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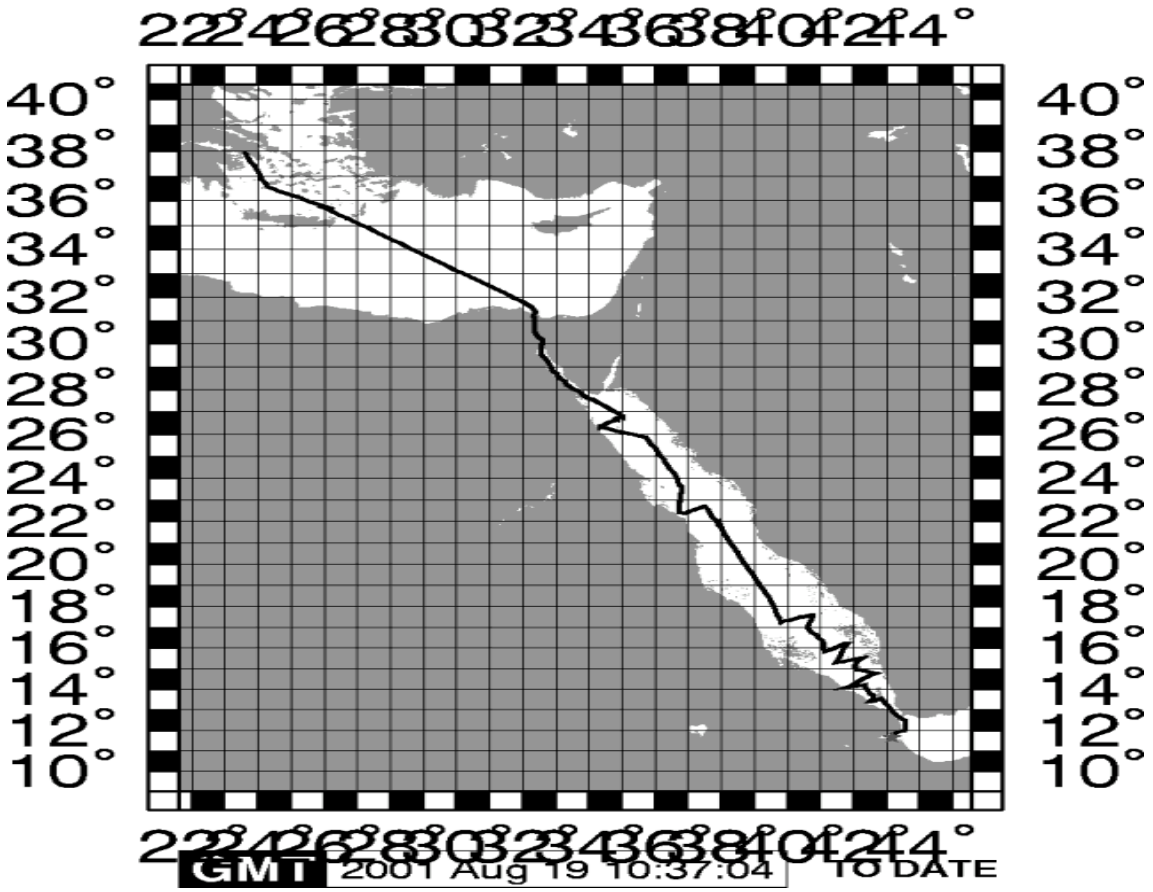
R/V Maurice Ewing Data Reduction Summary

EW−0109 Piraeus, Greece − Djibouti

Date	Julian Date	Time	Port
August 4, 2001	216	09:00:00	Piraeus, Greece
August 19, 2001	231	09:54:00	Djibouti

EW 0109



Project Summary

DESCRIPTION

Background and Scientific Objectives

Physical Oceanography, including ADCP and CTD sampling of the Red Sea.

Cruise Members

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Cruise Notes

All data in this report is logged using GMT time and Julian days in order to avoid confusion with local time changes.

Hydrosweep

Hydrosweep was a little tricky to get started after leaving Piraeus, but should be relatively normal after about day 217.

Gravity

No Special notes.

ADCP

Chris repaired the shipboard ACDP unit and started taking data on day 219.

CTD

The CTD was plagued with problems for a large piece of the cruise. First, the slip ring had to be replaced. Then there were issues with the cable which took some time to be resolved. The cable had to be reterminated at least twice, and the joysticks failed. The 12kHz pinger seemed to be interfering with the bottle firing, so that was turned off. Station 26 (waypiont 23?) was the beginning of the good CTD data.

