

H13554

U.S. Department of Commerce  
National Oceanic and Atmospheric Administration  
National Ocean Service

**DESCRIPTIVE REPORT**

Type of Survey: Navigable Area

Registry Number: H13554

**LOCALITY**

State(s): California

General Locality: Channel Islands National Marine Sanctuary

Sub-locality: 9NM West of Santa Rosa Island

**2021**

CHIEF OF PARTY  
CAPT John Lomnicky

LIBRARY & ARCHIVES

Date:

**HYDROGRAPHIC TITLE SHEET**

**H13554**

**INSTRUCTIONS:** The Hydrographic Sheet should be accompanied by this form, filled in as completely as possible, when the sheet is forwarded to the Office.

State(s): **California**

General Locality: **Channel Islands National Marine Sanctuary**

Sub-Locality: **9NM West of Santa Rosa Island**

Scale: **10000**

Dates of Survey: **10/06/2021 to 10/10/2021**

Instructions Dated: **09/15/2021**

Project Number: **OPR-L397-FA-21**

Field Unit: **NOAA Ship *Fairweather***

Chief of Party: **CAPT John Lomnicky**

Soundings by: **Multibeam Echo Sounder**

Imagery by: **Multibeam Echo Sounder Backscatter**

Verification by: **Pacific Hydrographic Branch**

Soundings Acquired in: **meters at Mean Lower Low Water**

**Remarks:**

*Any revisions to the Descriptive Report (DR) applied during office processing are shown in red italic text. The DR is maintained as a field unit product, therefore all information and recommendations within this report are considered preliminary unless otherwise noted. The final disposition of survey data is represented in the NOAA nautical chart products. All pertinent records for this survey are archived at the National Centers for Environmental Information (NCEI) and can be retrieved via <https://www.ncei.noaa.gov/>. Products created during office processing were generated in NAD83 UTM 10N, MLLW. All references to other horizontal or vertical datums in this report are applicable to the processed hydrographic data provided by the field unit.*

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## Descriptive Report to Accompany Survey H13554

Project: OPR-L397-FA-21

Locality: Channel Islands National Marine Sanctuary

Sublocality: 9NM West of Santa Rosa Island

Scale: 1:10000

October 2021 - October 2021

**NOAA Ship *Fairweather***

Chief of Party: CAPT John Lomnicky

### A. Area Surveyed

The survey area is located 9NM West of Santa Rosa Island, California.

#### A.1 Survey Limits

Data were acquired within the following survey limits:

<b>Northwest Limit</b>	<b>Southeast Limit</b>
30° 1' 31.42" N 120° 29' 31.06" W	33° 50' 22.55" N 120° 7' 42.07" W

*Table 1: Survey Limits*

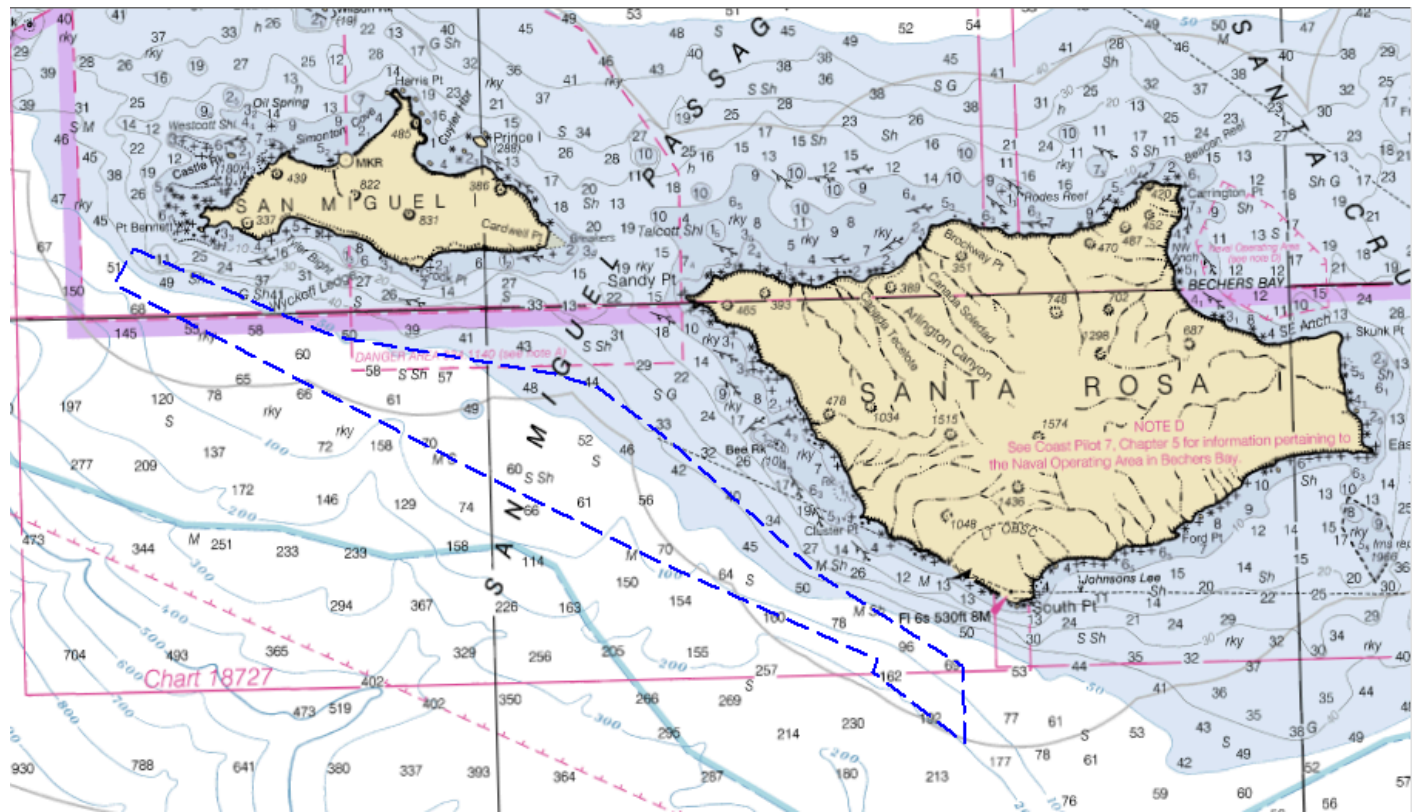


Figure 1: H13554 sheet limits (in blue) overlaid onto Chart 18720

Data were acquired to the survey limits in accordance with the requirements in the Project Instructions and the 2021 NOS Hydrographic Surveys Specifications and Deliverables (HSSD). Coverage acquired in H13554 is shown in Figure 1.

## A.2 Survey Purpose

This year the Channel Islands National Marine Sanctuary work will focus on the remaining survey area (prior projects 2017-2019) offshore of the Channel Islands (about 151 sq. mi.), located about 30 miles offshore of the California mainland city of Santa Barbara. The waters surrounding CINMS are highly productive and are home to recreational and commercial fishing efforts, and regularly host kayakers, surfers, sightseers, whale watchers, researchers, and Channel Islands National Park concessionaires, who all access the sanctuary via boats. Correspondingly, the abundance of sea life and aquatic habitats drives a thriving industry of recreational and commercial fishing that brings varied vessel traffic through the waters of CINMS. Additionally, major mainland port traffic transiting to and from Los Angeles and Long Beach, California routes large cargo and tanker vessels close to CINMS boundaries. The Ports of Los Angeles and Long Beach are top 10 ports in the United States for containers and tonnage. This poses a serious risk to life, property, and the delicate ecosystem of the area. This survey will continue modern mapping efforts to identify any similar threats that may exist in these waters. The CINMS hydrographic survey will be as unique as the region itself. In addition to providing data for crucial nautical chart updates, this survey will

also generate backscatter data, which will be used in habitat mapping and substrate analysis. Both multibeam echo sounder and backscatter data will not only serve to enhance marine navigational safety, but will also be used by sanctuary managers, planners, and researchers, aiding them in the conservation of this most precious resource. As an additional task, multibeam, backscatter, and water column data are being collected in support of the Bureau of Ocean Energy Management Pacific Region area around selected offshore platforms and pipelines. Survey data from this project is intended to supersede all prior survey data in the common area.

### A.3 Survey Quality

The entire survey is adequate to supersede previous data.

Data acquired in H13554 meet multibeam echo sounder (MBES) coverage requirements for complete coverage, as required by the HSSD. This includes crosslines (see Section B.2.1), NOAA allowable uncertainty (see Section B.2.10), and density requirements (see Section B.2.11).

### A.4 Survey Coverage

The following table lists the coverage requirements for this survey as assigned in the project instructions:

Water Depth	Coverage Required
All waters in survey area	Complete Coverage

*Table 2: Survey Coverage*

The entirety of H13554 was acquired with Complete Coverage, meeting the requirements listed above and in the HSSD. See Figure 2 for an overview of coverage.

