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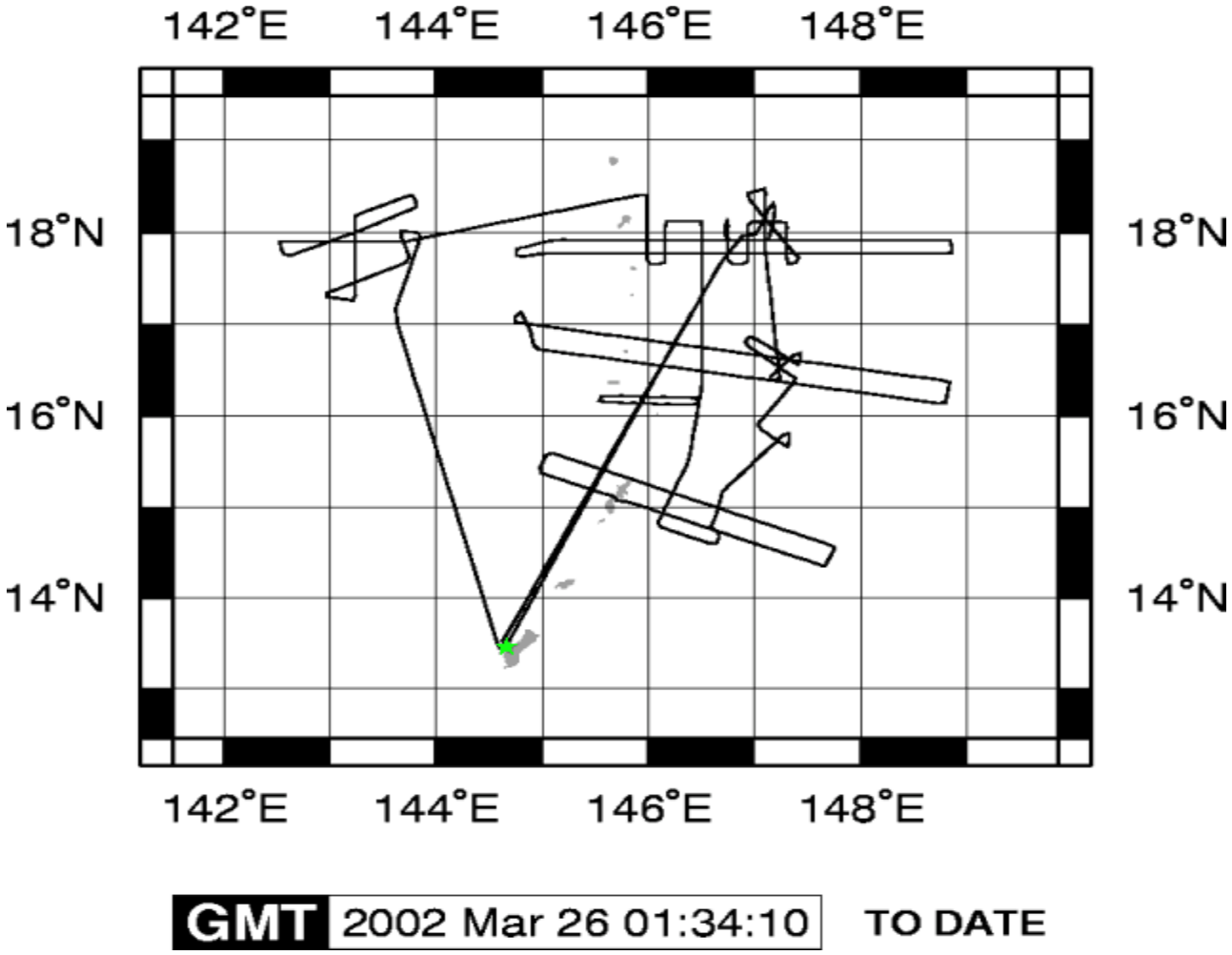
R/V Maurice Ewing Data Reduction Summary

EW–0202 Guam – Guam

Date	Julian Date	Time	Port
February 24, 2002	2002.055	00:10:00	Apra, Guam
March 26, 2002	2002.084	06:42:00	Apra, Guam



Project Summary

DESCRIPTION

Background and Scientific Objectives

Multi−scale Seismic Imaging of the Mariana Subduction Factory:

Leg 1 (EW0202 MCS) Overview:

The MARGINS programs in the US and Japan (of NSF and MEXT) have funded an integrated seismic study (marine multi−channel seismic reflection, controlled−source wide−angle reflection/refraction, and passive recording of local and teleseismic earthquakes) to provide a comprehensive velocity, attenuation, structural and stratigraphic image of the Mariana island−arc system, from the subducting Pacific Plate to the backarc, at 14°−20°N, 141°−149°E. Participating institutions include SOEST, Stanford, Washinton St. Louis, Scripps, JAMSTEC, ERI, ORI and Kobe.