Data Logging

The R/V Maurice Ewing data logging system is run on a Sparc Ultra Enterprise Server. Attached are 48 serial ports via 3 16−port Digi International SCSI Terminal Servers. Generally, all data logged by the Ewing Data Acquisition System (DAS) is time stamped with the CPU time of the server, and broadcast to the Ewing network using UDP packet broadcasts. The CPU time of the server is synchronized once every half hour to a Datum UTC gps time clock.

GPS times are also time−tagged with cpu time, although the time of the GPS position is from the GPS fix itself.

The following tables describe the data instruments which performed logging during this cruise. The tables associated with the instruments describe logging periods and data losses for that instrument.

Time Reference

Datum StarTime 9390−1000

logging interval: 30 minutes
file id: tr2

Used as the CPU synchronization clock. This clock is polled once every half hour to synchronize the CPU clock of the data logger to UTC time. The logger (octopus) is responsible for updating the times of the other CPUs.

The logging process for the datum clock died early in the cruise and was not restarted until day 223.

Interruption s greater than 30 minutes are displayed in the following table

Log Date	LogDate	Comment
2001+216:00:02:29		Logging officially started
2001+216:07:02:29	2001+223:12:03:30	Logging process dead
2001+230:23:52:29.728		Logging officially ends

GPS Receivers

GPS data is usually logged at 10 second intervals. The NMEA strings GPGGA and GPVTG are logged for position, speed, and heading fixes. This data was logged constantly throughout the cruise.

The Tasmon GPS was the primary GPS for this cruise.

Trimble Tasmon P/Y Code Receiver

logging interval: 10 seconds
file id: gp1

The Tasmon is the primary GPS receiver for the Ewing Logging system and the primary GPS for Spectra fixes. The accuracy is around 15 meters. There were no interruptions during this cruise.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2001+216:00:00:03.966		Logging officially started
2001+230:23:59:58.617		Logging officially ends

Trimble NT200D

logging interval: 10 seconds
file id: gp2

The Trimble is the secondary receiver for GPS data. Data is logged at 10 second intervals and is also used as an input to Spectra, although it is weighed at a lower value than the Tasmon receiver.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2001+216:00:00:01.899		Logging officially started
2001+216:06:54:30.019	2001+216:07:05:07.603	
2001+216:07:06:49.630	2001+216:09:27:01.254	
2001+230:23:59:57.981		Logging Ends

Speed and Heading

Furuno CI−30 Dual Axis Speed Log
Sperry MK−27 Gyro

logging interval: 6 seconds
file id: fu

The Furuno and Gyro are combined to output speed, heading and course information to a raw Furuno file, as well as an NMEA VDVHW signal used as an input to various systems including steering and Spectra.

Interruptions greater than 30 minutes are displayed in the following table

Log Date	Log Date	Comment
2001+216:00:00:02.546		Official start date
2001+230:23:59:59.637		Official end date

Gravity

Bell Aerospace BGM−3 Marine Gravity Meter System

logging interval: 1 second
file id: vc. (raw), vt. (processed)
drift per day: 0.035

The BGM consists of a forced feedback accelerometer mounted on a gyro stabilized platform. The gravity meter outputs raw counts approximately once per second which are logged and processed to provide real−time gravity displays during the course of the cruise as well as adjusted gravity data at the end of the cruise.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	Log Date	Comment
2001+216:00:00:00.826		Official start date
2001+230:23:59:59.177		Official end time

Bathymetry

Krupp Atlas Hydrosweep−DS2

logging interval: variable based on water depth
file id: hb (centerbeam), hs (swath)

The hydrosweep full swath data is continuously logged for every cruise, and centerbeam data is extracted and processed separately. The centerbeam operates at a logging frequency dependent on the water depth.

The full swath data is not routinely processed, but can be processed with the MB−System software which can be downloaded for free. For instructions, use the website: http://www.ldeo.columbia.edu/MB−System.

MBSystem, version 5.0b3 is necessary to process data after June 1, 2000.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2001+216:10:37:03.000		Official start logging
2001+216:17:54:40	2001+216:19:05:00	
2001+230:23:59:58.000		Official end logging

Weather Station

RM Young Precision Meteorological Instruments, 26700 series

logging interval: 1 minute
file id: wx

The weather station is used to log wind speed, direction, air temperature, and barometric pressure. We log this information at 1−minute intervals. On Julian day 228 we discovered that the temperature offset was wrong for the weather pack, and Chris set it to 31 degrees farenheit. Temperatures before 11:00 on 228 should add 17.22 Celcius degrees.