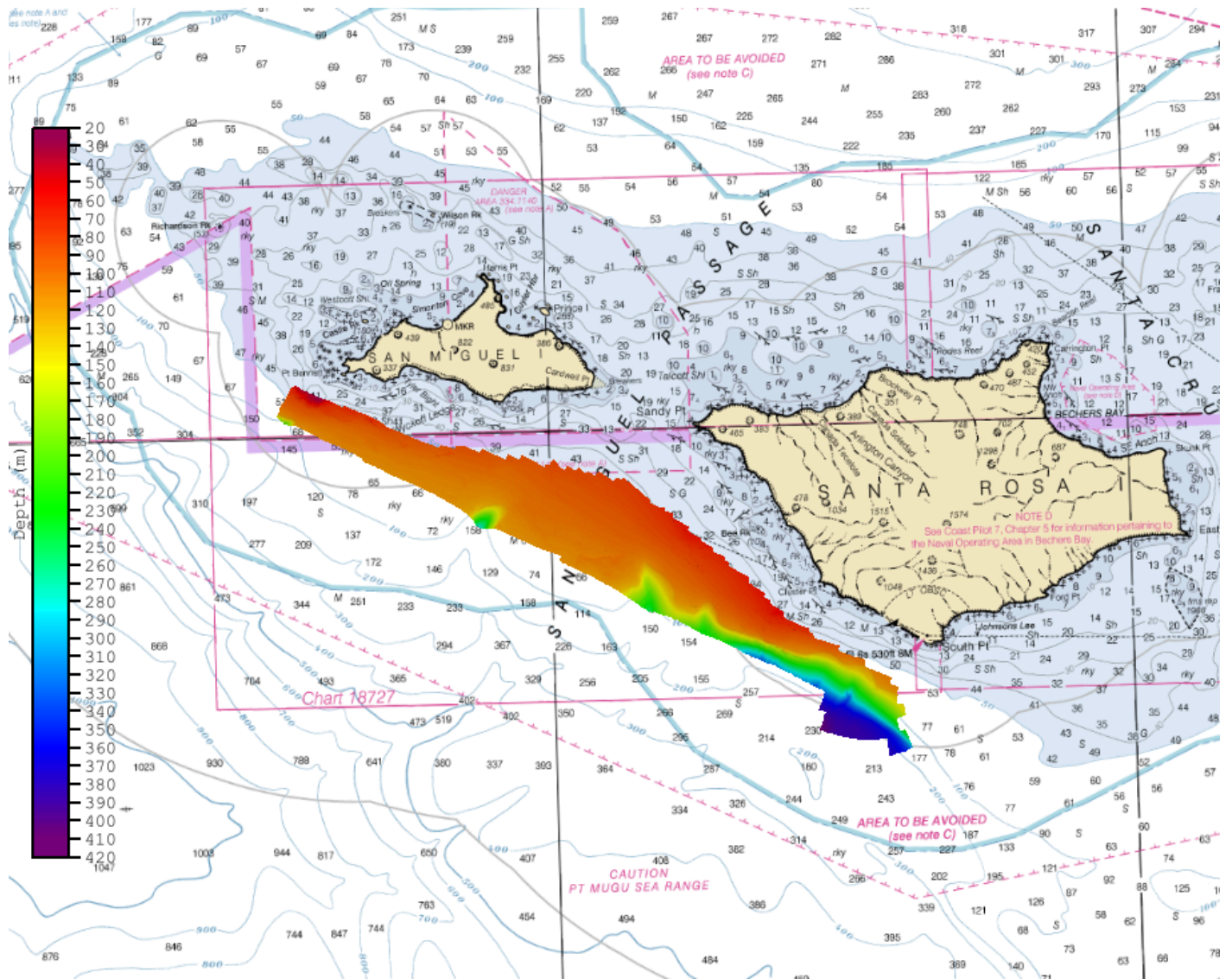


Figure 2: H13554 survey coverage overlaid onto Chart 18720

### A.6 Survey Statistics

The following table lists the mainscheme and crossline acquisition mileage for this survey:



	<b>HULL ID</b>	<i>S220</i>	<i>2805</i>	<i>Total</i>
<b>LNM</b>	<b>SBES Mainscheme</b>	0.0	0.0	0.0
	<b>MBES Mainscheme</b>	209.4195	0.0	209.1495
	<b>Lidar Mainscheme</b>	0.0	0.0	0.0
	<b>SSS Mainscheme</b>	0.0	0.0	0.0
	<b>SBES/SSS Mainscheme</b>	0.0	0.0	0.0
	<b>MBES/SSS Mainscheme</b>	0.0	0.0	0.0
	<b>SBES/MBES Crosslines</b>	0.0	11.4475	11.4475
	<b>Lidar Crosslines</b>	0.0	0.0	0.0
<b>Number of Bottom Samples</b>			0	
<b>Number Maritime Boundary Points Investigated</b>			0	
<b>Number of DPs</b>			0	
<b>Number of Items Investigated by Dive Ops</b>			0	
<b>Total SNM</b>			37.62	

*Table 3: Hydrographic Survey Statistics*

The following table lists the specific dates of data acquisition for this survey:

<b>Survey Dates</b>	<b>Day of the Year</b>
10/06/2021	279
10/07/2021	280

<b>Survey Dates</b>	<b>Day of the Year</b>
10/08/2021	281
10/09/2021	282
10/10/2021	283

*Table 4: Dates of Hydrography*

## **B. Data Acquisition and Processing**

### **B.1 Equipment and Vessels**

Refer to the Data Acquisition and Processing Report (DAPR) for a complete description of data acquisition and processing systems, survey vessels, quality control procedures and data processing methods. Additional information to supplement sounding and survey data, and any deviations from the DAPR are discussed in the following sections.

#### **B.1.1 Vessels**

The following vessels were used for data acquisition during this survey:

<b>Hull ID</b>	<b><i>S220</i></b>	<b><i>2805</i></b>
<b>LOA</b>	70.4 meters	8.6 meters
<b>Draft</b>	4.8 meters	1.1 meters

*Table 5: Vessels Used*

## B.1.2 Equipment

The following major systems were used for data acquisition during this survey:

<b>Manufacturer</b>	<b>Model</b>	<b>Type</b>
Applanix	POS MV 320 v5	Positioning System
Teledyne RESON	SVP 70	Sound Speed System
Teledyne RESON	SVP 71	Sound Speed System
AML Oceanographic	MVP200	Conductivity, Temperature, and Depth Sensor
Sea-Bird Scientific	SBE 19plus V2	Conductivity, Temperature, and Depth Sensor
Kongsberg Maritime	EM 710	MBES
Kongsberg Maritime	EM 2040	MBES

*Table 6: Major Systems Used*

The equipment was installed on the survey platform as follows: S220 utilizes the Kongsberg EM 710 MBES, a POS M/V v5 system for position and attitude, SVP 70 surface sound speed sensors, and AML Oceanographic MVP 200 for conductivity, temperature, and depth (CTD) casts. All launches utilize the Kongsberg EM 2040 MBES, a POS M/V v5 system for position and attitude, SVP 71 surface sound speed sensors, and Sea-Bird SBE 19plus v2 CTDs for conductivity, temperature, and depth casts.

## B.2 Quality Control

### B.2.1 Crosslines

Crosslines were collected, processed and compared in accordance with Section 5.2.4.2 of the HSSD. To evaluate crosslines, a surface generated via data strictly from mainscheme lines and a surface generated via data strictly from crosslines were created. From these two surfaces, a difference surface (mainscheme - crosslines = difference surface) was generated. Statistics show the mean difference between the depths derived from mainscheme data and crossline data was 0.04 meters (with mainscheme being deeper) and 95% of nodes falling within 0.4 meters (Figure 3). For the respective depths, the difference surface was compared to the allowable NOAA uncertainty standards. In total, over 99.5% of the depth differences between H13554 mainscheme and crossline data were within allowable NOAA uncertainties.

