

G. Vertical and Horizontal Control

The vertical datum for this project is Mean Lower Low Water. The vertical control method used was VDatum.

Per section 5.1.2.3 of the Field Procedures Manual (2014 ed), no Horizontal and Vertical Control Report has been generated for W00478.

The horizontal datum for this project is North American Datum of 1983 (NAD 83). The projection used for this project is Universal Transverse Mercator (UTM) Zone 10.

Vessel kinematic data were post-processed using Applanix POSPac processing software and RTX positioning methods described in the DAPR. Smoothed Best Estimate of Trajectory (SBET) and associated error (RMS) were applied to all MBES data in CARIS HIPS and SIPS.

The Wide Area Augmentation System (WAAS) was used for real-time horizontal control during data acquisition.