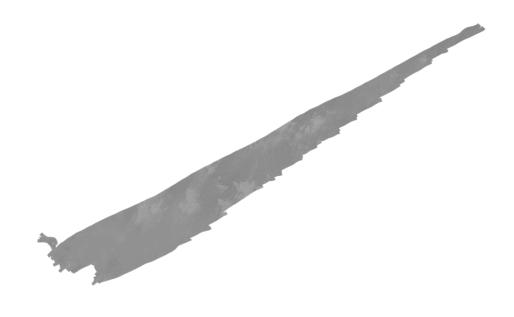
#### **B.3.2** Calibrations

All sounding systems were calibrated as detailed in the DAPR.

## **B.4 Backscatter**

Backscatter data were collected throughout the survey and are retained in the raw DB files. Every effort was made in the field to collect quality backscatter data while maintaining the primary mandate of high quality bathymetric data. While no processing or analysis of backscatter was required, eTrac Inc. verified

coverage and general quality of the backscatter data collected. A beam intensity window was monitored in Qinsy during acquisition to ensure backscatter data collection. Raw backscatter data were viewed in QPS FMGeocoder to further confirm collection criteria had been met. Shown below is an example of the unprocessed backscatter mosaic from H13467 DN183 (R/V Rapid).



# 9/

Figure 26: Raw Backscatter from R/V Rapid (DN183)

# **B.5 Data Processing**

## **B.5.1 Primary Data Processing Software**

The following Feature Object Catalog was used: NOAA Profile Version 2021

Feature Object Catalog, NOAA Profile Version 2021 was used only in CARIS. Qimera was used as the primary processing software.

#### **B.5.2 Surfaces**

The following surfaces and/or BAGs were submitted to the Processing Branch:

Surface Name	Surface Type	Resolution	Depth Range	Surface Parameter	Purpose
H13467_MB_1m_LWD_Final_1of5	BAG	1 meters	8.27 meters - 11.29 meters	NOAA_1m	Complete MBES
H13467_MB_1m_LWD_Final_2of5	BAG	1 meters	6.69 meters - 9.34 meters	NOAA_1m	Complete MBES
H13467_MB_1m_LWD_Final_3of5	BAG	1 meters	4.71 meters - 9.12 meters	NOAA_1m	Complete MBES
H13467_MB_1m_LWD_Final_4of5	BAG	1 meters	0.38 meters - 9.39 meters	NOAA_1m	Complete MBES
H13467_MB_1m_LWD_Final_5of5	BAG	1 meters	0.27 meters - 9.91 meters	NOAA_1m	Complete MBES

Table 10: Submitted Surfaces

1m surfaces are provided meeting complete coverage MBES with backscatter specifications for H13467.

Note: A sheetwide surface was unable to be created due to technical issues within Qimera.

Therefore, the 1m surface was divided into 5 parts. Together the 5 surfaces cover the entirety of the survey area.

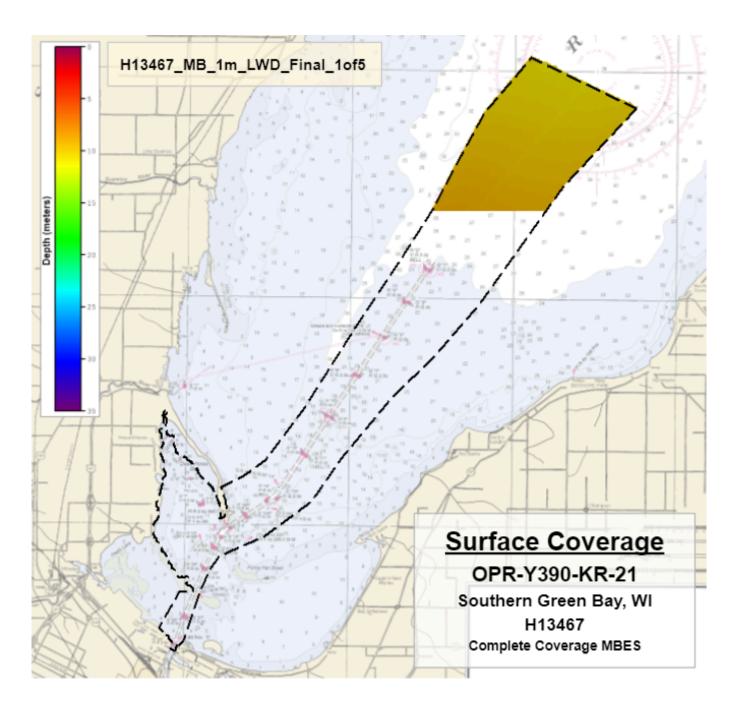


Figure 27: H13467 Finalized 1m CUBE weighted Dynamic Surface Coverage (1 of 5)