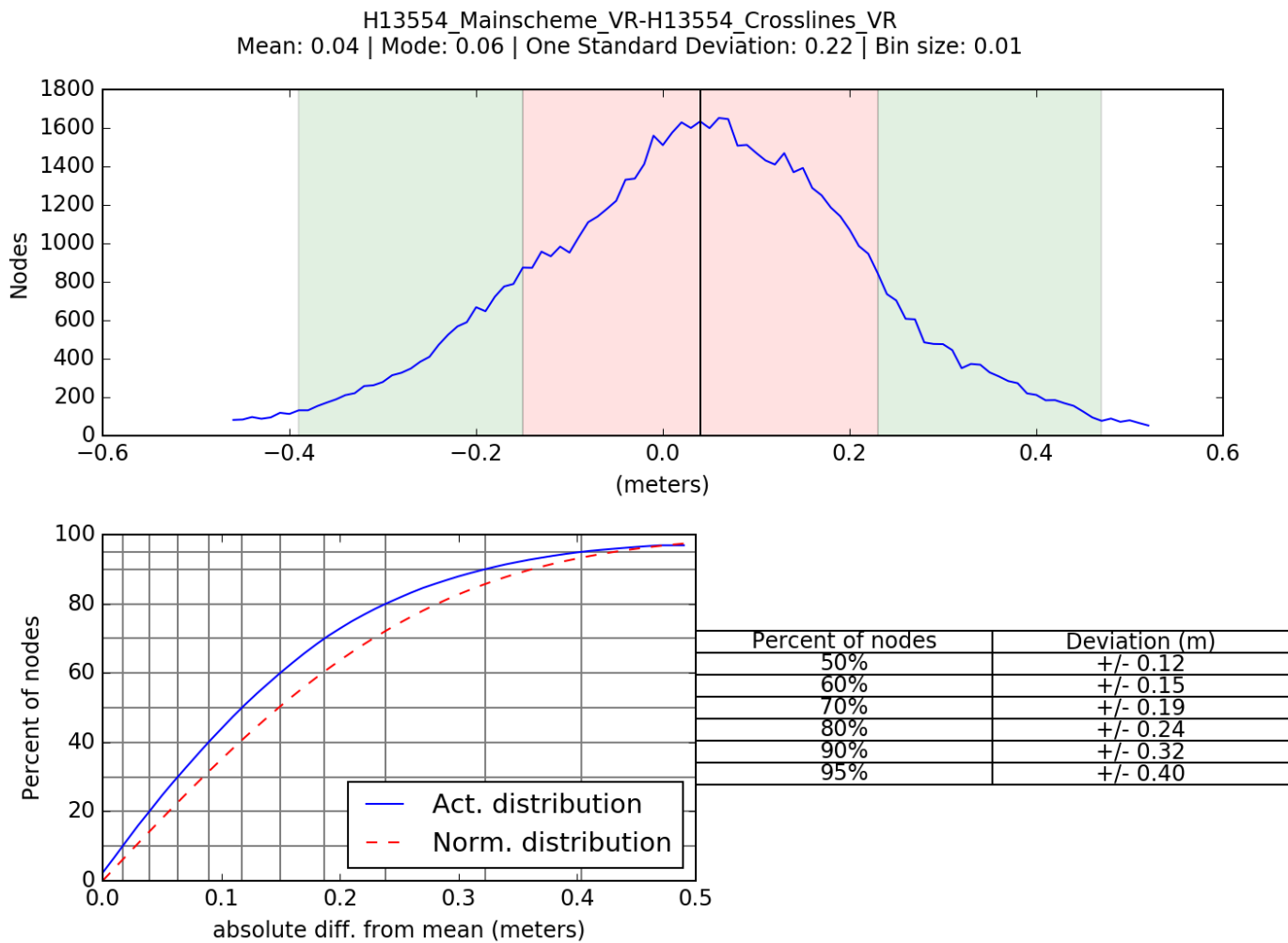


Figure 3: H13554 crossline and mainscheme difference statistics

### B.2.2 Uncertainty

The following survey specific parameters were used for this survey:

Method	Measured	Zoning
ERS via VDATUM	0.0 meters	8.05 centimeters

Table 7: Survey Specific Tide TPU Values.

<b>Hull ID</b>	<b>Measured - CTD</b>	<b>Measured - MVP</b>	<b>Measured - XBT</b>	<b>Surface</b>
S220	N/A meters/second	1 meters/second	N/A meters/second	0.5 meters/second
2805	2 meters/second	N/A meters/second	N/A meters/second	0.5 meters/second

*Table 8: Survey Specific Sound Speed TPU Values.*

In addition to the usual a priori estimates of uncertainty via device models for vessel motion and VDATUM, real-time and post-processed uncertainty sources were also incorporated into the depth estimates of survey H13554. Real-time uncertainties were provided via EM 2040 MBES data and Applanix Delayed Heave RMS. Following post-processing of the real-time vessel motion, recomputed uncertainties of vessel roll, pitch, gyro and navigation were applied in CARIS HIPS and SIPS via a Smoothed Best Estimate of Trajectory (SBET) RMS file generated in Applanix POSPac.

### **B.2.3 Junctions**

H13554 junctions with 1 adjacent surveys from this project, H13552 and 3 surveys from prior projects, H13082, H13084, and H13085, as shown in Figure 4. Data overlap between H13554 and each adjacent survey was achieved. These areas of overlap between surveys were reviewed in CARIS HIPS and SIPS by surface differencing (at equal resolutions) to assess surface agreement. The multibeam data were also examined in CARIS Subset Editor for consistency and agreement. The junctions with H13554 are within the NOAA allowable uncertainty in their areas of overlap. For all junctions with H13554, a negative difference indicates H13554 was shoaler and a positive difference indicates H13554 was deeper.

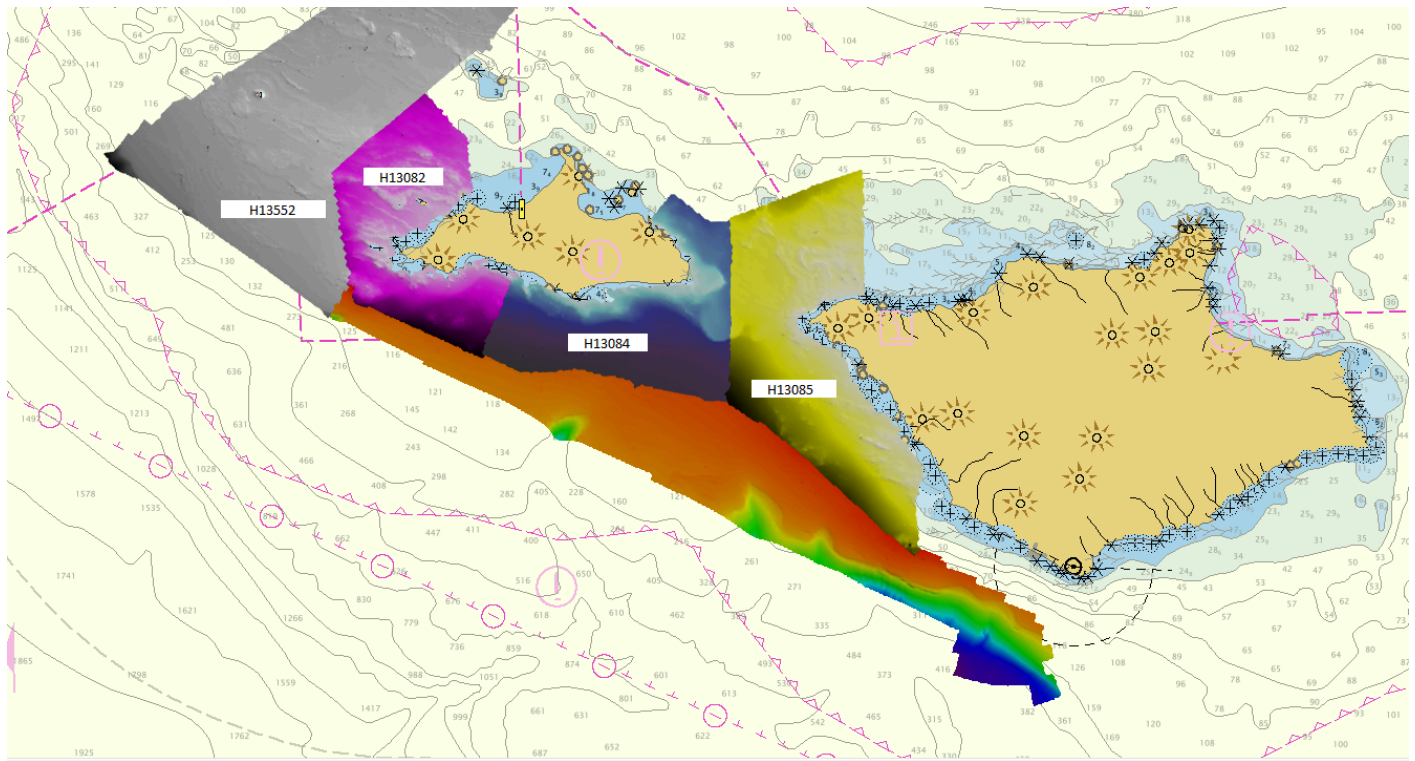


Figure 4: H13554 (Rainbow) and its Junction surveys.

The following junctions were made with this survey:

Registry Number	Scale	Year	Field Unit	Relative Location
H13082	1:20000	2017	NOAA Ship Rainier	N
H13084	1:20000	2017	NOAA Ship Rainier	N
H13085	1:20000	2017	NOAA Ship Rainier	N
H13552	1:10000	2021	NOAA Ship Fairweather	NW

Table 9: Junctioning Surveys

### H13082

Surface differencing in CARIS HIPS and SIPS was used to assess junction agreement between the surface from H13554 and the surface from H13082. The statistical analysis of the difference surface shows a mean of 0.10 meters with 95% of the nodes having a maximum deviation of +/- 3.43 meters, as seen in Figure 5. It was found that 77% of nodes are within NOAA allowable uncertainty. The region of this junction covers several rocky areas and steep slopes, which accounts for the regions with the most significant difference between the two surveys. In the flat regions, there is high agreement.