Log Date	LogDate	Comment
2001+216:06:57:54.146		Official start logging
2001+230:23:59:00.816		Official end logging

Magnetics

Varian Magnetometer

logging interval: 12 seconds
file id: mg

The following table shows the times the magnetometer was logging

Start Log Date	End LogDate	Comment

Gravity Ties

LOCATION 1

EW0108 Piraeus, Greece

Pier/Ship	Latitude	Longitude
	37 56.297N	23 38.160E

At the east corner of the pier in front of the Piraeus Port Authority building

Reference	Latitude	Longitude
	37 56.46N	23 38.40E

At the Lat/Lon reported by Andrew's handheld GPS, near the customs gate exit

	Id	Julian	Date	Mistie	Drift/Day	Prev Mistie
Pre Cruise	EW0104	104	04/14/2001	8.99	0.08	8.25
Post Cruise	EW0108	213	08/01/2001	22.69	0.126	8.99
Total Days			109.00	13.70		

Time	Entry	Value	
09:25	CDeck Level BELOW Pier	0.00	
10:13	Pier 1 L&R Value	3636.55	L&R
10:45	Reference L&R Value	3637.11	L&R
11:08	Pier 2 L&R Value	3636.55	L&R
	Reference Gravity	980048.20	mGals
	Gravity Meter Value (BGM Reading)	980072.00	mGals
	Potsdam Corrected	0	1 if corrected

*Gravity meter is **5.5** meters below CDeck*

Difference in meters between Gravity Meter and Pier: **5.50** meters

Height Cor = Pier Height* FAA Constant

Pier Height*	FAA Constant				
5.50	0.31			1.71	mGals/min

Difference in mGals between Pier and Gravity Meter

Pier (avg) −	Reference	*1.06 L&R/mGal		Delta L&R	
3636.55	3637.11	1.06		−0.60	mGals

Gravity in mGals at Pierside

Reference + Delta mGals [+ Potsdam]				Pier Gravity	
980048.20	−0.60	0.00		980047.60	mgals

Gravity in mGals at Meter

Pier Gravity+	Height Correction			Gravity@meter	
980047.60	1.71			980049.31	mGals

Current Mistie

BGM Reading	Calculated Gravity			Current Mistie	
980072.00	980049.31			22.69	mGals

For all formats, a – in the time field means an invalid value for some reason.

Streamer Compass/Bird Data cb.r

This data is not processed, but can still be found in the "processed" data directory.

```
Shot Time               Line     Shot     Latitude      Longitude

2000+079:00:08:40.085  strike1 000296  N 15 49.6217 W 060 19.8019

2nd GPS Position                      Tailbuoy Position
Latitude     Longitude                Latitude     Longitude

N 15 49.6189 W 060 19.8101    N 15 47.1234 W 060 20.1901

Furuno  Streamer
Gyro    Compasses & Heading

344.1       C01 2.3 C02 1.7  ...
```

Gun Depths dg

Gun depths in tenths of meters. There will always be 20 gundepths even if only one gun was configured and shooting.

```
                        Gun Depths
Shot Time               1   2   3  4    5   6   7   8   9  ...  20

2001+089:06:47:05.909 189 068 005 005 096 005 060 054 005 ... 6
```

Raw Furuno Log fu.s

This data has been smoothed and output 1 fix per minute.

```
CPU Time Stamp         Track Speed Hdg   Gyro

2000+166:00:01:53.091 –     4.4   140.5 148.3
```

Hydrosweep Centerbeam hb.n

Hydrosweep data merged with navigation

```
                              Centerbeam
CPU Time Stamp       Latitude Longitude          Depth

2000+074:09:55:00.000  N 13 6.6206    W 59 39.3908   134.9
```

Merged Data m

```
                                                        GPS
CPU Time Stamp         Latitude     Longitude          Used  Set  Drift Depth

2000+200:12:25:00.000  N 45 54.1583 W 42 47.1770       gp1   0.0  0.0

Magnetic                        Gravity
Total Intensity   Anomaly     FAA  GRV       EOTVOS   Drift   Shift

49464.7           55.5        22.2 980735.0   –8.4     –0.1     2.8

Temperature Salinity Conductivity

0.0         0.0      0.0
```

The gravity drift and shift are values that have been added to the raw gravity to make up for drift in the meter that has been lost in accordance with a gravity check at each port stop.

Temperature,Salinity and Conductivity will only be valid while logging a Thermosalinograph, which is not usually the case.

