U.S. Department of Commerce National Oceanic and Atmospheric Administration National Ocean Service				
]	DESCRIPTIVE REPORT			
Type of Survey:	Basic Hydrographic Survey			
Registry Number:	H13765			
	LOCALITY			
State(s):	Maryland Virginia			
General Locality:	Southwest Chesapeake Bay			
Sub-locality:	Mathias Point Neck to Alexandria			
	2023			
	CHIEF OF PARTY David Neff, C.H.			
	LIBRARY & ARCHIVES			
Date:				

U.S. DEPARTMENT OF COMMERCE REGISTRY NUMBER: NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION						
HYDROGRAPHIC TITLE SHEETH13765						
INSTRUCTIONS: The	Hydrographic Sheet should be accompanied by this form, filled in as completely as possil	ble, when the sheet is forwarded to the Office				
State(s):	Maryland Virginia					
General Locality:	Southwest Chesapeake Bay					
Sub-Locality:	Mathais Point Neck to Alexandria					
Scale:	10000					
Dates of Survey:	02/05/2023 to 05/21/2023					
Instructions Dated:	03/08/2023					
Project Number:	OPR-E351-KR-22					
Field Unit:	eTrac					
Chief of Party:	David Neff, C.H.					
Soundings by:	Multibeam Echo Sounder					
Imagery by:	Multibeam Echo Sounder Backscatter Side Scan Sonar					
Verification by:	Atlantic Hydrographic Branch					
Soundings Acquired in:	meters at Mean Lower Low Water					
erification by:	Atlantic Hydrographic Branch	r Side Scan So				

Remarks:

All times are UTC. The purpose of this survey is to update existing NOS nautical charts. H13765 covers approximately 79 square nautical miles of the Potomac River from Mathais Point Neck to Alexandria, Maryland and Virginia.

Any revisions to the Descriptive Report (DR) applied during office processing are shown in red italic text. The DR is maintained as a field unit product, therefore all information and recommendations within this report are considered preliminary unless otherwise noted. The final disposition of survey data is represented in the NOAA nautical chart products. All pertinent records for this survey are archived at the National Centers for Environmental Information (NCEI) and can be retrieved via https://www.ncei.noaa.gov/. Products created during office processing were generated in NAD83 UTM 18N, MLLW. All references to other horizontal or vertical datums in this report are applicable to the processed hydrographic data provided by the field unit.

Table of Contents

A. Area Surveyed	1
A.1 Survey Limits	1
A.2 Survey Purpose	3
A.3 Survey Quality	
A.4 Survey Coverage	4
A.6 Survey Statistics	6
B. Data Acquisition and Processing	9
B.1 Equipment and Vessels	9
B.1.1 Vessels	9
B.1.2 Equipment	
B.2 Quality Control	
B.2.1 Crosslines	
B.2.2 Uncertainty	
B.2.3 Junctions.	
B.2.4 Sonar QC Checks	
B.2.5 Equipment Effectiveness	
B.2.6 Factors Affecting Soundings	
B.2.7 Sound Speed Methods	
B.2.8 Coverage Equipment and Methods	
B.2.9 Data Density Evaluation	
B.3 Echo Sounding Corrections	19
B.3.1 Corrections to Echo Soundings	
B.3.2 Calibrations	
B.4 Backscatter	
B.5 Data Processing	
B.5.1 Primary Data Processing Software	
B.5.2 Surfaces	
B.5.3 Additional Task: Final Data Submission - Grids	24
C. Vertical and Horizontal Control	25
C.1 Vertical Control	
C.2 Horizontal Control	
C.3 Additional Horizontal or Vertical Control Issues	
C.3.1 Additional Task: Final Data Submission- Grids	
D. Results and Recommendations	
D.1 Chart Comparison	
D.1.1 Electronic Navigational Charts	
D.1.2 Shoal and Hazardous Features	
D.1.3 Charted Features	
D.1.4 Uncharted Features	
D.1.5 Channels	
D.2 Additional Results	
D.2.1 Aids to Navigation	
D.2.2 Maritime Boundary Points	

D.2.3 Bottom Samples	
D.2.4 Overhead Features	
D.2.5 Submarine Features	
D.2.6 Platforms	
D.2.7 Ferry Routes and Terminals	
D.2.8 Abnormal Seafloor or Environmental Conditions	
D.2.9 Construction and Dredging	
D.2.10 New Survey Recommendations	
D.2.11 ENC Scale Recommendations	
E. Approval Sheet	
F. Table of Acronyms	

List of Tables

le 1: Survey Limits1	L
le 2: Survey Coverage4	ł
le 3: Hydrographic Survey Statistics	
le 4: Dates of Hydrography9)
le 5: Vessels Used	
le 6: Major Systems Used10)
le 7: Survey Specific Tide TPU Values)
le 8: Survey Specific Sound Speed TPU Values12	2
le 9: Junctioning Surveys14	1
le 10: Submitted Surfaces	Ĺ
le 11: ERS method and SEP file	5
le 12: Largest Scale ENCs	3
le 10: Submitted Surfaces	

List of Figures

Figure 1: Survey Limits Overview (light blue area)	2
Figure 2: Survey Limits (black line)	
Figure 3: Survey Coverage with combinded MBES and SSS	
Figure 4: Coverage Gaps due to Fishing Gear	6
Figure 5: H13765 Crossline Comparison	
Figure 6: H13765 Finalized 1m MBES TVU Statistics	13
Figure 7: H13765 - H13766 Junction Comparison	15
Figure 8: H13765 - H13766 Difference Statistics	15
Figure 9: H13765 - H11693 Junction Comparison	16
Figure 10: H13765 - H17693 Difference Statistics	16
Figure 11: H13765 - F00628 Junction Comparison	17
Figure 12: H13765 - F00628 Difference Statistics	17
Figure 13: H13765 Finalized 1m Set Line Spacing MBES Density Distribution	19
Figure 14: H13765 Finalized 1m CUBE Weighted Dynamic Surface Coverage	
Figure 15: H13765 Finalized 2m MBAB mosaics	23

Figure	16:	H13765 Finalized 1m SSS mosaic	24
Figure	17:	Generated Soundings used for Chart Comparison (US5MD44M)	27
U		Generated Soundings used for Chart Comparison (US5MD43M)	

Descriptive Report to Accompany Survey H13765

Project: OPR-E351-KR-22 Locality: Southwest Chesapeake Bay Sublocality: Mathais Point Neck to Alexandria Scale: 1:10000 February 2023 - May 2023 **eTrac**

Chief of Party: David Neff, C.H.

A. Area Surveyed

eTrac conducted hydrographic survey operations in the Potomac River, Maryland and Virginia. H13765 covers approximately 79 square nautical miles of survey area from Mathais Point Neck to Alexandria. 2042.83 linear nautical miles were acquired during the survey.

Survey was conducted within these limits between February 05, 2023 (DN036) and May 21, 2023, (DN141).