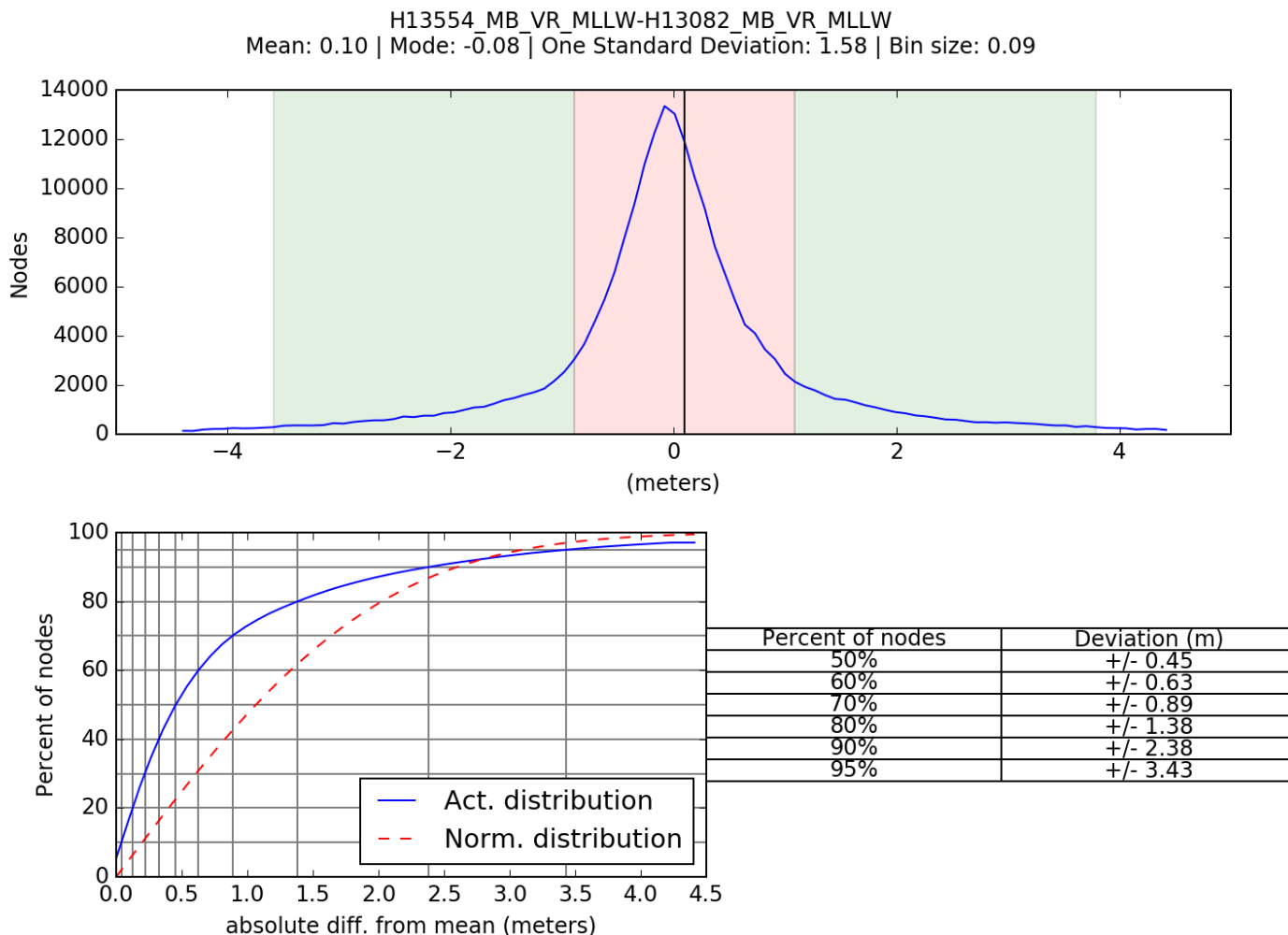


Figure 5: H13554 and H13082 junction difference statistics

### H13084

Surface differencing in CARIS HIPS and SIPS was used to assess junction agreement between the surface from H13554 and the surface from H13084. The statistical analysis of the difference surface shows a mean of 0.06 meters with 95% of the nodes having a maximum deviation of +/- 0.6 meters, as seen in Figure 6. It was found that 99.5% of nodes are within NOAA allowable uncertainty.

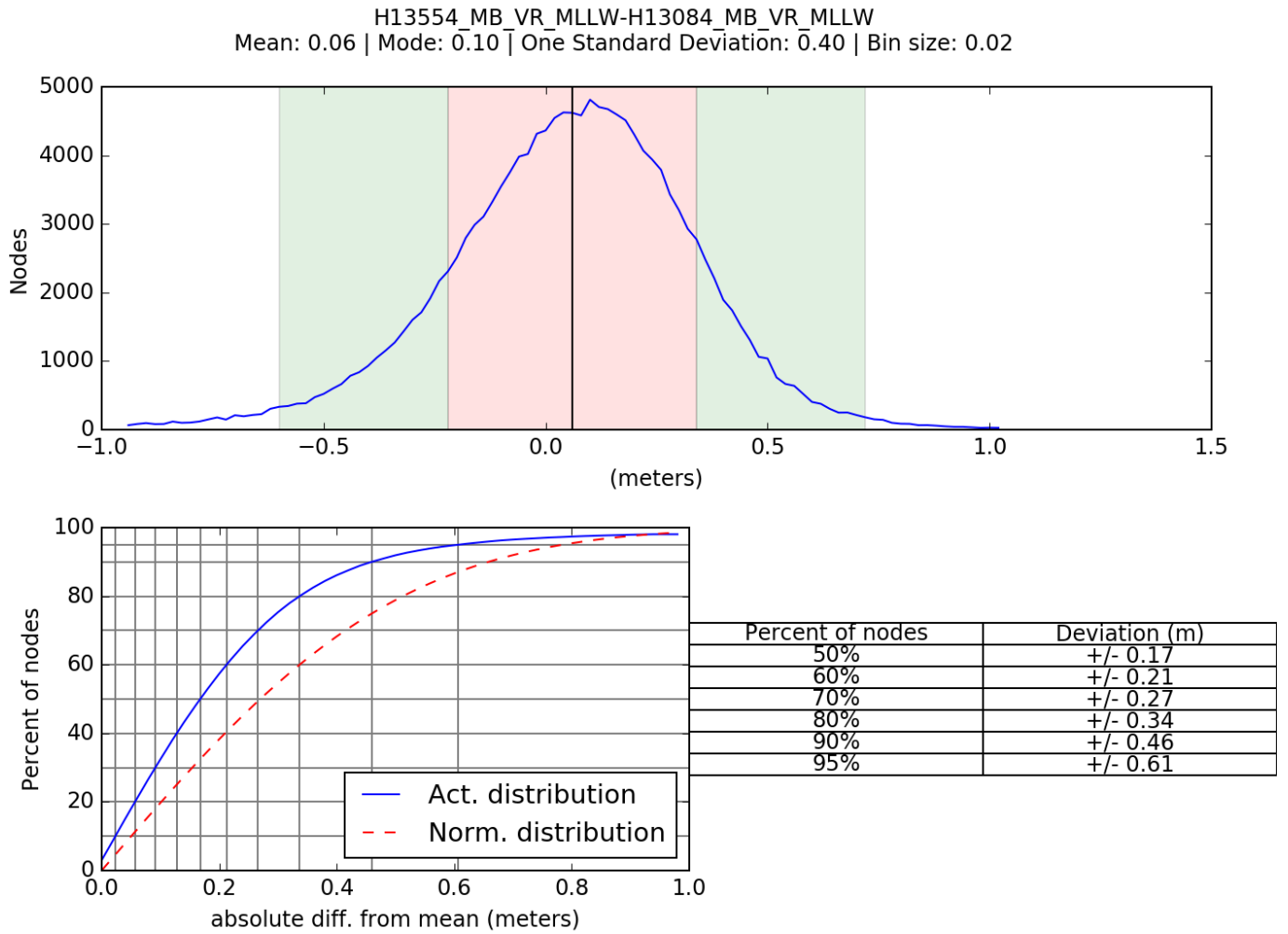


Figure 6: H13554 and H13084 junction difference statistics

H13085

Surface differencing in CARIS HIPS and SIPS was used to assess junction agreement between the surface from H13554 and the surface from H13085 (Figure 7). The statistical analysis of the difference surface shows a mean of 0.15 meters with 95% of the nodes having a maximum deviation of +/- 0.94 meters, as seen in Figure 7. It was found that 98% of nodes are within NOAA allowable uncertainty.