This study of the active Mariana arc−trench−backarc system will be implemented on several cruises, starting with EW0202 (Leg 1: MCS) and EW0203 (Leg 2: active source OBS and MCS). Another active source OBS transect will be shot on R/V Kaiyo in January/February, 2003. Finally, an array of ~75 passive OBSs will be set out in April/May 2003, to be recovered one year later, with overlapping deployments of PASSCAL seismometers on the islands of the CNMI.

Our study will provide the baseline seismic information required for the MARGINS Subduction Factory experiment in the Mariana system. We therefore plan to collect the data necessary to create images detailed enough to guide future geochemical measurements and proposed IODP drilling to understand the material fluxes input at the trench and output at the forerc, volcanic arc, and backarc. The MCS component of this intergrated program is described below.

EW0202 MCS reflection profiling of the forearc/arc/backarc:

Stratigraphy and structure of the sediments and basement Our seismic reflection profiles of the Mariana system will provide the highest resolution images of its tectonic, volcanic and sedimentary history. They will provide the cross−sections that (1) reveal the variation of the system along− and across−strike, (ii) place outcrop and drill sites in context and (iii) allow the geologic evolution to be better interpreted. Understanding this evolution is essential if the MARGINS Subduction Factory initiative is to quantify the modern and average material fluxes through the Mariana system.

Cruise Members

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All data in this report is logged using GMT time and Julian days in order to avoid confusion with local time changes.

Spectra

Spectra logs data to files in UKOOA[1] P1/90 format and P2/94 Format. The file formats are included in separate PDF documents on the tape. The contents of these files contain all the parameters used during shooting each of the lines, as well as the positions of all the sensors. I have included perl scripts for extracting shot times and positions from the P1 and P2 files on the tape.

Spectra had some trouble filling the P1 files during this cruise. It finally stablized about halfway through the cruise. The true cause of the problem has not been determined.

Positioning of Sensors

The Spectra system defines a reference point which is used as a reference to all points which need an offset (range and bearing to TB, for example). This reference point has been defined as the center of the ship's mast, at sealevel.

Any documentation included herein that refers to the vessel reference or reference or master will be referring to this reference point.

However, daily navigation files that are not related to spectra (ie. n., hb.n, mg.n, files) are referenced to the Tasmon P−Code GPS filtered positions.

Offset information can be found under the **Ship Diagrams** section of this document.

Data Reduction

Since spectra positions its shots precisely based on a Kalman filtering algorithm, we will assume that it has the correct shot location. However, as a fallback measure, I have also processed the shots using our normal navigation filtering.

Therefore you will find the following shotlog files:

- nb0.r Contains shot times and positions based on Spectra positioning.
- nb2.r Contains shot times and positions based on Spectra navigation
- ts.n Contains shot times and positions based on Ewing navigation
- shots.p1 Contains shot times and positions based on Spectra P1 files
- shots.p2 Contains shot times and positions based on Spectra P2 files

Please see the File Formats section for more information on these files.

1 *United Kingdom Offshore Operators Association*

Hydrosweep

Hydrosweep exhibited a nasty nadir−beam canyon behavior for the first two weeks of the cruise. The firmware was updated with a fix from Atlas and the data has been much cleaner ever since. There may still be some artifacts, but they are subtle enough that they have not yet been fully characterized.

Gravity

no notes.

Seismic Acquisition

Several streamer sections and cans were replaced at deployment.

The tailbuoy has been flakey, but hasn't been pulled. The communication to the tailbuoy has been solid, but the GPS unit is extermely finicky about locking on a position. Replacement units are being investigated.

Magnetics

The magnetometer became very noisy and was pulled, fixed, and redeplyed (with the fins back on and the water dumped out) on day 68. The data has been pristine ever since.