A.1 Survey Limits

Data were acquired within the following survey limits:

Northwest Limit	Southeast Limit
38° 48' 17.07" S	38° 20' 7.09" S
77° 22' 56.34" W	76° 59' 18.34" W

Table 1: Survey Limits

All data were acquired in accordance with the requirements in the project Instructions and specifications set forth in the Hydrographic Survey Specifications and Deliverables 2022 Edition (HSSD 2022).

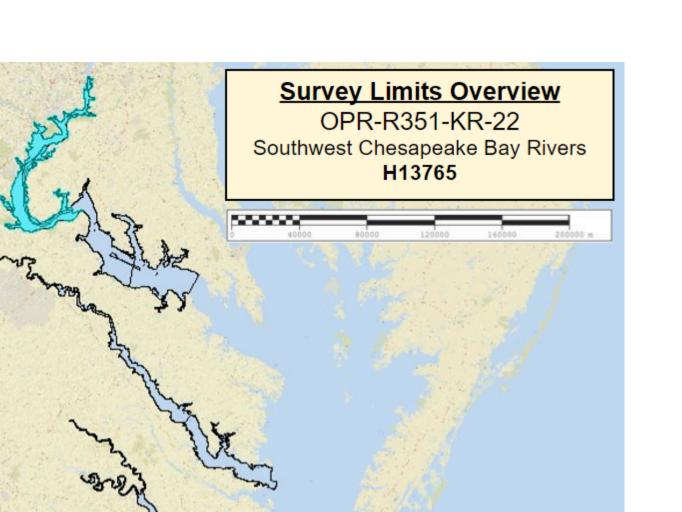


Figure 1: Survey Limits Overview (light blue area)

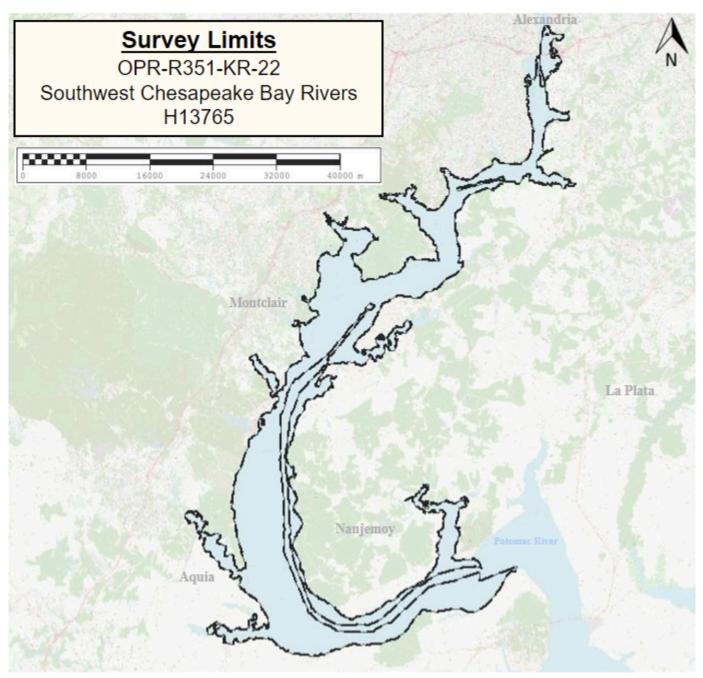


Figure 2: Survey Limits (black line)

A.2 Survey Purpose

The principal objective of the Southwest Chesapeake Bay Rivers project is manifold. Firstly, the surveys will supply forecasters and decision makers at the NOAA National Water Center with bathymetric data for critical hydrodynamic modeling. This data is necessary to understand the timing of rapid river stage increases and decreases, the duration of high water, inundation, or drought. This data will support the Potomac River's reservoir and dam infrastructure controlling effect which depend on the river

hydrodynamics. Secondly, this survey will inform best preservation practices for NOAA's National Marine Sanctuary - Mallows Bay, last surveyed in 1972, to operate, conserve, and promote its maritime historic and cultural resources. Finally, this survey will emphasize features that effect safe navigation and update the Office of Coast Survey Nautical charts and services.

A.3 Survey Quality

The entire survey is adequate to supersede previous data.

Survey H13765 is accurate to International Hydrographic Organization (IHO) Order 1a as required per the HSSD 2022.

A.4 Survey Coverage

The following table lists the coverage requirements for this survey as assigned in the project instructions:

Water Depth	Coverage Required		
All waters in survey area	Complete Coverage Option B		
All waters in survey area 2 to 8 m water depth	Sidescan Sonar Data may be aquired at an altitude of 6-20% of the range-scale		

Table 2: Survey Coverage

Survey coverage was in accordance with the requirements listed above and in the HSSD 2022.

Note: Survey coverage did not extend to the entire survey boundary as the Navigable Area Limit Line (NALL) was reached.

Additionally, coverage gaps occurred due to fishing gear that was not safe to approach. An example of a coverage gap is shown below:

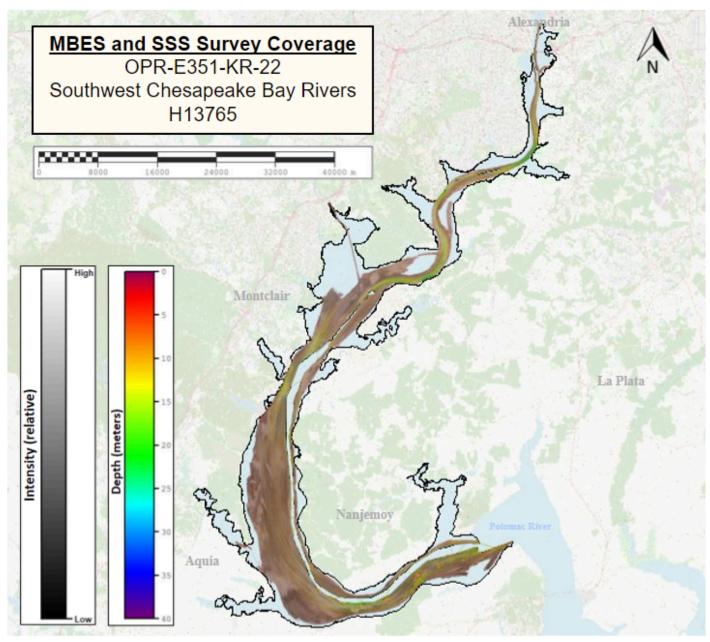


Figure 3: Survey Coverage with combinded MBES and SSS

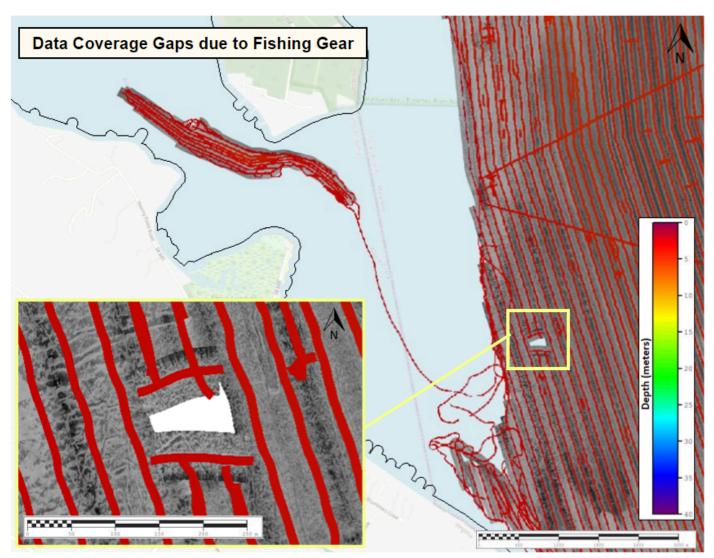


Figure 4: Coverage Gaps due to Fishing Gear

A.6 Survey Statistics

The following table lists the mainscheme and crossline acquisition mileage for this survey:

	HULL ID	R/V Endeavor	R/V Pulse	R/V Spectrum	R/V Taku	R/V Voxel	R/V 505	Total
	SBES Mainscheme	0.0	0.0	0.0	0.0	0.0	0.0	0.0
	MBES Mainscheme	0.0	0.0	0.0	0.0	0.0	0.0	0.0
	Lidar Mainscheme	0.0	0.0	0.0	0.0	0.0	0.0	0.0
TNINT	SSS Mainscheme	10.0	0.0	0.0	0.0	0.0	0.0	0.0
LNM	SBES/SSS Mainscheme	0.0	0.0	0.0	0.0	0.0	0.0	0.0
	MBES/SSS Mainscheme	163.07	656.66	658.74	259.14	130.59	93.76	1798.88
	SBES/MBES Crosslines	0.0	11.55	0.0	62.89	0.0	0.0	74.44
	Lidar Crosslines	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Numb Bottor	er of n Samples							8
	er Maritime lary Points igated							0
Numb	er of DPs							0
	er of Items igated by)ps							0
Total S	SNM							54.96

Table 3: Hydrographic Survey Statistics

The following table lists the specific dates of data acquisition for this survey:

Survey Dates	Day of the Year
02/05/2023	36

Survey Dates	Day of the Year
02/06/2023	37
02/07/2023	38
02/08/2023	39
02/09/2023	40
02/10/2023	41
02/11/2023	42
02/12/2023	43
02/13/2023	44
02/14/2023	45
02/15/2023	46
02/16/2023	47
02/17/2023	48
02/18/2023	49
02/19/2023	50
02/20/2023	51
02/21/2023	52
02/22/2023	53
02/23/2023	54
02/25/2023	56
02/26/2023	57
02/27/2023	58
02/28/2023	59
03/01/2023	60
03/02/2023	61
03/03/2023	62
03/04/2023	63
03/05/2023	64
03/06/2023	65
03/07/2023	66
03/30/2023	89
03/31/2023	90
04/01/2023	91

Survey Dates	Day of the Year
04/02/2023	92
04/03/2023	93
04/04/2023	94
04/05/2023	95
04/06/2023	96
04/18/2023	108
04/19/2023	109
04/20/2023	110
05/19/2023	139
05/20/2023	140
05/21/2023	141

Table 4: Dates of Hydrography

B. Data Acquisition and Processing

B.1 Equipment and Vessels

Refer to the Data Acquisition and Processing Report (DAPR) for a complete description of data acquisition and processing systems, survey vessels, quality control procedures and data processing methods. Additional information to supplement sounding and survey data are discussed in the following sections.

B.1.1 Vessels

The following vessels were used for data acquisition during this survey:

Hull ID	R/V Endeavor	R/V Pulse	R/V Spectrum	R/V Taku	R/V Voxel	R/V 505
LOA	13.4 meters	7.3 meters	6.7 meters	9.4 meters	14.0 meters	10.0 meters
Draft	0.8 meters	0.61 meters	0.6 meters	0.8 meters	0.6 meters	0.6 meters

Table 5: Vessels Used

The R/V Endeavor is a 13.4 meter aluminum catamaran built by Armstrong Marine equipped with an overthe-side Pitman Arm Sonar Mount with a secondary tie point, a hydraulic A-frame and davit. The R/V Pulse is a 7.3 aluminum monohull equipped with a Universal Sonar Mount (USM) starboard multibeam pole mount and davit.

The R/V Spectrum is a 6.7 meter aluminum monohull equipped with a Universal Sonar Mount (USM) starboard multibeam pole mount and davit.

The R/V Taku is a 9.4 aluminum catamaran built by Armstrong Marine equipped with a Universal Sonar Mount (USM) stern mutibeam pole mount, hydraulic A-frame and davit.

The R/V Voxel is a 14.0 meter aluminum catamaran built by Armstrong Marine equipped with an electro hydraulic actuated moonpool accessed adjustable aluminum and stainless steel custom mount and hydraulic A-frame.

The R/V 505 is a 10 meter aluminum catamaran equipped with a Universal Sonar Mount (USM) starboard multibeam pole mount and davit.

B.1.2 Equipment

Manufacturer	Model	Туре
R2Sonic	2022	MBES
R2Sonic	2024	MBES
AML Oceanographic	3-RT Velocity Probe	Sound Speed System
AML Oceanographic	MicroX SV	Sound Speed System
AML Oceanographic	AML-3 LGR	Sound Speed System
AML Oceanographic	BaseX2	Sound Speed System
Applanix	POS MV WaveMaster	Positioning and Attitude System
Applanix	POS MV OceanMaster	Positioning and Attitude System
R2Sonic	I2NS	Positioning System
EdgeTech	4125	SSS
EdgeTech	4200	SSS

The following major systems were used for data acquisition during this survey:

Table 6: Major Systems Used

Note: R/V Endeavor utilized a single head R2Sonic 2024 multibeam echosounder system (MBES), an AML 3-RT for the surface sound speed system, an AML-3 LGR for the sound speed system, an R2Sonic I2NS for the positioning and attitude system, and an EdgeTech 4200 MP side scan sonar (SSS).

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R/V Pulse utilized a single head R2Sonic 2022 multibeam echosounder system (MBES), an AML 3-RT for the surface sound speed system, an AML-3 LGR for the sound speed system, an Applanix POSMV WaveMaster for the positioning and attitude system, and an EdgeTech 4125 side scan sonar (SSS).

R/V Spectrum utilized a single head R2Sonic 2024 multibeam echosounder system (MBES), an AML Micro.X for the surface sound speed system, an AML Base.X2 for the sound speed system, an Applanix POSMV WaveMaster for the positioning and attitude system, and an EdgeTech 4125 side scan sonar (SSS).