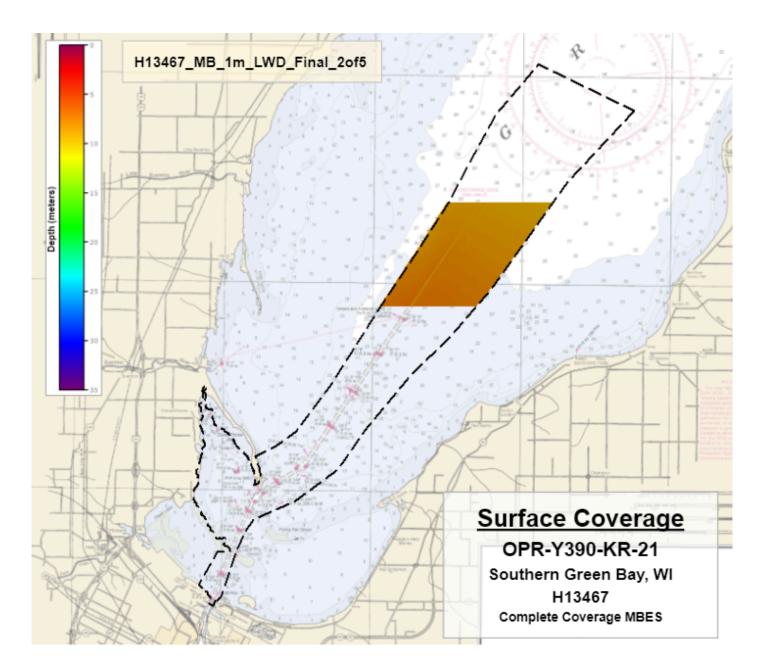


Figure 28: H13467 Finalized 1m CUBE weighted Dynamic Surface Coverage (2 of 5)

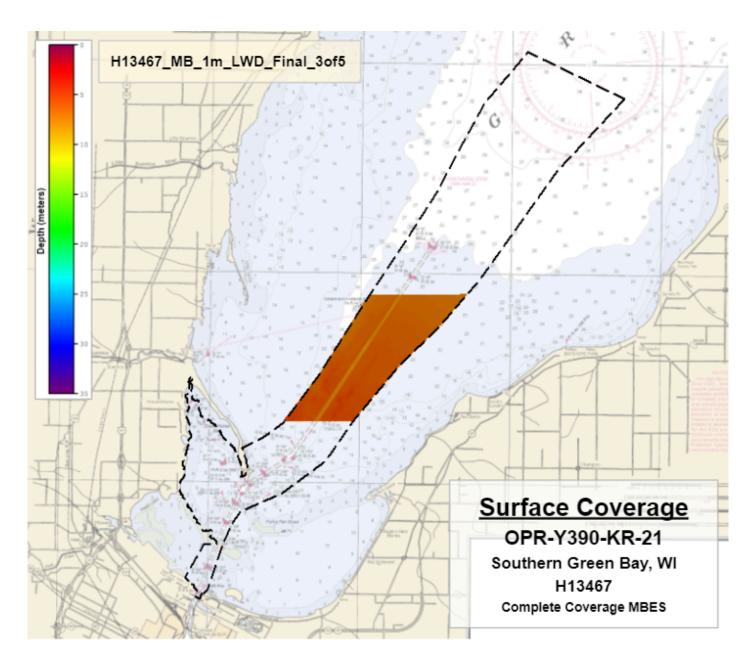


Figure 29: H13467 Finalized 1m CUBE weighted Dynamic Surface Coverage (3 of 5)