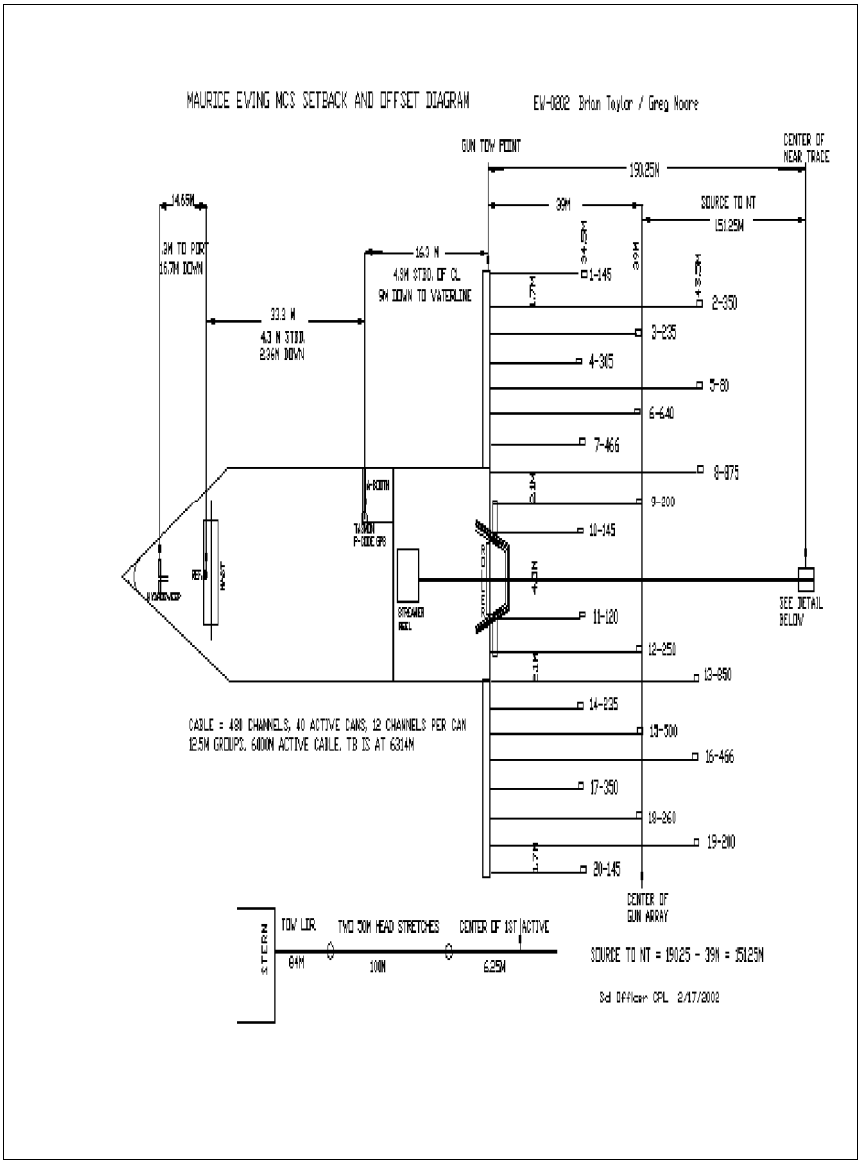
Furuno

A faulty repeater in the Furuno line was removed on the afternoon of day 059 resulting in a spurious heading for about 60 minutes.

Weather

The temperature sensor on the weather pack is still waiting for a replacement.

Ship Offset Diagram



Data Logging

The R/V Maurice Ewing data logging system is run on a Sparc Ultra Enterprise Server. Attached are 48 serial ports via 3 16−port Digi International SCSI Terminal Servers. Generally, all data logged by the Ewing Data Acquisition System (DAS) is time stamped with the CPU time of the server, and broadcast to the Ewing network using UDP packet broadcasts. The CPU time of the server is synchronized once every half hour to a Datum UTC gps time clock.

GPS times are also time−tagged with cpu time, although the time of the GPS position is from the GPS fix itself.

The following tables describe the data instruments which performed logging during this cruise. The tables associated with the instruments describe logging periods and data losses for that instrument.

Time Reference

Datum StarTime 9390−1000

logging interval: 30 minutes
file id: tr2

Used as the CPU synchronization clock. This clock is polled once every half hour to synchronize the CPU clock of the data logger to UTC time. The logger (octopus) is responsible for updating the times of the other CPUs.

This clock was running and synchronizing the system the entire cruise.