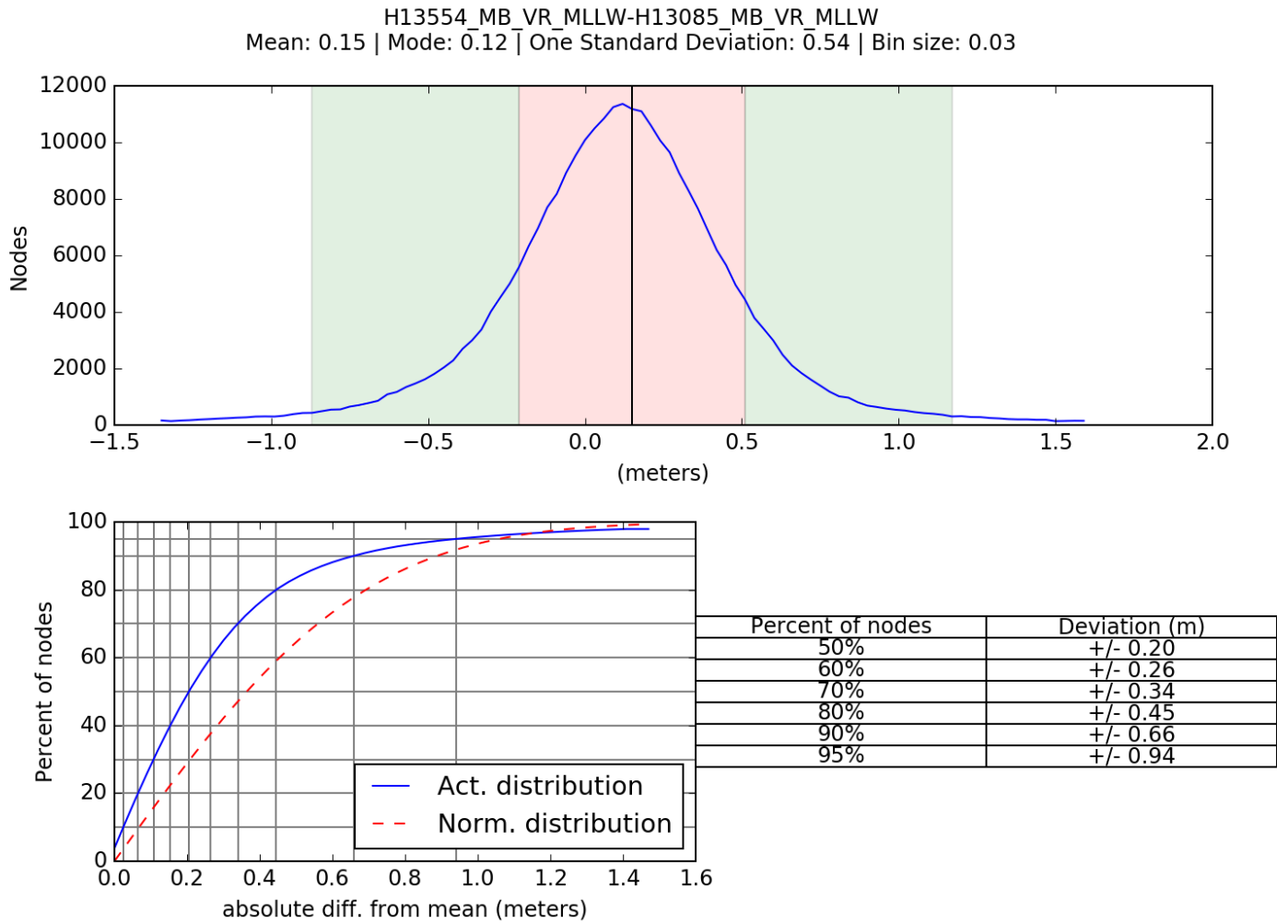


Figure 7: H13554 and H13085 junction difference statistics

H13552

Surface differencing in CARIS HIPS and SIPS was used to assess junction agreement between the surface from H13554 and the surface from H13082. The statistical analysis of the difference surface shows a mean of 0.04 meters with 95% of the nodes having a maximum deviation of +/- 0.93meters, as seen in Figure 8. It was found that 97% of nodes are within NOAA allowable uncertainty.

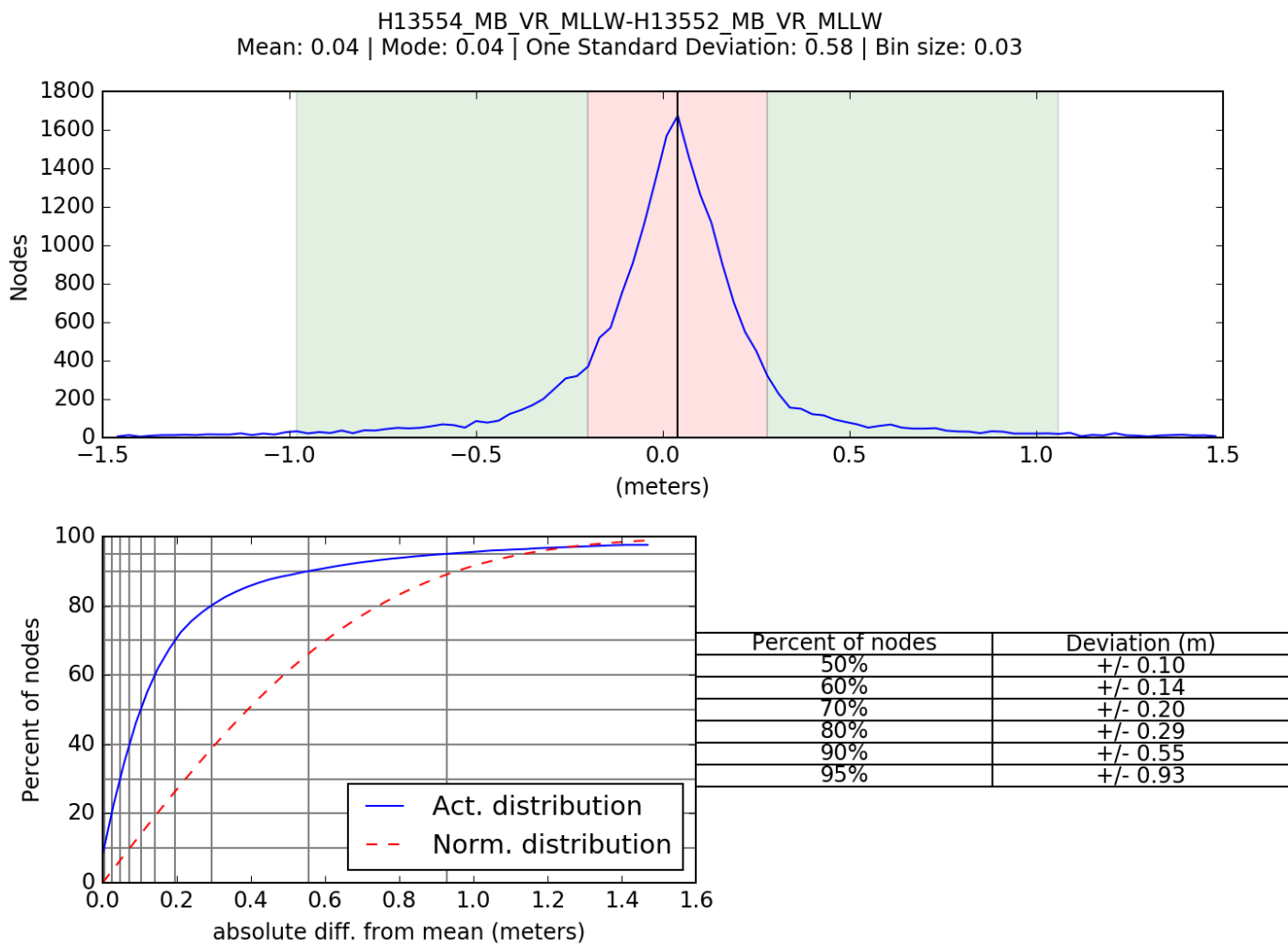


Figure 8: H13554 and H13552 junction difference statistics

### B.2.4 Sonar QC Checks

Sonar system quality control checks were conducted as detailed in the quality control section of the DAPR.

### B.2.5 Equipment Effectiveness

There were no conditions or deficiencies that affected equipment operational effectiveness.