R/V Taku utilized a single head R2Sonic 2024 mutibeam echosounder system (MBES), an AML 3-RT for the surface sound speed system, an AML Base.X2 for the sound speed system, an Applanix POSMV OceanMaster for the positioning and attitude system, and an EdgeTech 4125 side scan sonar (SSS).

R/V Voxel utilized a single head R2Sonic 2024 multibeam echosounder system (MBES), an AML 3-RT for the surface sound speed system, an AML-3 LGR for the sound speed system, an Applanix POSMV OceanMaster for the positioning and attitude system, and an EdgeTech 4125 side scan sonar (SSS).

R/V 505 utilized a single head R2Sonic 2022 multibeam echosounder system (MBES), an AML Micro.X for the surface sound speed system, an AML Base.X2 for the sound speed system, an Applanix POSMV OceanMaster for the positioning and attitude system, and an EdgeTech 4125 side scan sonar (SSS).

B.2 Quality Control

B.2.1 Crosslines

A beam-to-beam statistical analysis was performed using the Cross Check tool in Qimera. A 1 meter Combined Uncertainty and Bathymetric Estimator (CUBE) weighted dynamic surface was created incorporating only the mainscheme lines and excluded crosslines. The Cross Check tool was used to perform the beam-by-beam comparison of the crossline data to the mainscheme surface. Comparisons showed excellent agreement, well above 95% of the allowable TVU.

The percentage of crossline miles as compared to main scheme miles was 4.12%

Note: This surface was created for QC only and is not submitted as a surface deliverable.

Below is a histogram of the crossline comparison statistics showing IHO Order 1a compliance per beam.

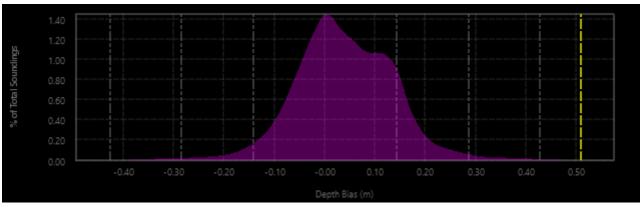


Figure 5: H13765 Crossline Comparison

B.2.2 Uncertainty

The following survey specific parameters were used for this survey:

Method	Measured	Zoning
ERS via ERTDM	0.06 meters	N/A

Table 7: Survey Specific Tide TPU Values.

Hull ID	Measured - CTD	Measured - MVP	Measured - XBT	Surface
R/V Endeavor	0.05 meters/second	N/A	N/A	0.2 meters/second
R/V Pulse	0.05 meters/second	N/A	N/A	0.2 meters/second
R/V Spectrum	0.05 meters/second	N/A	N/A	0.2 meters/second
R/V Taku	0.05 meters/second	N/A	N/A	0.2 meters/second
R/V Voxel	0.05 meters/second	N/A	N/A	0.2 meters/second
R/V 505	0.05 meters/second	N/A	N/A	0.2 meters/second

Table 8: Survey Specific Sound Speed TPU Values.

The standard deviation uncertainty and the total vertical uncertainty (TVU) layers of the Dynamic Surface were utilized during data processing to search for features, water column noise, and systematic errors.

IHO Order 1a uncertainty specification was met by 100% of the nodes.

In Qimera versions beginning in 2.5.1 and beyond, the user has the ability to export the Dynamic Surface to a Bathymetric Attributed Grid (BAG) with TVU represented in the uncertainty layer.

Using this BAG, the percentage of nodes that fell within the TVU specification for each Dynamic Surface was calculated using the NOAA QC tools program. These results are shown in an image below.

Complete Coverage Option B MBES (Finalized 1m CUBE weighted Dynamic Surface in NOAA QC Tools) = 95.5% of nodes are within the allowable TVU.

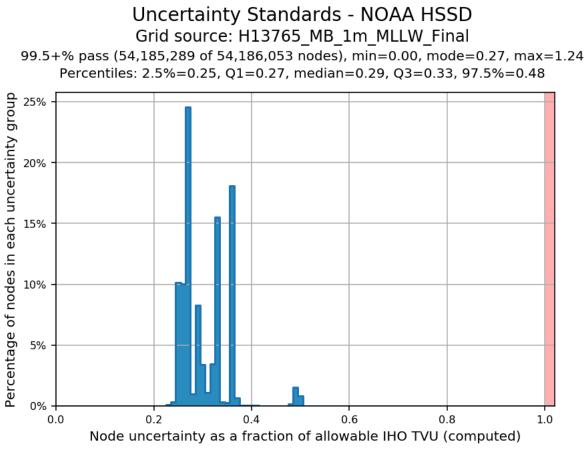


Figure 6: H13765 Finalized 1m MBES TVU Statistics

B.2.3 Junctions

Depth differences between junctioning surveys were evaluated using the JunctionTrac program, developed in-house by eTrac. For each junction, each CUBE weighted dynamic surface's nodes were exported to

an ASCII CSV file where the fields were (Easting, Northing, Depth) for each node. A 1 meter difference surface between the junctioning datasets was also created and exported to an ASCII CSV file where the fields were (Easting, Northing, Diff) for each node. The three ASCII CSV files were then loaded into the JunctionTrac program and junction statistics were computed. A file was also created in this process to locate any nodes from the difference surface that exceed the allowable TVU, which was imported into Qimera and any identified points from JunctionTrac were analyzed. Note: the difference surfaces were created for comparison efforts only and are not submitted as surface deliverables.

The following junctions were made with this survey:

Registry Number	Scale	Year	Field Unit	Relative Location
H13766	1:5000	2023	eTrac	Е
H11693	1:10000	2007	ВН	SE
F00628	1:10000	2012	NRT5	N

Table 9: Junctioning Surveys

<u>H13766</u>

The junction comparison was performed using all overlapping data between H13765 and H13766. Below is a histogram of junction comparison statistics showing the difference between the junctioning surfaces and allowable TVU as well as difference statistics. 100% of nodes were within allowable TVU.

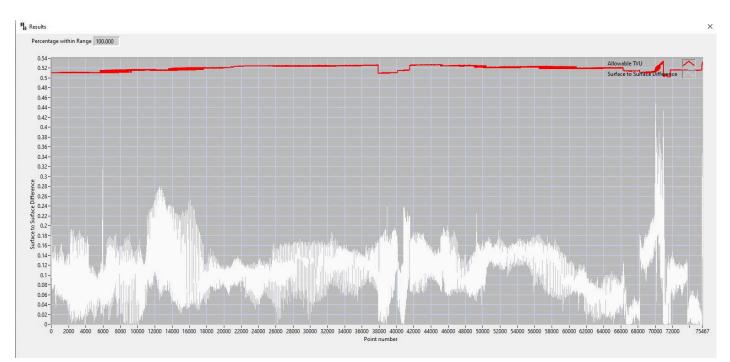


Figure 7: H13765 - H13766 Junction Comparison

Criteria	Number of Nodes	Resulting %
DIFF < 10cm	34562	45.80%
10cm < DIFF < 20cm	39543	52.40%
20cm < DIFF < 30cm	1303	1.73%
30cm < DIFF < 50cm	60	0.08%
DIFF > 50cm	0	0.00%
Total	75468	100.00%

Figure 8: H13765 - H13766 Difference Statistics

<u>H11693</u>

The junction comparison was performed using all overlapping data between H13765 and H11693. Below is a histogram of junction comparison statistics showing the difference between the junctioning surfaces and allowable TVU as well as difference statistics. 92.8883% of nodes were within allowable TVU.