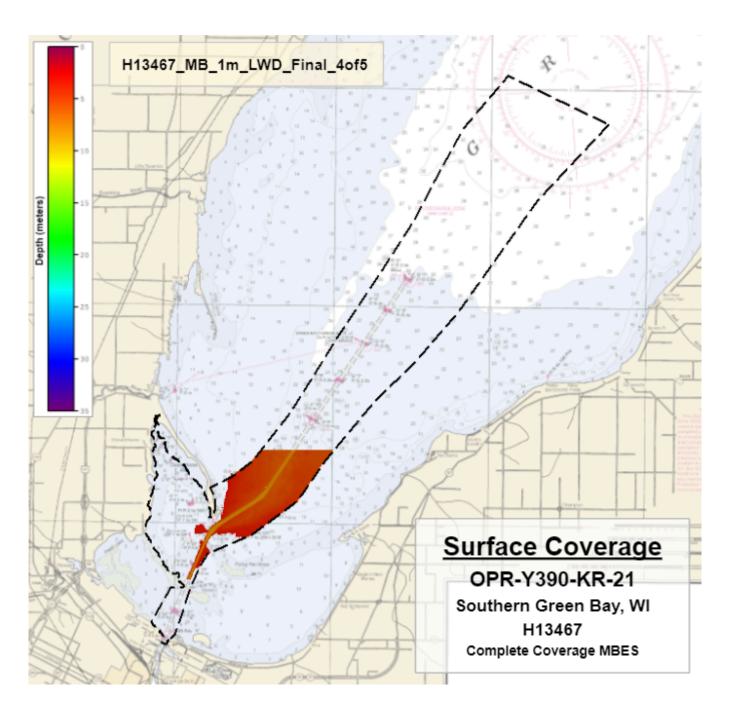


Figure 30: H13467 Finalized 1m CUBE weighted Dynamic Surface Coverage (4 of 5)

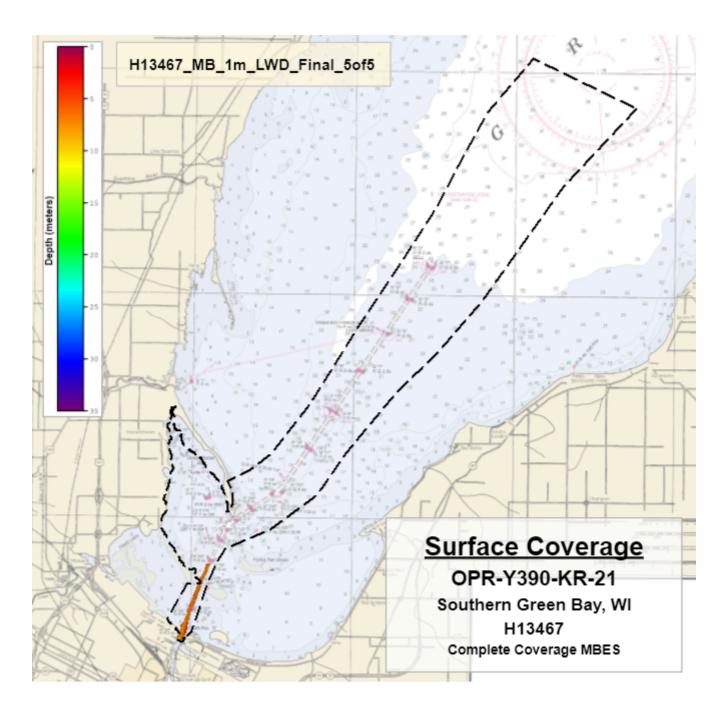


Figure 31: H13467 Finalized 1m CUBE weighted Dynamic Surface Coverage (5 of 5)

To improve grid management, the five (5) subdivided grids were combined into a single 1m resolution BAG by AHB personnel. The final grid deliverable for use in chart updates and archive at NCEI is H13467\_MB\_1m\_LWD\_1of1.bag.

## **C. Vertical and Horizontal Control**

Additional information discussing the vertical or horizontal control for this survey can be found in the accompanying HVCR and DAPR.

### **C.1 Vertical Control**

The vertical datum for this project is Low Water Datum IGLD-1985.