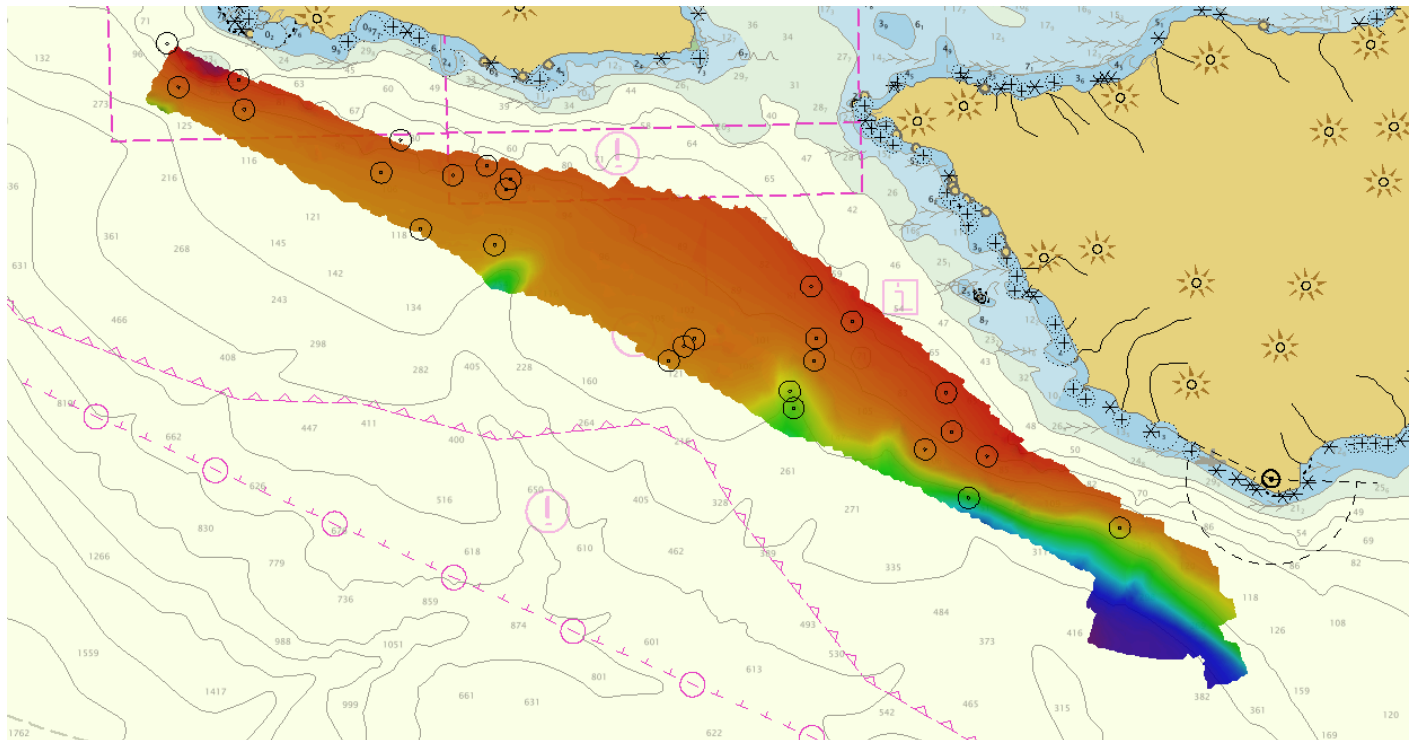
## B.2.6 Factors Affecting Soundings

There were no other factors that affected corrections to soundings.

## B.2.7 Sound Speed Methods

Sound Speed Cast Frequency: Casts were conducted at a minimum of one every four hours.

Casts were conducted more frequently in areas where the influx of freshwater had an effect on the speed of sound in the water column and when there was a change in surface sound speed greater than two meters per second. MVP casts on S220 were conducted at an average interval of 49 minutes, guided by observation of the surface sound speed and targeted to deeper areas. All sound speed methods were used as detailed in the DAPR.



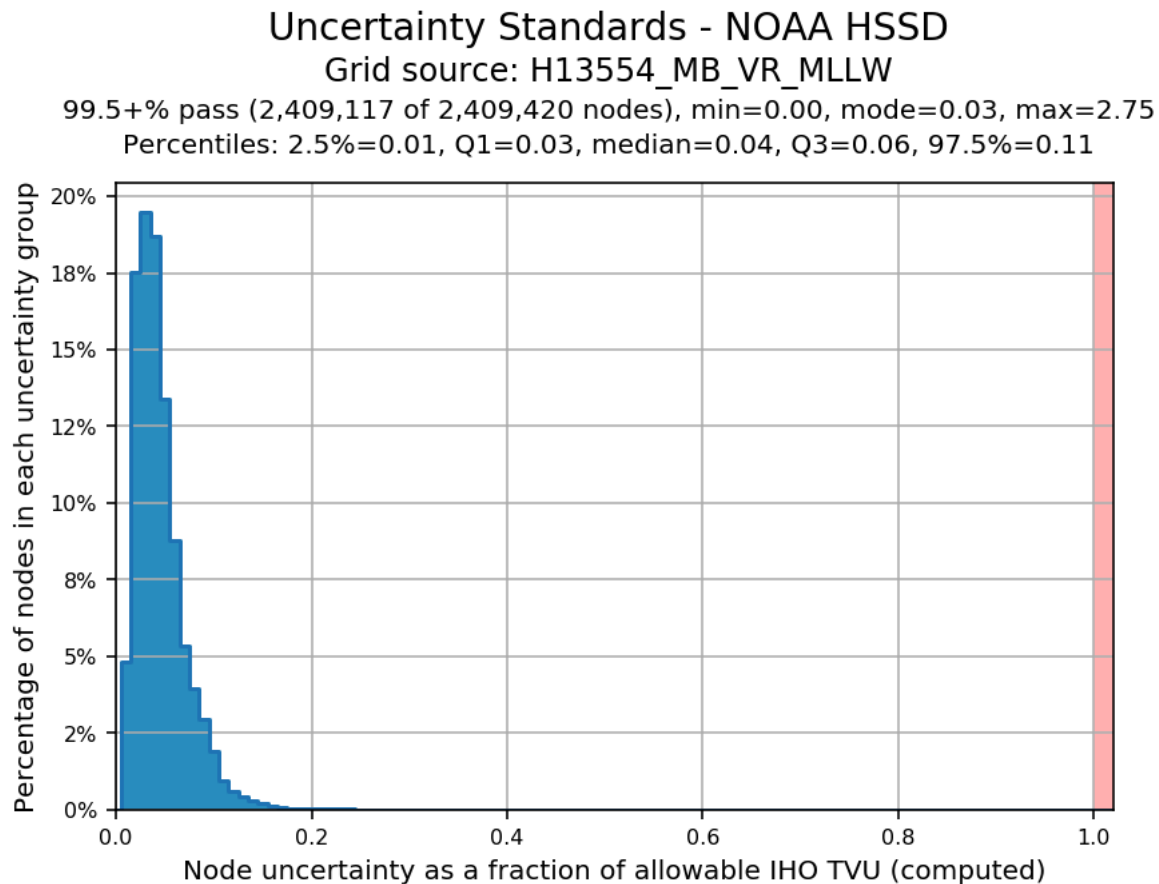
*Figure 9: MVP cast locations*

## B.2.8 Coverage Equipment and Methods

All equipment and survey methods were used as detailed in the DAPR.