Magnetics Data mg.n

- A minus sign in the time stamp is flagged as a spike point, probably noise...
- Anomaly is based on the International Geomagnetic Reference Field revision 2000

```
CPU Time Stamp        Latitude     Longitude      Raw Value Anomaly
200+077:00:23:00.000 N 16 11.2918 W  59 47.8258 36752.2   -166.8
```

Navigation File n

```
CPU Time Stamp         Latitude     Longitude       Used  Set  Drift
2000+074:00:03:00.000 N 13 6.2214  W  59 37.9399   gp1   0.0   0.0
```

Navigation Block nb0

Navigation is a compendium of Ewing logged data at shot time. The shot position here is the shot position from the Spectra system.

```
Shot Time               Shot # CPU Time               Shot Position
2001+088:00:00:00.606 016967 2001+088:00:00:03.031 N 30 11.8324 W 042 10.8162

Water  Sea    Wind   -------------Tailbuoy------------------ Line
Depth  Temp Spd  Dir Latitude     Longitude     Range Bearg Name   Speed Heading
2565.1 20.7 16.4 164 N 30 12.0427 W 042 14.7319 6296.3 93.5 MEG-10 4.2   101.1
```

Tailbuoy Navigation tb1.c

Raw tailbuoy fixes

```
CPU Time Stamp         Latitude     Longitude       GPS Precision
2001+088:00:00:02.000 N 30 12.0424 W 042 14.7309   SA
```

GPS Precision is either SA, DIFF or PCODE

Ewing Processed Shot Times ts.n

Shot times and positions based on the Ewing navigation data processing

```
CPU Time Stamp         Shot # Latitude     Longitude     Line Name
2000+079:00:08:01.507 000295 N 15 49.5703 W 060 19.7843 strike1
```

Shot Data Status ts.n.status

The ts.nxxx.status file describes the line information for that day, giving some basic statistics about the line: start, end times; missing shots; start and end shots.

```
LINE   strike1: 98+079:00:00:15.568 : 000283 .. 002286
        MISSING: 347, 410, 1727
LINE   dip2: 98+079:23:05:22.899 : 000002 .. 000151
```

This example says that on Julian Day 079 of 1998, two lines (strike1 and dip2) were run: the end of strike 1 (shots 000283 to 002286) and the start of dip2 (shots 000002 to 000151).

Line strike1 had some missing shots in the data file (probably missing on the SEG-d header as well).

Spectra Shot Times — nb2.r

The shot times and positions based on the Spectra positioning; with raw tailbuoy range and bearing.

```
CPU Time Stamp          Shot # Latitude      Longitude      Line Name
2001+084:00:00:05.924 009245 N 23 31.2410 W 045 25.0894

                                Tailbuoy
Latitude      Longitude      Range  Bearing  Line Name
N 23 30.4540 W 045 21.4338 6389.8 283.2    KANE-4
```

Raw Gravity Counts — vc.r

sample BGM-3 gravity count record (without time tag):

```
pp:dddddd ss
|    |    |___________ status: 00 = No DNV error; 01 = Platform DNV
|    |                         02 = Sensor DNV;   03 = Both DNV's
|    |________________ count typically 025000 or 250000
|_____________________ counting interval, 01 or 10
                       The input of data can be at 1 or 10 seconds.
```

Gravity Data — vt.n

* A minus sign in the time stamp is flagged as a spike point
* m_grv3 calculates the Eotvos correction as:
  eotvos_corr = 7.5038 * vel_east * cos(lat) + .004154 * vel*vel
* The theoretical gravity value is based upon different models for the earth's shape.
  - 1930 = 1930 International Gravity Formula
  - 1967 = 1967 Geodetic Reference System Formula
  - 1980 = 1980 Gravity Formula
* The FAA is computed as:
  faa = corrected_grv – theoretical_grv
* Velocity smoothing is performed w/ a 5 point window

```
CPU Time Stamp          Latitude      Longitude      Model FAA      RAW
2000+148:00:10:00.000 N 09 34.7255 W 085 38.5826 1980  9.48    978264.16

Eotvos  Drift DC      Raw  Velocity     Smooth Velocity
Smooth  Total Shift   North     East     North    East
-74.78  0.06  4.16    1.875 -10.373     1.927 \10.166
```

Datum Time — ts2.r

```
CPU Time                Datum Time        Time Reference
2001+069:00:15:29.727 069 00 15 29.378 datum
```

Raw GPS — gp(12).d, tb1.d

Raw GPS is in NMEA Format.