#### ERS Datum Transformation

The following ellipsoid-to-chart vertical datum transformation was used:

Method	Ellipsoid to Chart Datum Separation File
ERS via VDATUM	OPR_Y390_KR_21_NAD83_to_LWD_IGLD85.qgfvom

#### Table 11: ERS method and SEP file

Survey data were vertically referenced to the ellipsoid. A time dependent, 7 parameter transformation from ITRF-2014 to NAD83\_2011 was performed in QPS Qinsy. Using VDatum, a vertical separation model was created to transform the ellipsoidally referenced data from NAD83\_2011 to LWD\_IGLD85. The transformation and the separation model were applied in QPS Qinsy on the vessels in real-time to achieve LWD\_IGLD85 in the field.

## C.2 Horizontal Control

The horizontal datum for this project is North American Datum of 1983 (NAD 83).

The projection used for this project is Universal Transverse Mercator (UTM) Zone 16.

The following PPK methods were used for horizontal control:

• RTX

Applanix PosPac MMS was utilized to post process realtime positioning data utilizing Trimble's PP-RTX implementation of Trimble CenterPoint RTX to create a Smoothed Best Estimate of Trajectory (SBET).

#### <u>RTK</u>

GNSS satellite corrections were received on each vessel using the G2+ carrier signal from the Marinestar Global Correction System maintained by Fugro.

## **D.** Results and Recommendations

## **D.1 Chart Comparison**

A chart comparison was conducted for H13467 using Pydro CA tools, Qimera, and Caris HIPS and SIPS. Survey data were compared against the largest scale ENC to accomplish the chart comparison. The largest scale ENC does not cover the entire survey boundary so two other charts were used to complete the chart comparison. Details of the ENCs used are listed below.

US5WI01M, scale: 15000, edition: 6, update application date: 09/08/2021, issue date: 09/08/2021 US5WI02M, scale: 25000, edition: 20, update application date: 08/11/2021, issue date: 08/11/2021 US4WI03M, scale: 80000, edition: 26, update application date: 09/16/2021, issue date: 10/06/2021

Throughout survey operations sounding comparisons between the charted depths and the surveyed depths were analyzed to identify depth discrepancies. Using 1 meter CUBE weighted Dynamic surfaces, soundings were generated in the "Sounding Selection" tab of Pydro CA tools. Soundings were displayed against the charted soundings and a visual comparison was made in Caris HIPS and SIPS. Additionally, potential DtoNs and discrepancies were generated using the "DTM vs Chart" tab of Pydro CA tools. The results were displayed through CA tools and investigated in CARIS HIPS and SIPS and Qimera.

An overview image of the generated soundings on each chart is included below.

Results of the chart comparison are included in the following sections.

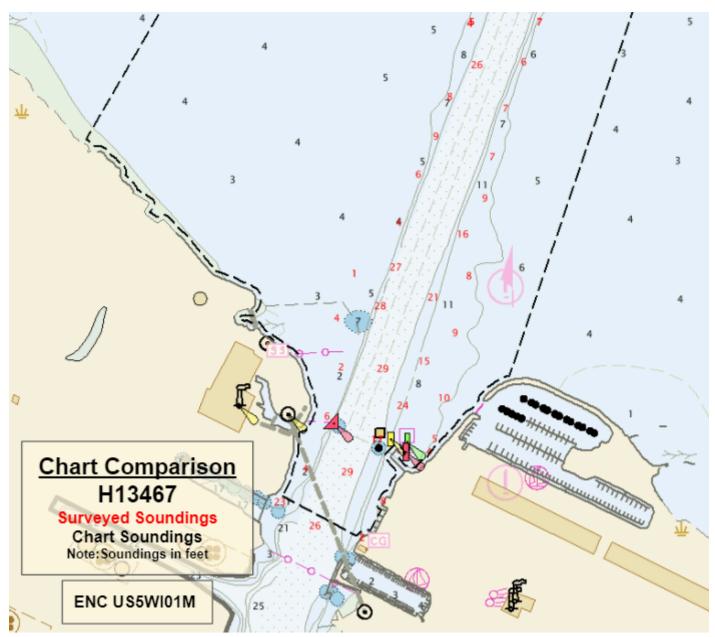


Figure 32: Generated Soundings used for Chart Comparison (US5WI01M)