### B.2.9 NOAA Allowable Uncertainty

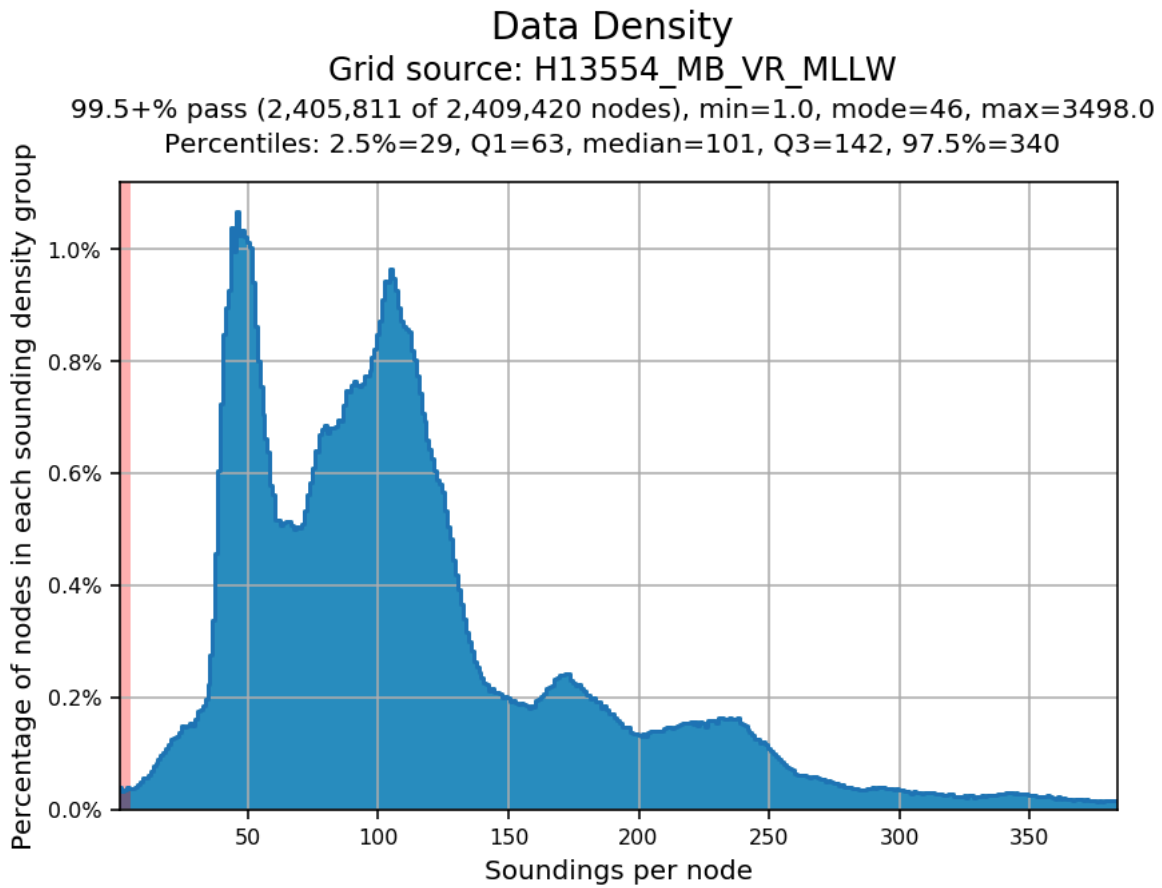
The surface was analyzed using the HydrOffice QC Tools Grid QA feature to determine compliance with specifications. Overall, 99% of nodes within the surface meet NOAA Allowable Uncertainty specifications for H13554.



*Figure 10: H13554 allowable uncertainty statistics*

### B.2.10 Density

The surface was analyzed using the HydrOffice QC Tools Grid QA feature to determine compliance with specifications. Density requirements for H13554 were achieved with at least 99% of surface nodes containing five or more soundings as required by HSSD Section 5.2.2.3.



*Figure 11: H13554 data density statistics*

## **B.3 Echo Sounding Corrections**

### **B.3.1 Corrections to Echo Soundings**

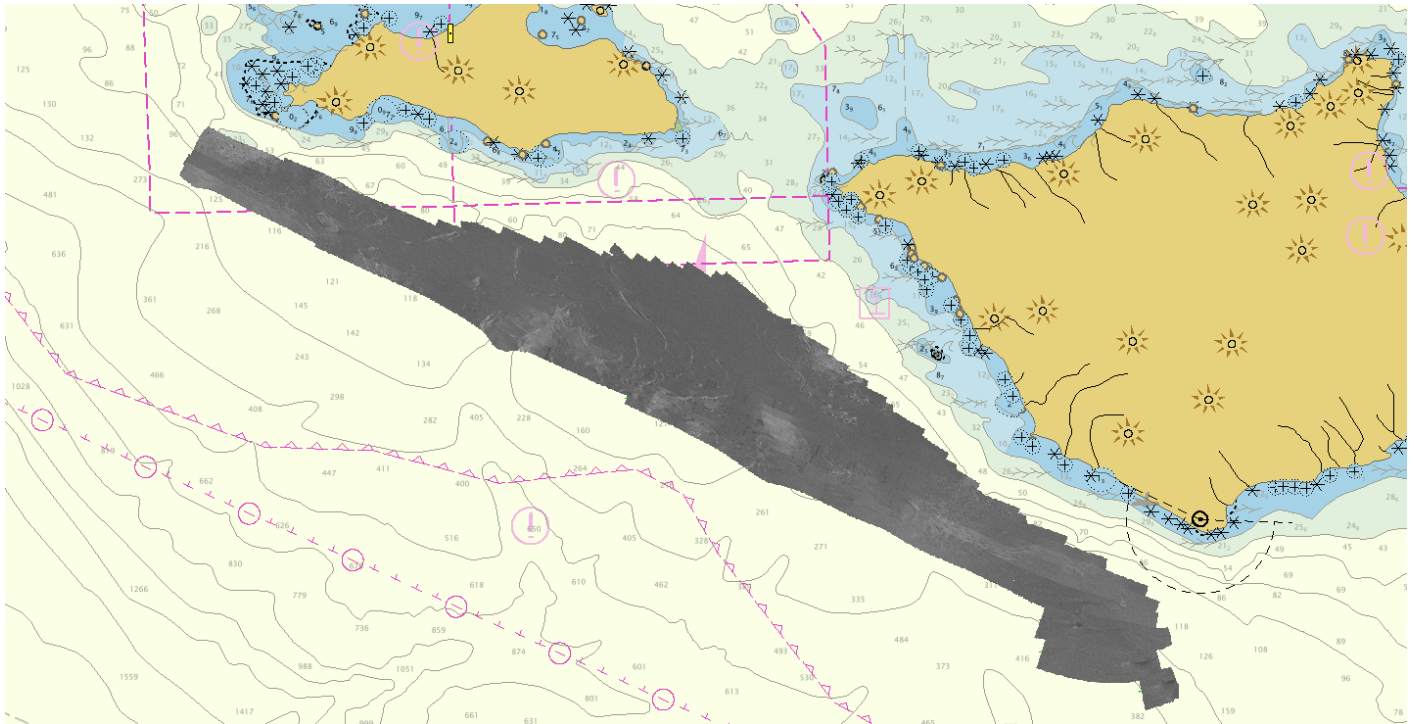
All data reduction procedures conform to those detailed in the DAPR.

### **B.3.2 Calibrations**

All sounding systems were calibrated as detailed in the DAPR.

## B.4 Backscatter

Raw backscatter data were stored in the .all file for Kongsberg systems. All backscatter were processed to GSF files and a floating point mosaic was created by the field unit via Fledermaus FMGT 7.9.0. See Figure 12 for a greyscale representation of the complete mosaic.



*Figure 12: Backscatter mosaic for H13554*

## B.5 Data Processing

### B.5.1 Primary Data Processing Software

The following software program was the primary program used for bathymetric data processing:

Manufacturer	Name	Version
CARIS	HIPS and SIPS	11.4

*Table 10: Primary bathymetric data processing software*

The following software program was the primary program used for imagery data processing:

<b>Manufacturer</b>	<b>Name</b>	<b>Version</b>
QPS	Fledermaus	7.9.0

*Table 11: Primary imagery data processing software*

The following Feature Object Catalog was used: NOAA Profile Version 2021.

### **B.5.2 Surfaces**

The following surfaces and/or BAGs were submitted to the Processing Branch:

<b>Surface Name</b>	<b>Surface Type</b>	<b>Resolution</b>	<b>Depth Range</b>	<b>Surface Parameter</b>	<b>Purpose</b>
H13554_MB_VR_MLLW.csar	CARIS VR Surface (CUBE)	Variable Resolution	25.0 meters - 411.7 meters	NOAA_VR	Complete MBES
H13554_MB_VR_MLLW_Final.csar	CARIS VR Surface (CUBE)	Variable Resolution	25.0 meters - 411.7 meters	NOAA_VR	Complete MBES

*Table 12: Submitted Surfaces*

The NOAA CUBE parameters defined in the HSSD were used for the creation of all CUBE surfaces for H13554. The surfaces have been reviewed where noisy data, or "fliers" are incorporated into the gridded solutions causing the surface to be shoaler or deeper than the true sea floor. Where these spurious soundings cause the gridded surface to vary from the reliably measured seabed by greater than the maximum allowable Total Vertical Uncertainty at that depth, the noisy data have been rejected by the hydrographer and the surface recomputed.

Flier Finder v9, part of the QC Tools package within HydrOffice, was used to assist the search for spurious soundings following gross cleaning. Flier Finder was run iteratively until all remaining flagged fliers were deemed to be valid aspects of the surface. There are 144 remaining fliers, which are along the edge of the surface and are in a dynamic area. They have been deemed to be a part of the surface and are false positives.

## C. Vertical and Horizontal Control

Per Section 5.2.2.1.3 of the 2020 Field Procedures Manual, no Horizontal and Vertical Control Report has been generated for H13554.

### C.1 Vertical Control

The vertical datum for this project is Mean Lower Low Water.

#### ERS Datum Transformation

The following ellipsoid-to-chart vertical datum transformation was used:

Method	Ellipsoid to Chart Datum Separation File
ERS via VDATUM	OPR-L397-FA-21_100m_NAD83_2011- MLLW_geoid18.csar

*Table 13: ERS method and SEP file*

### C.2 Horizontal Control

The horizontal datum for this project is North American Datum of 1983 (NAD 83).

The projection used for this project is Universal Transverse Mercator (UTM) Zone 10.