Interruption s greater than 30 minutes are displayed in the following table

Log Date	LogDate	Comment
2002+055:00:04:29.736		Logging officially started
2002+084:22:34:29.842		Logging officially ends

Spectra

Spectra uses its own Trimble gps receiver for synchronizing its hardware to UTC time. This is the time the shot points are referenced to; not the CPU time.

GPS Receivers

GPS data is usually logged at 10 second intervals. The NMEA strings GPGGA and GPVTG are logged for position, speed, and heading fixes. This data was logged constantly throughout the cruise.

The Tasmon GPS was the primary GPS for this cruise.

Trimble Tasmon P/Y Code Receiver

logging interval: 10 seconds
file id: gp1

The Tasmon is the primary GPS receiver for the Ewing Logging system and the primary GPS for Spectra fixes. The accuracy is around 15 meters. There were no interruptions during this cruise.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2002+055:00:01:12.268		Logging officially started
2002+055:23:59:59.558	2002+056:03:10:53.183	
2002+056:03:10:53.344	2002+056:03:51:02.297	
2002+084:22:33:31.117		Logging officially ends

Trimble NT200D

logging interval: 10 seconds
file id: gp2

The Trimble is the secondary receiver for GPS data. Data is logged at 10 second intervals and is also used as an input to Spectra, although it is weighed at a lower value than the Tasmon receiver.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2002+055:00:10:21.646		Logging officially started
2002+055:23:59:59.87	2002+056:03:10:57.653	
2002+056:03:10:57.854	2002+056:03:51:27.974	
2002+059:06:34:47.549	2002+059:08:37:09.619	
2002+061:07:09:53.838	2002+061:07:49:29.751	
2002+061:07:53:07.994	2002+061:09:35:03.583	
2002+084:22:33:30.129		Logging Ends

Tailbuoy Garmin GP8

logging interval: 10 seconds
file id: tb1

Interruptions greater than 30 minutes are displayed in the following table

Log Date	Log Date	Comment
2002+056:17:28:38.666		Tailbuoy logging starts
2002+056:19:17:15.263	2002+056:19:45:54.648	
2002+063:09:48:48.703	2002+063:10:06:30.008	
2002+064:15:28:22.891	2002+064:15:40:58.023	
2002+069:08:23:08.494	2002+069:08:36:02.122	
2002+069:15:47:18.768	2002+069:16:01:09.914	
2002+082:16:46:02.724	2002+082:17:07:41.471	
2002+082:20:33:12.973	2002+082:20:48:12.124	
2002+083:11:54:31.422	2002+083:12:09:31.162	
2002+084:03:03:51.859	2002+084:03:30:14.829	
2002+084:05:02:23.519		Tailbuoy logging officially ends

Speed and Heading

Furuno CI−30 Dual Axis Speed Log
Sperry MK−27 Gyro

logging interval: 6 seconds
file id: fu

The Furuno and Gyro are combined to output speed, heading and course information to a raw Furuno file, as well as an NMEA VDVHW signal used as an input to various systems including steering and Spectra.

Interruptions greater than 30 minutes are displayed in the following table

Log Date	Log Date	Comment
2002+055:00:01:27.611		Official start date
2002+084:22:33:29.397		Official end date

Gravity

Bell Aerospace BGM−3 Marine Gravity Meter System

logging interval: 1 second
file id: vc. (raw), vt. (processed)
drift per day: 0.035

The BGM consists of a forced feedback accelerometer mounted on a gyro stabilized platform. The gravity meter outputs raw counts approximately once per second which are logged and processed to provide real−time gravity displays during the course of the cruise as well as adjusted gravity data at the end of the cruise.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	Log Date	Comment
2002+055:00:01:33.712		Official start date
2002+084:22:33:30.997		Official end time

Bathymetry

Krupp Atlas Hydrosweep−DS2

logging interval: variable based on water depth
file id: hb (centerbeam), hs (swath)

The hydrosweep full swath data is continuously logged for every cruise, and centerbeam data is extracted and processed separately. The centerbeam operates at a logging frequency dependent on the water depth.

The full swath data is not routinely processed, but can be processed with the MB−System software which can be downloaded for free. For instructions, use the website: http://www.ldeo.columbia.edu/MB−System.