Note: Spikes above the allowable TVU were caused by migrating shoals.

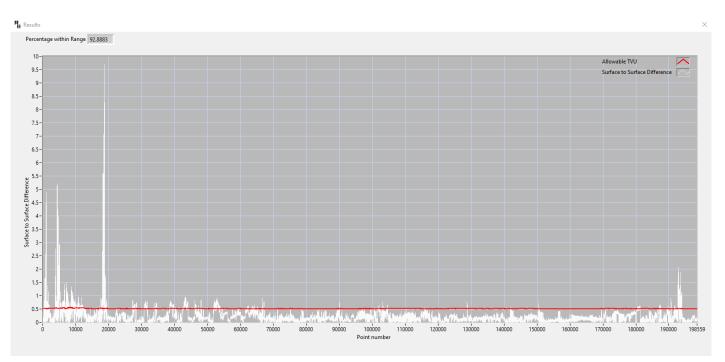


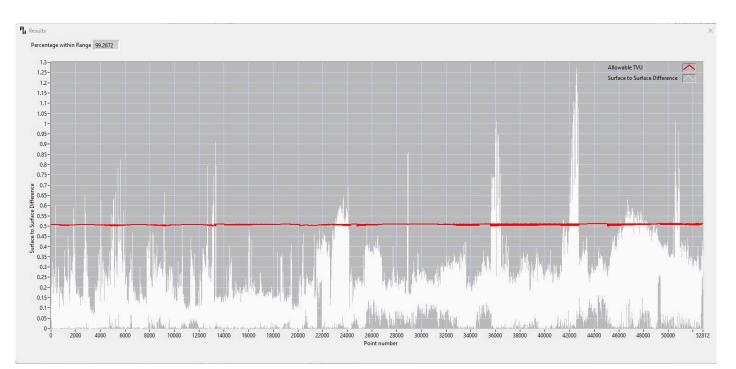
Figure 9: H13765 - H11693 Junction Comparison

Criteria	Number of Nodes	Resulting %
DIFF < 10cm	70483	35.50%
10cm < DIFF < 20cm	57851	29.14%
20cm < DIFF < 30cm	28174	14.19%
30cm < DIFF < 50cm	26720	13.46%
DIFF > 50cm	15332	7.72%
Total	198560	100.00%

Figure 10: H13765 - H17693 Difference Statistics

F00628

The junction comparison was performed using all overlapping data between H13765 and F00628. Below is a histogram of junction comparison statistics showing the difference between the junctioning surfaces and allowable TVU as well as difference statistics. 99.2672% of nodes were within allowable TVU.



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Figure 11: H13765 - F00628 Junction Comparison

Criteria	Number of Nodes	Resulting %
DIFF < 10cm	21933	41.53%
10cm < DIFF < 20cm	18410	34.86%
20cm < DIFF < 30cm	6973	13.20%
30cm < DIFF < 50cm	5055	9.57%
DIFF > 50cm	442	0.84%
Total	52813	100.00%

Figure 12: H13765 - F00628 Difference Statistics

B.2.4 Sonar QC Checks

Sonar system quality control checks were conducted as detailed in the quality control section of the DAPR.

17

B.2.5 Equipment Effectiveness

There were no conditions or deficiencies that affected equipment operational effectiveness.

B.2.6 Factors Affecting Soundings

There were no other factors that affected corrections to soundings.

B.2.7 Sound Speed Methods

Sound Speed Cast Frequency: SVP casts were generally taken every 2 hours. Occasionally casts would exceed a 2 hour frequency, however would never exceed a 4 hour frequency.

On R/V Endeavor, R/V Pulse, R/V Spectrum, R/V Taku, R/V Voxel, and R/V 505 casts were applied in QPS Qinsy acquisition software at the time of the cast. Surface SVP measured at 1Hz was compared to surface speed from the current profile in real-time. If the surface velocity comparison was in excess of 2m/s at any time during survey operations, a new cast was taken.

Surface sound speeds were compared in real-time and profile to profile for each cast on the vessel. Additionally, the processor reviewed profiles in Qimera to remove spurious readings within a cast, compare day-to-day casts, and to check distribution over the surveyed area, in order to better understand trends for efficient acquisition planning.

B.2.8 Coverage Equipment and Methods

All equipment and survey methods were used as detailed in the DAPR.

B.2.9 Data Density Evaluation

In order to determine if the density of the data met the specified 5 soundings per node, data density was evaluated using DensityTrac in the AmiTrac program, developed in-house by eTrac. Each finalized CUBE weighted dynamic surface's nodes were exported to a BBH file. The BBH file was then loaded into the DensityTrac program and density statistics were computed.

For H13765 the following percentages represent the results of the density query:

Complete Coverage MBES (Finalized 1m CUBE weighted Dynamic Surface) = 98.5993% of nodes are composed from at least 5 soundings.

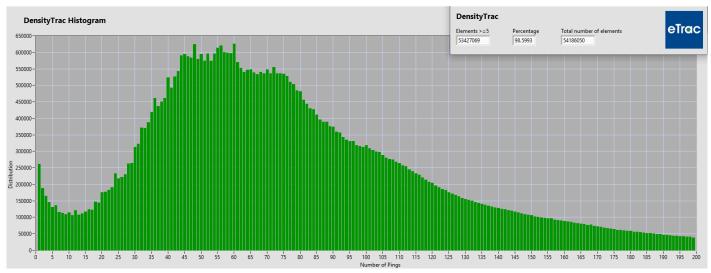


Figure 13: H13765 Finalized 1m Set Line Spacing MBES Density Distribution

B.3 Echo Sounding Corrections

B.3.1 Corrections to Echo Soundings

All data reduction procedures conform to those detailed in the DAPR.

B.3.2 Calibrations

All sounding systems were calibrated as detailed in the DAPR.

B.4 Backscatter

Backscatter data were collected throughout the survey and are retained in the raw DB files. Every effort was made in the field to collect quality backscatter data while maintaining the primary mandate of high quality bathymetric data. eTrac verified coverage and general quality of the backscatter data collected daily. A beam intensity window was monitored in Qinsy during acquisition to ensure backscatter data collection. Raw

backscatter data were viewed in QPS FMGeocoder (FMGT) to further confirm collection criteria had been met. After MBES data was fully processed and cleaned in Qimera, GSF files were exported and brought into FMGT and processed into backscatter mosaics grouped by acoustic frequency and survey system.