The following PPK methods were used for horizontal control:

- RTX

Vessel kinematic data were post-processed using Applanix POSPac processing software and RTX positioning methods described in the DAPR. Smoothed Best Estimate of Trajectory (SBET) and associated error (RMS) data were applied to all MBES data in CARIS HIPS and SIPS.

#### WAAS

During real-time acquisition, all platforms received correctors from the Wide Area Augmentation System (WAAS) for increased accuracies similar to USCG DGPS stations. WAAS and SBETs were the sole methods of positioning for H13554 as no DGPS stations were available for real-time horizontal control.



## D. Results and Recommendations

### D.1 Chart Comparison

#### D.1.1 Electronic Navigational Charts

The following are the largest scale ENC's, which cover the survey area:

ENC	Scale	Edition	Update Application Date	Issue Date
US5CA64M	1:40000	16	01/18/2022	01/18/2022
US5CA66M	1:40000	12	03/29/2022	03/29/2022
US4CA68M	1:100000	16	04/07/2022	05/05/2022
US3CA69M	1:232188	28	01/18/2022	05/05/2022

*Table 14: Largest Scale ENC's*

#### D.1.2 Shoal and Hazardous Features

No shoals or potentially hazardous features exist for this survey.

#### D.1.3 Charted Features

No charted features exist for this survey.

#### D.1.4 Uncharted Features

No uncharted features exist for this survey.

#### D.1.5 Channels

No channels exist for this survey. There are no designated anchorages, precautionary areas, safety fairways, traffic separation schemes, pilot boarding areas, or channel and range lines within the survey limits.

## **D.2 Additional Results**

### **D.2.1 Aids to Navigation**

No Aids to navigation (ATONs) exist for this survey.

### **D.2.2 Maritime Boundary Points**

No Maritime Boundary Points were assigned for this survey.

### **D.2.3 Bottom Samples**

No bottom samples were required for this survey.

### **D.2.4 Overhead Features**

No overhead features exist for this survey.

### **D.2.5 Submarine Features**

No submarine features exist for this survey.

### **D.2.6 Platforms**

No platforms exist for this survey.

### **D.2.7 Ferry Routes and Terminals**

No ferry routes or terminals exist for this survey.

### **D.2.8 Abnormal Seafloor or Environmental Conditions**

No abnormal seafloor or environmental conditions exist for this survey.

### **D.2.9 Construction and Dredging**

No present or planned construction or dredging exist within the survey limits.

**D.2.10 New Survey Recommendations**

No new surveys or further investigations are recommended for this area.

**D.2.11 ENC Scale Recommendations**

No new ENC scales are recommended for this area.

## E. Approval Sheet

As Chief of Party, field operations for this hydrographic survey were conducted under my direct supervision, with frequent personal checks of progress and adequacy. I have reviewed the attached survey data and reports.

All field sheets, this Descriptive Report, and all accompanying records and data are approved. All records are forwarded for final review and processing to the Processing Branch.

The survey data meets or exceeds requirements as set forth in the NOS Hydrographic Surveys Specifications and Deliverables, Field Procedures Manual, Letter Instructions, and all HSD Technical Directives. These data are adequate to supersede charted data in their common areas. This survey is complete and no additional work is required with the exception of deficiencies noted in the Descriptive Report.

Approver Name	Approver Title	Approval Date	Signature
CAPT John Lomnicky	Chief of Party	06/22/2022	 <small>Digitally signed by LOMNICKY.JOHN.JOSEPH.1257920239 Reason: I have reviewed this document Location: CO, NOAA Ship FAIRWEATHER Date: 2022.06.24 09:31:52 -07'00'</small>
LT Michael Card	Operations Officer	06/22/2022	<small>CARD.MICHAEL.DOUGLAS.1011746507</small> <small>46507</small> <small>Digitally signed by CARD.MICHAEL.DOUGLAS.1011746507 Date: 2022.06.24 09:17:40 -07'00'</small>
PS Charles Corea	Physical Scientist	06/22/2022	<small>COREA.CHARLES.NICHOLAS.1469690691</small> <small>90691</small> <small>Digitally signed by COREA.CHARLES.NICHOLAS.1469690691 Date: 2022.06.22 15:37:33 -07'00'</small>

## F. Table of Acronyms

<b>Acronym</b>	<b>Definition</b>
<b>AHB</b>	Atlantic Hydrographic Branch
<b>AST</b>	Assistant Survey Technician
<b>ATON</b>	Aid to Navigation
<b>AWOIS</b>	Automated Wreck and Obstruction Information System
<b>BAG</b>	Bathymetric Attributed Grid
<b>BASE</b>	Bathymetry Associated with Statistical Error
<b>CO</b>	Commanding Officer
<b>CO-OPS</b>	Center for Operational Products and Services
<b>CORS</b>	Continuously Operating Reference Station
<b>CTD</b>	Conductivity Temperature Depth
<b>CEF</b>	Chart Evaluation File
<b>CSF</b>	Composite Source File
<b>CST</b>	Chief Survey Technician
<b>CUBE</b>	Combined Uncertainty and Bathymetry Estimator
<b>DAPR</b>	Data Acquisition and Processing Report
<b>DGPS</b>	Differential Global Positioning System
<b>DP</b>	Detached Position
<b>DR</b>	Descriptive Report
<b>DTON</b>	Danger to Navigation
<b>ENC</b>	Electronic Navigational Chart
<b>ERS</b>	Ellipsoidal Referenced Survey
<b>ERTDM</b>	Ellipsoidally Referenced Tidal Datum Model
<b>ERZT</b>	Ellipsoidally Referenced Zoned Tides
<b>FFF</b>	Final Feature File
<b>FOO</b>	Field Operations Officer
<b>FPM</b>	Field Procedures Manual
<b>GAMS</b>	GPS Azimuth Measurement Subsystem
<b>GC</b>	Geographic Cell
<b>GPS</b>	Global Positioning System
<b>HIPS</b>	Hydrographic Information Processing System
<b>HSD</b>	Hydrographic Surveys Division

<b>Acronym</b>	<b>Definition</b>
<b>HSSD</b>	Hydrographic Survey Specifications and Deliverables
<b>HSTB</b>	Hydrographic Systems Technology Branch
<b>HSX</b>	Hypack Hysweep File Format
<b>HTD</b>	Hydrographic Surveys Technical Directive
<b>HVCR</b>	Horizontal and Vertical Control Report
<b>HVF</b>	HIPS Vessel File
<b>IHO</b>	International Hydrographic Organization
<b>IMU</b>	Inertial Motion Unit
<b>ITRF</b>	International Terrestrial Reference Frame
<b>LNM</b>	Linear Nautical Miles
<b>MBAB</b>	Multibeam Echosounder Acoustic Backscatter
<b>MCD</b>	Marine Chart Division
<b>MHW</b>	Mean High Water
<b>MLLW</b>	Mean Lower Low Water
<b>NAD 83</b>	North American Datum of 1983
<b>NALL</b>	Navigable Area Limit Line
<b>NTM</b>	Notice to Mariners
<b>NMEA</b>	National Marine Electronics Association
<b>NOAA</b>	National Oceanic and Atmospheric Administration
<b>NOS</b>	National Ocean Service
<b>NRT</b>	Navigation Response Team
<b>NSD</b>	Navigation Services Division
<b>OCS</b>	Office of Coast Survey
<b>OMAO</b>	Office of Marine and Aviation Operations (NOAA)
<b>OPS</b>	Operations Branch
<b>MBES</b>	Multibeam Echosounder
<b>NWLON</b>	National Water Level Observation Network
<b>PDBS</b>	Phase Differencing Bathymetric Sonar
<b>PHB</b>	Pacific Hydrographic Branch
<b>POS/MV</b>	Position and Orientation System for Marine Vessels
<b>PPK</b>	Post Processed Kinematic
<b>PPP</b>	Precise Point Positioning
<b>PPS</b>	Pulse per second

<b>Acronym</b>	<b>Definition</b>
<b>PRF</b>	Project Reference File
<b>PS</b>	Physical Scientist
<b>RNC</b>	Raster Navigational Chart
<b>RTK</b>	Real Time Kinematic
<b>RTX</b>	Real Time Extended
<b>SBES</b>	Singlebeam Echosounder
<b>SBET</b>	Smooth Best Estimate and Trajectory
<b>SNM</b>	Square Nautical Miles
<b>SSS</b>	Side Scan Sonar
<b>SSSAB</b>	Side Scan Sonar Acoustic Backscatter
<b>ST</b>	Survey Technician
<b>SVP</b>	Sound Velocity Profiler
<b>TCARI</b>	Tidal Constituent And Residual Interpolation
<b>TPU</b>	Total Propagated Uncertainty
<b>USACE</b>	United States Army Corps of Engineers
<b>USCG</b>	United States Coast Guard
<b>UTM</b>	Universal Transverse Mercator
<b>XO</b>	Executive Officer
<b>ZDF</b>	Zone Definition File