MBSystem, version 5.0beta3 is necessary to process data after June 1, 2001.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2002+055:00:03:48.000		Official start logging
2002+084:22:33:26.000		Official end logging

Weather Station

RM Young Precision Meteorological Instruments, 26700 series

logging interval: 1 minute
file id: wx

The weather station is used to log wind speed, direction, air temperature, and barometric pressure. We log this information at 1−minute intervals.

Log Date	LogDate	Comment
2002+055:00:04:30.559		Official start logging
2002+084:22:33:00.216		Official end logging

Magnetics

Varian Magnetometer

logging interval: 12 seconds
file id: mg

The following table shows the times the magnetometer was logging

Start Log Date	End LogDate	Comment
2002+055:01:13:45.894	2002+055:21:21:59.180	
2002+056:23:42:13.059	2002+068:23:39:19.739	
2002+069:00:59:10.522	2002+078:06:34:12.151	
2002+078:07:02:39.534	2002+083:11:32:18.722	

The following items were of concern during this cruise:

- The P2 and P1 formats do not store the shot time in millisecond range
- SIOSEIS cannot handle the Spectra output header for SEG−D

There are several files for each line reflecting the line status:

File	Description
ts.n	Shot time is merged with Ewing navigation to determine shot location
nb2.r	Navigation is from Spectra, and includes tailbuoy, tailbuoy range and bearing
shotlog.p1	Shots are from the p1 file. (should be identical to nb2.r), includes source position
shotlog.p2	Shots are from the p2 file (should be identical to tss.n), includes source position

Shot Files Table

Line Name	Times ()	Ewing(ts.n, nb2.r)		Spectra (shots.p1, shotlog.p2)		
		Shots	Missing	P1 Shots	P2 Shots	Missing

LOCATION 1

EW0114 Hobart, Tasmania

Pier/Ship	Latitude	Longitude
	47 53.140S	147 20.042E

The pier tie was taken at an unumbered bollard five (5) set on drain opening marking on warehouse. (Shed #2)

Reference	Latitude	Longitude
	32 03.156S	115 48.800E

The reference tie was made inside the main terminal at the extreme right of

	Id	Julian	Date	Mistie	Drift/Day	Prev Mistie
Pre Cruise	EW0113	338	12/03/2001	9.22	0.01	8.94
Post Cruise	EW0114	25	01/25/2002	9.44	0.004	9.22
Total Days			53.00	0.22		

Time	Entry	Value	
15:00	CDeck Level BELOW Pier	1.00	
15:00	Pier 1 L&R Value	4004.32	L&R
15:39	Reference L&R Value	4001.16	L&R
16:30	Pier 2 L&R Value	4004.32	L&R
	Reference Gravity	980449.40	mGals
	Gravity Meter Value (BGM Readir	980464.20	mGals
	Potsdam Corrected	0	1 if corrected

*Gravity meter is **5.5** meters below CDeck*

Difference in meters between Gravity Meter and Pi: 6.50 meters

Height Cor = Pier Height* FAA Constant

6.50	0.31			2.02 mGals/min

Difference in mGals between Pier and Gravity Meter

Pier (avg) −	Reference	1.06 L&R/mGal		Delta L&R
4004.32	4001.16	1.06		3.35 mGals

Gravity in mGals at Pierside

Reference +	Delta mGals	[+ Potsdam]		Pier Gravity
980449.40	3.35	0.00		980452.75 mgals

Gravity in mGals at Meter

Pier Gravity +	Height Correction			Gravity@meter
980452.75	2.02			980454.76 mGals

Current Mistie

BGM Readin	Calculated Gravity			Current Mistie
980464.20	980454.76			9.44 mGals

Location 2

EW0202 Apra, Guam

Pier/Ship	Latitude	Longitude
	14 27.809N	144 39.074E

The corner of the end of the pier on Hotel Wharf (H), Apra Harbor

Reference	Latitude	Longitude
	13 27.57N	144 39.72E

Commercial Port, Wharf F–1, on the fuel pier as marked on the reference map as DOD#0061–T

	Id	Julian	Date	Mistie	Drift/Day	Prev Mistie
Pre Cruise	EW0114	25	01/25/2002	9.44	0.00	9.22
Post Cruise	EW0202	86	03/27/2002	23.80	0.235	9.44
Total Days			61.00	14.36		