B.5 Data Processing

B.5.1 Primary Data Processing Software

The following Feature Object Catalog was used: NOAA Profile Version 2022.

Feature Object Catalog, NOAA Profile Version 2022 was used only in CARIS. Qimera was used as the primary processing software.

B.5.2 Surfaces

The following surfaces and/or BAGs were submitted to the Processing Branch:

Surface Name	Surface Type	Resolution	Depth Range	Surface Parameter	Purpose
H13765_MB_1m_MLLW_Final	BAG	1 meters	0.353 meters - 22.839 meters	NOAA_1m	Complete MBES
H13765_MBAB_2m_EN_400kHz_1of6	MB Backscatter Mosaic	2 meters	-	N/A	Complete MBES
H13765_MBAB_2m_VO_400kHz_20f6	MB Backscatter Mosaic	2 meters	-	N/A	Complete MBES
H13765_MBAB_2m_TA_400kHz_3of6	MB Backscatter Mosaic	2 meters	-	N/A	Complete MBES
H13765_MBAB_2m_FF_400kHz_4of6	MB Backscatter Mosaic	2 meters	-	N/A	Complete MBES
H13765_MBAB_2m_SP_400kHz_5of6	MB Backscatter Mosaic	2 meters	-	N/A	Complete MBES

Surface Name	Surface Type	Resolution	Depth Range	Surface Parameter	Purpose
H13765_MBAB_2m_PU_400kHz_6of6	MB Backscatter Mosaic	2 meters	-	N/A	Complete MBES
H13765_SSSAB_1m_400kHz_1of2	SSS Mosaic	1 meters	-	N/A	100% SSS
H13765_SSSAB_1m_400kHz_2of2	SSS Mosaic	1 meters	-	N/A	200% SSS

Table 10: Submitted Surfaces

A 1m surface is provided meeting complete coverage MBES with backscatter specifications for H13765.

Note: The 1m MBES surface's depth ranges were extended past 20m to include the remaining deeper values beyond

20m to avoid creating superfluous surfaces at a lower resolution.

A 1m mosaic is provided meeting complete coverage with 100% SSS specifications for H13765.

A separate 1m mosaic is also provided meeting specifications for the 200% disproval radii.

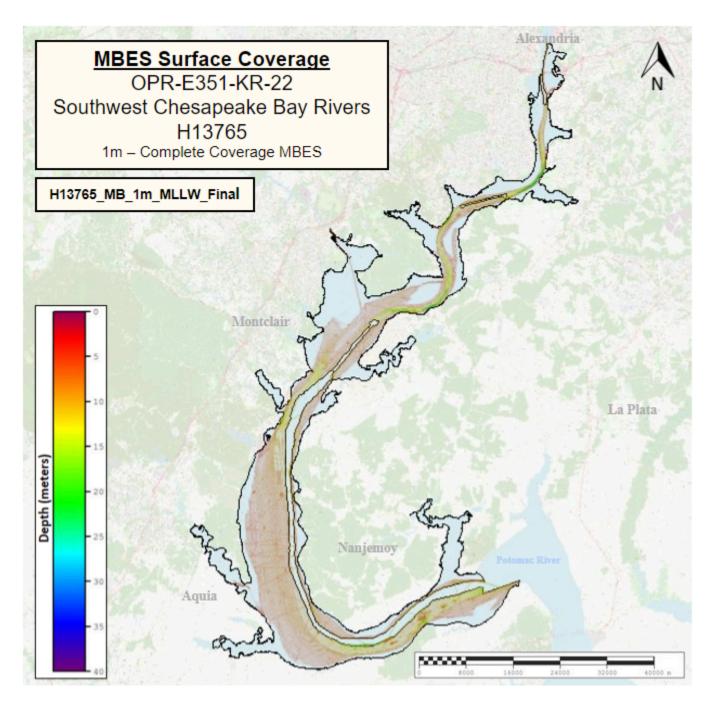


Figure 14: H13765 Finalized 1m CUBE Weighted Dynamic Surface Coverage

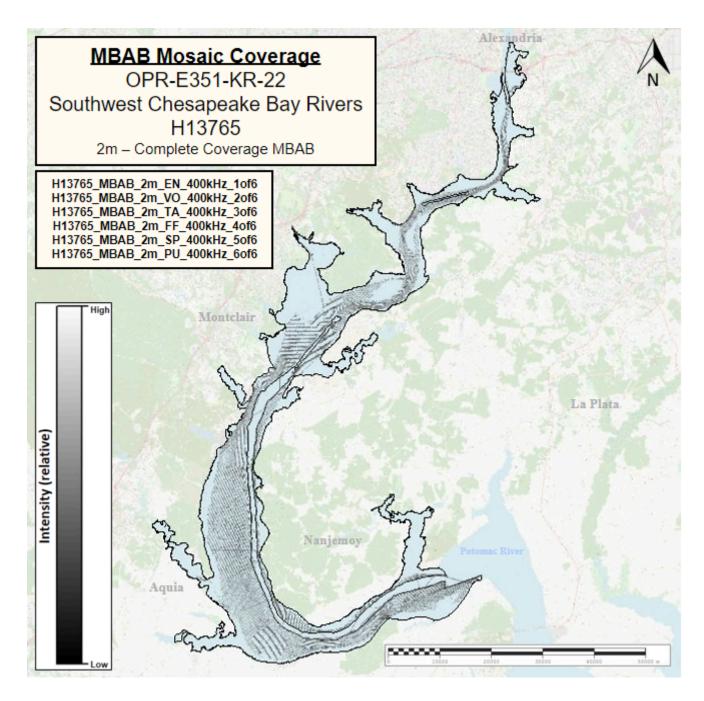


Figure 15: H13765 Finalized 2m MBAB mosaics

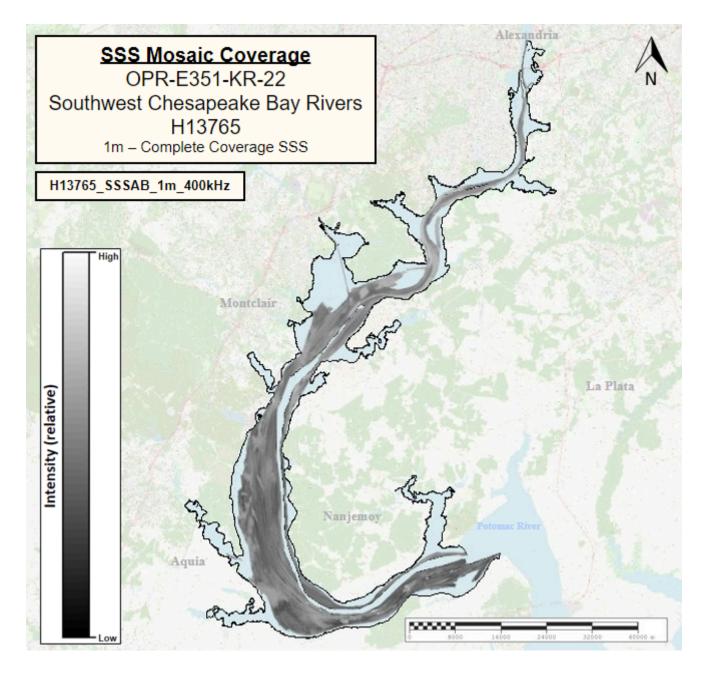


Figure 16: H13765 Finalized 1m SSS mosaic

B.5.3 Additional Task: Final Data Submission - Grids

An additional assigned task for this sheet was to include interpolated grids in Mean Lower Low Water (MLLW) and North American Vertical Datum of 1988 (NAVD88) datum.