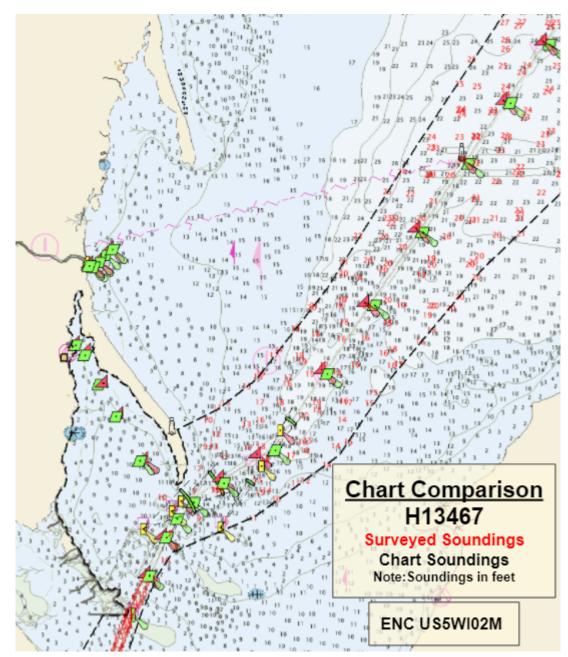


Figure 33: Generated Soundings used for Chart Comparison (US5WI02M)

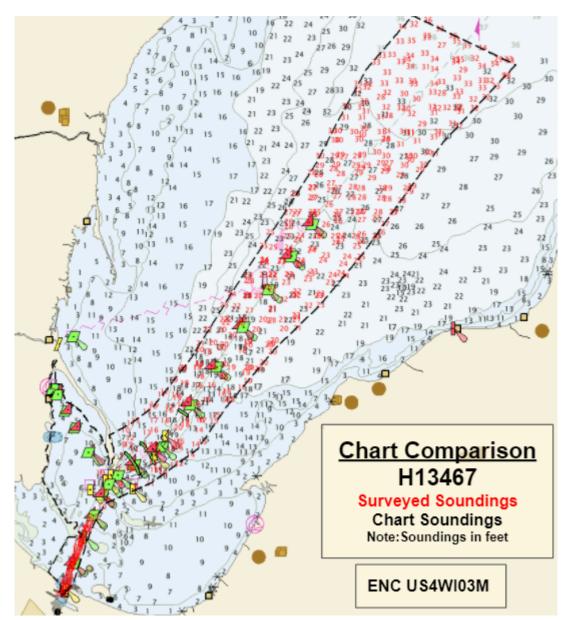


Figure 34: Generated Soundings used for Chart Comparison (US4WI03M)

#### **D.1.1 Electronic Navigational Charts**

ENC	Scale	Edition	Update Application Date	Issue Date
US5WI01M	1:15000	6	09/08/2021	09/08/2021
US5WI02M	1:25000	20	08/11/2021	08/11/2021
US4WI03M	1:80000	26	09/16/2021	10/06/2021

The following are the largest scale ENCs, which cover the survey area:

Table 12: Largest Scale ENCs

#### **D.1.2 Shoal and Hazardous Features**

There were 2 DtoNs found in H13467, and added to the Final Feature File (FFF). Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature. The DtoNs were submitted in the following Danger to navigation reports:

H13467\_DtoNs\_1-2\_USACE\_Report

H13467\_DtoNs\_1-2\_USACE\_Report contains 2 obstructions (subm piles).

1 DtoN has been applied to ENC US5WI01M.

#### **D.1.3 Charted Features**

There were 146 charted features assigned to H13467 that are included in the Final Feature File (FFF). Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature.

#### **D.1.4 Uncharted Features**

9 new features were found in H13467. Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature.

Note: DtoNs are not included in the number of new features in this section. DtoNs can be found separately in section D.1.2.