Time	Entry	Value	
02:14	CDeck Level BELOW Pier	1.00	
02:14	Pier 1 L&R Value	2186.00	L&R
02:48	Reference L&R Value	2190.00	L&R
03:43	Pier 2 L&R Value	2185.85	L&R
	Reference Gravity	978514.90	mGals
	Gravity Meter Value (BGM Reading)	978536.40	mGals
	Potsdam Corrected	0	1 if corrected

*Gravity meter is **5.5** meters below CDeck*

Difference in meters between Gravity Meter and Pier: 6.50 meters

Height Cor = Pier Height*	FAA Constant				
6.50	0.31			2.02	mGals/min

Difference in mGals between Pier and Gravity Meter

Pier (avg) –	Reference	*1.06 L&R/mGal		Delta L&R	
2185.93	2190.00	1.06		–4.32	mGals

Gravity in mGals at Pierside

Reference +	Delta mGals	[+ Potsdam]		Pier Gravity	
978514.90	–4.32	0.00		978510.58	mgals

Gravity in mGals at Meter

Pier Gravity+	Height Correction			Gravity@meter	
978510.58	2.02			978512.60	mGals

Current Mistie

BGM Reading	Calculated Gravity			Current Mistie	
978536.40	978512.60			23.80	mGals

For all formats, a – in the time field means an invalid value for some reason.

Streamer Compass/Bird Data cb.r

This data is not processed, but can still be found in the "processed" data directory.

```
Shot Time               Line     Shot     Latitude      Longitude

2000+079:00:08:40.085  strike1 000296  N 15 49.6217 W 060 19.8019

2nd GPS Position                      Tailbuoy Position
Latitude     Longitude                Latitude     Longitude

N 15 49.6189 W 060 19.8101    N 15 47.1234 W 060 20.1901

Furuno  Streamer
Gyro    Compasses & Heading

344.1       C01 2.3 C02 1.7  ...
```

Gun Depths dg

Gun depths in tenths of meters. There will always be 20 gundepths even if only one gun was configured and shooting.

```
                        Gun Depths
Shot Time               1   2   3  4    5   6   7   8   9  ...  20

2001+089:06:47:05.909 189 068 005 005 096 005 060 054 005 ... 6
```

Raw Furuno Log fu.s

This data has been smoothed and output 1 fix per minute.

```
CPU Time Stamp         Track Speed Hdg   Gyro

2000+166:00:01:53.091 –     4.4   140.5 148.3
```

Hydrosweep Centerbeam hb.n

Hydrosweep data merged with navigation

```
                              Centerbeam
CPU Time Stamp       Latitude Longitude          Depth

2000+074:09:55:00.000  N 13 6.6206    W 59 39.3908   134.9
```

Merged Data m

```
                                                        GPS
CPU Time Stamp         Latitude     Longitude          Used  Set  Drift Depth

2000+200:12:25:00.000  N 45 54.1583 W 42 47.1770       gp1   0.0  0.0

Magnetic                        Gravity
Total Intensity   Anomaly     FAA  GRV       EOTVOS   Drift   Shift

49464.7           55.5        22.2 980735.0   –8.4     –0.1     2.8

Temperature Salinity Conductivity

0.0         0.0      0.0
```

The gravity drift and shift are values that have been added to the raw gravity to make up for drift in the meter that has been lost in accordance with a gravity check at each port stop.

Temperature,Salinity and Conductivity will only be valid while logging a Thermosalinograph, which is not usually the case.

Magnetics Data — mg.n

- A minus sign in the time stamp is flagged as a spike point, probably noise...
- Anomaly is based on the International Geomagnetic Reference Field revision 2000

```
CPU Time Stamp        Latitude     Longitude      Raw Value Anomaly
200+077:00:23:00.000 N 16 11.2918 W  59 47.8258 36752.2   -166.8
```

Navigation File — n

```
CPU Time Stamp         Latitude     Longitude       Used  Set  Drift
2000+074:00:03:00.000 N 13 6.2214  W  59 37.9399   gp1   0.0   0.0
```

Navigation Block — nb0

Navigation is a compendium of Ewing logged data at shot time. The shot position here is the shot position from the Spectra system.

```
Shot Time               Shot # CPU Time               Shot Position
2001+088:00:00:00.606 016967 2001+088:00:00:03.031 N 30 11.8324 W 042 10.8162

Water  Sea    Wind   -------------Tailbuoy------------------ Line
Depth  Temp Spd  Dir Latitude     Longitude     Range Bearg Name   Speed Heading
2565.1 20.7 16.4 164 N 30 12.0427 W 042 14.7319 6296.3 93.5 MEG-10 4.2   101.1
```