C. Vertical and Horizontal Control

Additional information discussing the vertical or horizontal control for this survey can be found in the accompanying HVCR and DAPR.

C.1 Vertical Control

The vertical datum for this project is Mean Lower Low Water.

ERS Datum Transformation

The following ellipsoid-to-chart vertical datum transformation was used:

Method	Ellipsoid to Chart Datum Separation File
ERS via ERTDM	OPR-E351-KR-22_NAD83-MLLW.qgfvom

Table 11: ERS method and SEP file

In order to reference soundings to Mean Lower Low Water Datum, a separation model was provided by NOAA and was applied to the Qinsy DB files via a .qgfvom separation file in the acquisition software.

C.2 Horizontal Control

The horizontal datum for this project is North American Datum 1983 (2011).

The projection used for this project is Universal Transverse Mercator (UTM) Zone 18.

The following PPK methods were used for horizontal control:

• RTX

Applanix PosPac MMS was utilized to post process real time positioning data utilizing Trimble's PP-RTX implementation of Trimble CenterPoint RTX to create a Smoothed Best Estimate of Trajectory (SBET).

<u>RTK</u>

GNSS satellite corrections were received on each vessel using either the G2+ or G4+ carrier signal from the Marinestar Global Correction System maintained by Fugro.

C.3 Additional Horizontal or Vertical Control Issues

C.3.1 Additional Task: Final Data Submission- Grids

An additional assigned task for this sheet was to include interpolated grids in North American Vertical Datum of 1988 (NAVD88) datum. In order to reference soundings to NAVD88 Datum, a separation model was provided by NOAA and was applied to the gridded MLLW data in QGIS.

D. Results and Recommendations

D.1 Chart Comparison

A chart comparison was conducted for H13765 using Pydro CA tools, Qimera, and Caris HIPS and SIPS. Survey data were compared against the largest scale ENC to accomplish the chart comparison. The largest scale ENC does not cover the entire survey boundary so two other charts were used to complete the chart comparison. Details of the ENCs used are listed below.

US5MD44M, scale: 40000, edition: 21, update application date: 09/13/2021, issue date: 04/12/2022

US5MD43M, scale: 40000, edition: 16, update application date: 10/12/2021, issue date: 05/27/2022

Throughout survey operations sounding comparisons between the charted depths and the surveyed depths were analyzed to identify depth discrepancies. Using 1 meter CUBE weighted Dynamic surfaces, soundings were generated in the "Sounding Selection" tab of Pydro CA tools. Soundings were displayed against the charted soundings and a visual comparison was made in Caris HIPS and SIPS. Additionally, potential DtoNs and discrepancies were generated using the "DTM vs Chart" tab of Pydro CA tools. The results were displayed through CA tools and investigated in CARIS HIPS and SIPS and Qimera.

An overview image of the generated soundings on each chart is included below.

Results of the chart comparison are included in the following sections.

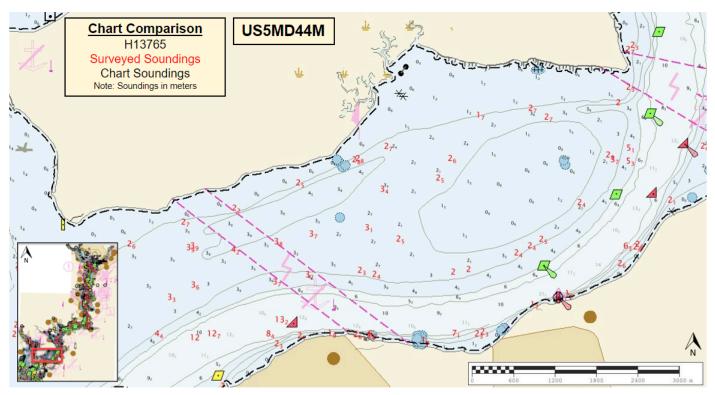


Figure 17: Generated Soundings used for Chart Comparison (US5MD44M)

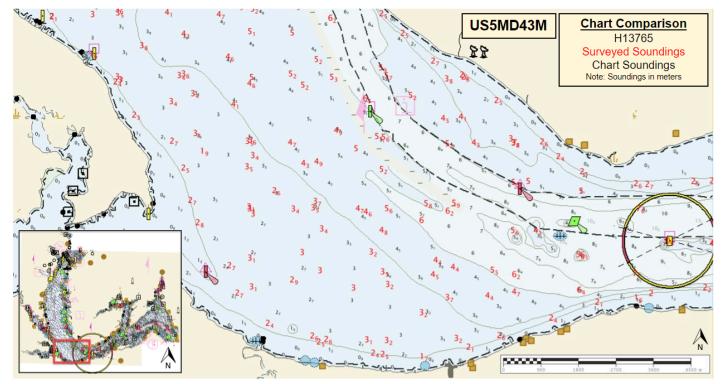


Figure 18: Generated Soundings used for Chart Comparison (US5MD43M)

D.1.1 Electronic Navigational Charts

The following are the largest scale ENCs, which cover the survey area:

ENC	Scale	Edition	Update Application Date	Issue Date
US5MD44M	1:40000	21	09/13/2021	04/12/2022
US5MD43M	1:40000	16	10/12/2021	05/27/2022

Table 12: Largest Scale ENCs

D.1.2 Shoal and Hazardous Features

There were 18 DtoNs found in H13765, and added to the Final Feature File (FFF). Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXXX). Refer to the FFF for determinations and recommendations of each feature. The DtoNs were submitted in the following Danger to navigation reports:

H13765_DtoN_01-07 H13765_DtoN_08-11 H13765_DtoN_12-14 H13765_Non_Dangerous_Pipeline

D.1.3 Charted Features

There were 672 charted features assigned to H13765 that are included in the Final Feature File (FFF). Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXXX). Refer to the FFF for determinations and recommendations of each feature.

D.1.4 Uncharted Features

127 new features were found in H13765. Each feature in the FFF has been given a unique identifier in the ""userid"" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature.

Note: DtoNs are not included in the number of new features in this section. DtoNs can be found separately in section D.1.2.

eTrac

D.1.5 Channels

No channels exist for this survey. There are no designated anchorages, precautionary areas, safety fairways, traffic separation schemes, pilot boarding areas, or channel and range lines within the survey limits.