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#### **D.1.5** Channels

The Green Bay Harbor Channel and Green Bay Harbor Entrance Channel is a maintained channel and has controlled depths between 4.7m and 7.6m. Dredge Area controlled depths in Green Bay Harbor Entrance Channel were compared against soundings derived from our 1m surface as described in section D.1. No discrepancies were found.

### **D.2 Additional Results**

#### **D.2.1** Aids to Navigation

There were 111 charted AtoNs assigned in H13467. Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature.

Note: All AtoNs were included in the number of charted features within section D.1.3.

#### **D.2.2 Maritime Boundary Points**

No Maritime Boundary Points were assigned for this survey.

#### **D.2.3 Bottom Samples**

11 bottom samples were obtained in accordance with section 7.1 of the HSSD 2021 in areas designated by the field through discussions with our COR. Detailed information and images of the bottom samples are located in the Final Feature File (FFF). Each bottom sample has been given a unique identifier in the "userid" field of the .000 S-57 file (format AX).

#### **D.2.4 Overhead Features**

There were 2 Overhead Features assigned in H13467. Note: Per investigation requirements the features were not included in the FFF.

Discussion of the 2 overhead features is below:

No discrepancies were found for the bridge and overhead cable.

#### **D.2.5 Submarine Features**

There were 3 Submarine Features assigned to H13467.

Note: Per Investigation Requirements, 1 submerged feature was not included in the FFF. Additionally, 2 submerged features were included the FFF and were included in the number of charted features within section D.1.3. Discussion of the 3 submarine features is below:

submerged cable was not visible in the MBES data.
 submerged pipeline was not visible in the MBES data.
 submerged pipeline was not safe to address due to being inshore of NALL.

#### **D.2.6 Platforms**

No platforms exist for this survey.

#### **D.2.7 Ferry Routes and Terminals**

No ferry routes or terminals exist for this survey.

#### **D.2.8** Abnormal Seafloor or Environmental Conditions

In some regions, marine vegetation was picked up by the MBES. The vegetation was investigated by collecting additional lines in various directions in a few different areas throughout OPR-Y390-KR-21. The overlap of the vegetation throughout the investigation lines was not consistent and therefore could be determined to be marine vegetation moving in the water column. After the investigation was complete, the marine vegetation was rejected from the dataset by data processors. Below is an example where this occurred in this survey. No data gaps were observed in the delivered surfaces from rejecting the marine vegetation in this survey.

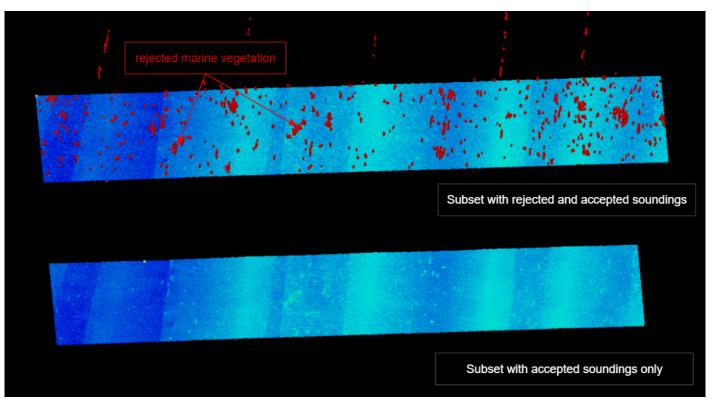


Figure 35: Marine Vegetation Rejected

#### **D.2.9** Construction and Dredging

There were 16 Dredge Areas assigned in H13467. Per investigation requirements the features were not included in the FFF. No discrepancies were found.

There were 2 Shoreline Construction Features assigned in H13467. Note: The Shoreline Construction Features were included in the FFF and were included in the number of charted features within section D.1.3.

Refer to the FFF for determinations of each feature.

#### **D.2.10 New Survey Recommendations**

No new surveys or further investigations are recommended for this area.

#### **D.2.11 ENC Scale Recommendations**

No new ENC scales are recommended for this area.

H13467

# E. Approval Sheet

As Chief of Party, field operations for this hydrographic survey were conducted under my direct supervision, with frequent personal checks of progress and adequacy. I have reviewed the attached survey data and reports.

All field sheets, this Descriptive Report, and all accompanying records and data are approved. All records are forwarded for final review and processing to the Processing Branch.