Tailbuoy Navigation — tb1.c

Raw tailbuoy fixes

```
CPU Time Stamp         Latitude     Longitude       GPS Precision
2001+088:00:00:02.000 N 30 12.0424 W 042 14.7309   SA
```

GPS Precision is either SA, DIFF or PCODE

Ewing Processed Shot Times — ts.n

Shot times and positions based on the Ewing navigation data processing

```
CPU Time Stamp         Shot # Latitude     Longitude     Line Name
2000+079:00:08:01.507 000295 N 15 49.5703 W 060 19.7843 strike1
```

Shot Data Status — ts.n.status

The ts.nxxx.status file describes the line information for that day, giving some basic statistics about the line: start, end times; missing shots; start and end shots.

```
LINE   strike1: 98+079:00:00:15.568 : 000283 .. 002286
        MISSING: 347, 410, 1727
LINE   dip2: 98+079:23:05:22.899 : 000002 .. 000151
```

This example says that on Julian Day 079 of 1998, two lines (strike1 and dip2) were run: the end of strike 1 (shots 000283 to 002286) and the start of dip2 (shots 000002 to 000151).

Line strike1 had some missing shots in the data file (probably missing on the SEG-d header as well).

Spectra Shot Times — nb2.r

The shot times and positions based on the Spectra positioning; with raw tailbuoy range and bearing.

```
CPU Time Stamp          Shot # Latitude      Longitude      Line Name
2001+084:00:00:05.924 009245 N 23 31.2410 W 045 25.0894

                                 Tailbuoy
Latitude      Longitude      Range  Bearing  Line Name
N 23 30.4540 W 045 21.4338 6389.8 283.2    KANE-4
```

Raw Gravity Counts — vc.r

sample BGM-3 gravity count record (without time tag):

```
pp:dddddd ss
|    |    |___________ status: 00 = No DNV error; 01 = Platform DNV
|    |                         02 = Sensor DNV;   03 = Both DNV's
|    |________________ count typically 025000 or 250000
|_____________________ counting interval, 01 or 10
                       The input of data can be at 1 or 10 seconds.
```

Gravity Data — vt.n

* A minus sign in the time stamp is flagged as a spike point
* m_grv3 calculates the Eotvos correction as:
  eotvos_corr = 7.5038 * vel_east * cos(lat) + .004154 * vel*vel
* The theoretical gravity value is based upon different models for the earth's shape.
  - 1930 = 1930 International Gravity Formula
  - 1967 = 1967 Geodetic Reference System Formula
  - 1980 = 1980 Gravity Formula
* The FAA is computed as:
  faa = corrected_grv – theoretical_grv
* Velocity smoothing is performed w/ a 5 point window

```
CPU Time Stamp          Latitude      Longitude      Model FAA      RAW
2000+148:00:10:00.000 N 09 34.7255 W 085 38.5826 1980  9.48    978264.16

Eotvos  Drift DC      Raw  Velocity     Smooth Velocity
Smooth  Total Shift   North     East     North    East
-74.78  0.06  4.16    1.875 -10.373     1.927 \10.166
```

Datum Time — ts2.r

```
CPU Time                Datum Time        Time Reference
2001+069:00:15:29.727 069 00 15 29.378 datum
```

Raw GPS — gp(12).d, tb1.d

Raw GPS is in NMEA Format.

Meteorological Data wx

```
                          True
CPU Time Stamp          Spd Dir

2001+045:00:00:00.967   7.8  22

Bird1:                                                Bird 2
Speed                     Direction                   Speed                     Direction
Inst  60sA   60mA  60sM  Inst 60sA 60mA              Inst  60sA  60mA  60sM    Inst 60sA 60mA

7.8   6.6    8.5   16.8  277  291  5                 0.0   0.0   0.0   0.0     0    0    0

Temperature                    Humidity
Inst  60mA  60mm  60mM         Inst 60mm 60mM          Barometer

15.0  14.2  14.3  15.1         92   90   93            1027.5

Inst:       Current
60sA:       60 second average
60mA:       60 minute average
60sM:       60 second maximum
60mm:       60 minute minimum
60mM:       60 minute maximum
```