D.2 Additional Results

D.2.1 Aids to Navigation

Throughout H13765 there were temporary aids for fishing gear. These aids were not included in the FFF due to their temporary nature. No AtoNs were reported to the U.S. Coast Gaurd.

A charted private aid to navigation (ATON) at 38-30-14.952N/077-17-51.543W was disproved by the field unit and included in the H13765 FFF. The ATON was reported to the NOAA Marine Chart Division via the OCS ASSIST application on 12/6/2023.

D.2.2 Maritime Boundary Points

No Maritime Boundary Points were assigned for this survey.

D.2.3 Bottom Samples

8 bottom samples were obtained in accordance with section 7.1 of the HSSD 2022 in areas designated by the field through discussions with our COR. Detailed information and images of the bottom samples are located in the Final Feature File (FFF). Each bottom sample has been given a unique identifier in the "userid" field of the .000 S-57 file (format AX).

D.2.4 Overhead Features

There were 26 overhead features assigned to H13765. Assigned overhead features were visually confirmed and no discrepancies were found. The overhead features were not included in the FFF following investigation requirements.

D.2.5 Submarine Features

There were 9 submarine features assigned to H13765 that are included in the Final Feature File (FFF). Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature.

D.2.6 Platforms

There were 20 offshore platforms assigned to H13765 that are included in the Final Feature File (FFF). Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature.

D.2.7 Ferry Routes and Terminals

No ferry routes or terminals exist for this survey.

D.2.8 Abnormal Seafloor or Environmental Conditions

No abnormal seafloor or environmental conditions exist for this survey.

D.2.9 Construction and Dredging

There were 143 shoreline construction features assigned to H13765 that are included in the Final Feature File (FFF). Each feature in the FFF has been given a unique identifier in the "userid" field of the .000 S-57 file (format 1XXXX). Refer to the FFF for determinations and recommendations of each feature.

2 dredge areas were assigned to H13765. One of the dredge areas was not fully addressed due to it being outside of the survey boundary, no discrepancies were found within our survey extents. The other dredge area was not dressed due to it being outside of the NALL. The dredge areas were not included in the FFF following investigation requirements.

D.2.10 New Survey Recommendations

No new surveys or further investigations are recommended for this area.

D.2.11 ENC Scale Recommendations

No new ENC scales are recommended for this area.

E. Approval Sheet

As Chief of Party, field operations for this hydrographic survey were conducted under my direct supervision, with frequent personal checks of progress and adequacy. I have reviewed the attached survey data and reports.

All CUBE surfaces, this Descriptive Report, and all accompanying records and data are approved. All records are forwarded for final review and processing to the Processing Branch.

The survey data meets or exceeds requirements as set forth in the NOS Hydrographic Surveys and Specifications Deliverables Manual, Field Procedures Manual, Letter Instructions, and all HSD Technical Directives. These data are adequate to supersede charted data in their common areas. This survey is complete and no additional work is required with the exception of deficiencies noted in the Descriptive Report.

Approver Name	Approver Title	Approval Date	Signature
David Neff	Chief of Party	10/18/2023	David Neff Div. C+US, David Neff Div. C+US, Over Trac Inc., CN=David Neff Date; 2023, 10.18 13:55:00-07'00'

F. Table of Acronyms

Acronym	Definition	
AHB	Atlantic Hydrographic Branch	
AST	Assistant Survey Technician	
ATON	Aid to Navigation	
AWOIS	Automated Wreck and Obstruction Information System	
BAG	Bathymetric Attributed Grid	
BASE	Bathymetry Associated with Statistical Error	
СО	Commanding Officer	
CO-OPS	Center for Operational Products and Services	
CORS	Continuously Operating Reference Station	
CTD	Conductivity Temperature Depth	
CEF	Chart Evaluation File	
CSF	Composite Source File	
CST	Chief Survey Technician	
CUBE	Combined Uncertainty and Bathymetry Estimator	
DAPR	Data Acquisition and Processing Report	
DGPS	Differential Global Positioning System	
DP	Detached Position	
DR	Descriptive Report	
DTON	Danger to Navigation	
ENC	Electronic Navigational Chart	
ERS	Ellipsoidal Referenced Survey	
ERTDM	Ellipsoidally Referenced Tidal Datum Model	
ERZT	Ellipsoidally Referenced Zoned Tides	
FFF	Final Feature File	
FOO	Field Operations Officer	
FPM	Field Procedures Manual	
GAMS	GPS Azimuth Measurement Subsystem	
GC	Geographic Cell	
GPS	Global Positioning System	
HIPS	Hydrographic Information Processing System	
HSD	Hydrographic Surveys Division	

Acronym	Definition	
HSSD	Hydrographic Survey Specifications and Deliverables	
HSTB	Hydrographic Systems Technology Branch	
HSX	Hypack Hysweep File Format	
HTD	Hydrographic Surveys Technical Directive	
HVCR	Horizontal and Vertical Control Report	
HVF	HIPS Vessel File	
ІНО	International Hydrographic Organization	
IMU	Inertial Motion Unit	
ITRF	International Terrestrial Reference Frame	
LNM	Linear Nautical Miles	
MBAB	Multibeam Echosounder Acoustic Backscatter	
MCD	Marine Chart Division	
MHW	Mean High Water	
MLLW	Mean Lower Low Water	
NAD 83	North American Datum of 1983	
NALL	Navigable Area Limit Line	
NTM	Notice to Mariners	
NMEA	National Marine Electronics Association	
NOAA	National Oceanic and Atmospheric Administration	
NOS	National Ocean Service	
NRT	Navigation Response Team	
NSD	Navigation Services Division	
OCS	Office of Coast Survey	
OMAO	Office of Marine and Aviation Operations (NOAA)	
OPS	Operations Branch	
MBES	Multibeam Echosounder	
NWLON	National Water Level Observation Network	
PDBS	Phase Differencing Bathymetric Sonar	
РНВ	Pacific Hydrographic Branch	
POS/MV	Position and Orientation System for Marine Vessels	
РРК	Post Processed Kinematic	
PPP	Precise Point Positioning	
PPS	Pulse per second	

Acronym	Definition	
PRF	Project Reference File	
PS	Physical Scientist	
RNC	Raster Navigational Chart	
RTK	Real Time Kinematic	
RTX	Real Time Extended	
SBES	Singlebeam Echosounder	
SBET	Smooth Best Estimate and Trajectory	
SNM	Square Nautical Miles	
SSS	Side Scan Sonar	
SSSAB	Side Scan Sonar Acoustic Backscatter	
ST	Survey Technician	
SVP	Sound Velocity Profiler	
TCARI	Tidal Constituent And Residual Interpolation	
TPU	Total Propagated Uncertainty	
USACE	United States Army Corps of Engineers	
USCG	United States Coast Guard	
UTM	Universal Transverse Mercator	
XO	Executive Officer	
ZDF	Zone Definition File	