Meteorological Data — wx

```
                          True
CPU Time Stamp          Spd Dir

2001+045:00:00:00.967   7.8  22

Bird1:                                          Bird 2
Speed                   Direction               Speed                   Direction
Inst  60sA   60mA  60sM  Inst 60sA 60mA         Inst  60sA  60mA  60sM   Inst 60sA 60mA

7.8   6.6    8.5   16.8  277  291  5            0.0   0.0   0.0   0.0    0    0    0

Temperature                     Humidity
Inst  60mA  60mm  60mM         Inst 60mm 60mM          Barometer

15.0  14.2  14.3  15.1         92   90   93            1027.5

Inst:       Current

60sA:       60 second average

60mA:       60 minute average

60sM:       60 second maximum

60mm:       60 minute minimum

60mM:       60 minute maximum
```

Shot Times from Spectra P1 Files — shots.p1

These files were created with the script: *extract_shots_from_p1* ***-a 1***

```
Epoch Time     Shot#  Source Lat/Lon         TB Lat      TB Lon
985788741.000 015570 30.283881 -41.854536  30.320144  -41.886642
Vessel Ref Lat/Lon    Antenna GPS Lat/Lon      Water Depth
30.283478 -41.854117 30.283531  -41.854078  2894.2
```

- Source is the Center of the Guns
- TB is the Tailbuoy, according to Spectra
- Vessel Ref is the location of the center of the Mast
- Antenna GPS is the location of Antenna 1 (-a 1 flag); in this case is the Tasmon GPS
- Water Depth is the HS Centerbeam depth

Shot Times from Spectra P2 Files — shots.p2

These files were created with the script: *extract_shots_from_p2 -o "V1 G1"*

```
Epoch Time  Shot#     Vessel Ref Lat/Lon   Source Lat/Lon
985716772.4 00015572 30.282803 -41.866136 30.283207 \41.866540
```

- Vessel Ref is the location of the center of the Mast
- Source is the Center of the Guns

Scripts

Included are some scripts for extracting information out of the P1 and P2 formatted files. In order to use these scripts you will also need to install the Ewing Perl libraries included in the scripts directory, or at least include that directory in your PERL5LIB environment. The use of perl is beyond the scope of this document.

extract_shots_from_p1 [−a antenna] [−h] filename

Given an input P1 File, create a shotpoint file with the times, and the positions of the given antenna [1 = tasmon, 2 = Trimble] and optionally the header records at the beginning of the file.

The output will be:

```
epochtime shotnumber sourcePos tbPos vesselPos antennaPos depth
```

- **epochtime** is the # of seconds since Jan 1, 1970
- **shotnumber** is the shot number
- **sourcePos** is the center position of the sound source [lat lon]
- **tbPos** is the position of the tailbuoy [lat lon]
- **vesselPos** is the position of the vessel reference (center of mast) [lat lon]
- **antennaPos** is the position of the specified antenna [lat lon]
  1 = tasmon, 2 = trimble
- **depth** is the water depth in meters

extract_shots_from_p2 [−s shotnumber] [−o "output values"]

−s define if you only want the statistics for a single shot

−o "*outputs*" defines the outputs you want from the P2 file.

This routine will output by default the shotpoint, the line name and the shot time. Optionally, you can output position (Lat Lon) info for a number of items:

Outputs can be one or more of the following:

- V1 Vessel 1 Reference
- V1G1 Tasmon GPS Receiver
- V1G2 Trimble GPS Receiver
- V1E1 Hydrosweep Transducer
- TB1 Tailbuoy 1
- S1 Streamer 1
- V1SC Streamer Compasses
- G1 Gun Array 1

All the formats output a Lat Lon pair in decimal degrees. (*West and South being negative*)

Output will be: `epochtime shotnumber [output lat/lon pairs]`

Tape Contents

EW#####/

EW####.pdf	this document
ew####.cdf	NetCDF database file of this cruise
ew####.cdf_nav	NetCDF database file of this cruise' navigation
docs/	File Formats, Spectra manuals
processed/	Processed datafiles merged with navigation
shotlogs/	processed Shot Files
trackplots/	daily cruise track plots (*postscript*)
raw/	Raw data directly from logger
reduction/	Reduced data files
clean/	daily processing directory, includes daily postscript plots of the data.
fixes/	fixes for the RTNu HS loss of d088
scripts/	Perl scripts and their friends
spectra/	P1/90 and P2/94 files from MCS lines
streamer/	Excel spreadsheets of streamer configuration