Merged Meteorological Data mmet

```
TSG, WX, CT merged with Nav at 1 minute fixes
date        time        lat       lon       gpu head spd
2001+244:00:00:00.000 12.14071 44.98469 gp1 10.2 83.0

tws  twd   temp hum  press  cti  cte  con sal  ct
26.5 228.0 30.6 87.0 1000.8 28.8 28.8 5.9 36.3 28.8

gpu  = gps unit in use
head = ship's heading
spd  = ship's speed in knots
tws  = true wind speed
twd  = true wind direction
temp = air temp (celcius)
hum  = relative humidity (%)
press= pressure in mb
cti  = sea temp from the internal TSG sensor
cte  = sea temp from the external TSG sensor
con  = conductivity, Siemens/meter
sal  = salinity, practical salinity units
ct   = sea temp from the C-keel sensor (to tenths of a degree)
```

Shot Times from Spectra P1 Files shots.p1

```
These files were created with the script: extract_shots_from_p1 -a 1
Epoch Time    Shot#  Source Lat/Lon         TB Lat      TB Lon
985788741.000 015570 30.283881 -41.854536  30.320144  -41.886642
Vessel Ref Lat/Lon   Antenna GPS Lat/Lon     Water Depth
```

30.283478 −41.854117 30.283531 −41.854078 2894.2

- Source is the Center of the Guns
- TB is the Tailbuoy, according to Spectra
- Vessel Ref is the location of the center of the Mast
- Antenna GPS is the location of Antenna 1 (−a 1 flag); in this case is the Tasmon GPS
- Water Depth is the HS Centerbeam depth

Shot Times from Spectra P2 Files shots.p2

These files were created with the script: *extract_shots_from_p2 −o "V1 G1"*

Epoch Time Shot# Vessel Ref Lat/Lon Source Lat/Lon

985716772.4 00015572 30.282803 −41.866136 30.283207 \41.866540

- Vessel Ref is the location of the center of the Mast
- Source is the Center of the Guns

Scripts

Included are some scripts for extracting information out of the P1 and P2 formatted files. In order to use these scripts you will also need to install the Ewing Perl libraries included in the scripts directory, or at least include that directory in your PERL5LIB environment. The use of perl is beyond the scope of this document.

extract_shots_from_p1 [−a antenna] [−h] filename

Given an input P1 File, create a shotpoint file with the times, and the positions of the given antenna [1 = tasmon, 2 = Trimble] and optionally the header records at the beginning of the file.

The output will be:

```
epochtime shotnumber sourcePos tbPos vesselPos antennaPos depth
```

- **epochtime** is the # of seconds since Jan 1, 1970
- **shotnumber** is the shot number
- **sourcePos** is the center position of the sound source [lat lon]
- **tbPos** is the position of the tailbuoy [lat lon]
- **vesselPos** is the position of the vessel reference (center of mast) [lat lon]
- **antennaPos** is the position of the specified antenna [lat lon]
  1 = tasmon, 2 = trimble
- **depth** is the water depth in meters

extract_shots_from_p2 [−s shotnumber] [−o "output values"]

−s define if you only want the statistics for a single shot

−o "*outputs*" defines the outputs you want from the P2 file.

This routine will output by default the shotpoint, the line name and the shot time. Optionally, you can output position (Lat Lon) info for a number of items:

Outputs can be one or more of the following:

- V1 Vessel 1 Reference
- V1G1 Tasmon GPS Receiver
- V1G2 Trimble GPS Receiver
- V1E1 Hydrosweep Transducer
- TB1 Tailbuoy 1
- S1 Streamer 1
- V1SC Streamer Compasses
- G1 Gun Array 1

All the formats output a Lat Lon pair in decimal degrees. (*West and South being negative*)

Output will be: `epochtime shotnumber [output lat/lon pairs]`

Tape Contents

EW202/

CruiseReport_EW0202.pdf	this document
ew0202.cdf	NetCDF database file of this cruise
ew0202.cdf_nav	NetCDF database file of this cruise' navigation
docs/	File Formats, Spectra manuals
processed/	Processed datafiles merged with navigation
shotlogs/	processed Shot Files
trackplots/	daily cruise track plots (*postscript*)
raw/	Raw data directly from logger
reduction/	Reduced data files
clean/	daily processing directory, includes daily postscript plots of the data.
fixes/	fixes for the RTNu HS loss of d088
scripts/	Perl scripts and their friends
spectra/	P1/90 and P2/94 files from MCS lines
XBT/	XBT data
streamer/	Excel spreadsheets of streamer configuration