The survey data meets or exceeds requirements as set forth in the NOS Hydrographic Surveys Specifications and Deliverables, Field Procedures Manual, Letter Instructions, and all HSD Technical Directives. These data are adequate to supersede charted data in their common areas. This survey is complete and no additional work is required with the exception of deficiencies noted in the Descriptive Report.

Approver Name	Approver Title	Approval Date	Signature
David Neff	Chief of Party	10/27/2021	Digitally signed by David Neff DN: C=US, David Neff D=Tracinc.com, D=Tracinc.com, D=Tracinc.com, D=tracinc.com,

# F. Table of Acronyms

Acronym	Definition
AHB	Atlantic Hydrographic Branch
AST	Assistant Survey Technician
ATON	Aid to Navigation
AWOIS	Automated Wreck and Obstruction Information System
BAG	Bathymetric Attributed Grid
BASE	Bathymetry Associated with Statistical Error
СО	Commanding Officer
CO-OPS	Center for Operational Products and Services
CORS	Continuously Operating Reference Station
CTD	Conductivity Temperature Depth
CEF	Chart Evaluation File
CSF	Composite Source File
CST	Chief Survey Technician
CUBE	Combined Uncertainty and Bathymetry Estimator
DAPR	Data Acquisition and Processing Report
DGPS	Differential Global Positioning System
DP	Detached Position
DR	Descriptive Report
DTON	Danger to Navigation
ENC	Electronic Navigational Chart
ERS	Ellipsoidal Referenced Survey
ERTDM	Ellipsoidally Referenced Tidal Datum Model
ERZT	Ellipsoidally Referenced Zoned Tides
FFF	Final Feature File
FOO	Field Operations Officer
FPM	Field Procedures Manual
GAMS	GPS Azimuth Measurement Subsystem
GC	Geographic Cell
GPS	Global Positioning System
HIPS	Hydrographic Information Processing System
HSD	Hydrographic Surveys Division

Acronym	Definition
HSSD	Hydrographic Survey Specifications and Deliverables
HSTB	Hydrographic Systems Technology Branch
HSX	Hypack Hysweep File Format
HTD	Hydrographic Surveys Technical Directive
HVCR	Horizontal and Vertical Control Report
HVF	HIPS Vessel File
ІНО	International Hydrographic Organization
IMU	Inertial Motion Unit
ITRF	International Terrestrial Reference Frame
LNM	Linear Nautical Miles
MBAB	Multibeam Echosounder Acoustic Backscatter
MCD	Marine Chart Division
MHW	Mean High Water
MLLW	Mean Lower Low Water
NAD 83	North American Datum of 1983
NALL	Navigable Area Limit Line
NTM	Notice to Mariners
NMEA	National Marine Electronics Association
NOAA	National Oceanic and Atmospheric Administration
NOS	National Ocean Service
NRT	Navigation Response Team
NSD	Navigation Services Division
OCS	Office of Coast Survey
OMAO	Office of Marine and Aviation Operations (NOAA)
OPS	Operations Branch
MBES	Multibeam Echosounder
NWLON	National Water Level Observation Network
PDBS	Phase Differencing Bathymetric Sonar
РНВ	Pacific Hydrographic Branch
POS/MV	Position and Orientation System for Marine Vessels
РРК	Post Processed Kinematic
PPP	Precise Point Positioning
PPS	Pulse per second

Acronym	Definition
PRF	Project Reference File
PS	Physical Scientist
RNC	Raster Navigational Chart
RTK	Real Time Kinematic
RTX	Real Time Extended
SBES	Singlebeam Echosounder
SBET	Smooth Best Estimate and Trajectory
SNM	Square Nautical Miles
SSS	Side Scan Sonar
SSSAB	Side Scan Sonar Acoustic Backscatter
ST	Survey Technician
SVP	Sound Velocity Profiler
TCARI	Tidal Constituent And Residual Interpolation
TPU	Total Propagated Uncertainty
USACE	United States Army Corps of Engineers
USCG	United States Coast Guard
UTM	Universal Transverse Mercator
XO	Executive Officer
ZDF	Zone Definition File